

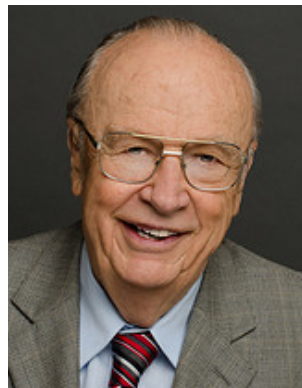
Isogeometric Analysis: Past, Present, Future

T.J.R. Hughes

Institute for Computational Engineering and Sciences (ICES)
The University of Texas at Austin

Collaborators:

C. Adam, F. Auricchio, I. Babuška, Y. Bazilevs, L. Beirão da Veiga, D. Benson, M. Borden, R. de Borst, V. Calo, E. Cohen, J.A. Cottrell, L. De Lorenzis, T. Elguedj, J. Evans, H. Gomez, R. Hiemstra, S. Hossain, M.-C. Hsu, D. Kamensky, C. Landis, J. Liu, S. Morganti, E. Rank, A. Reali, R. Riesenfeld, M. Sacks, G. Sangalli, D. Schillinger, M. Scott, T. Sederberg, H. Speleers, N. Sukumar, D. Toshniwal, I. Temizer, B. Urick, C. Verhoosel, Z. Wilson, P. Wriggers, J. Zhang



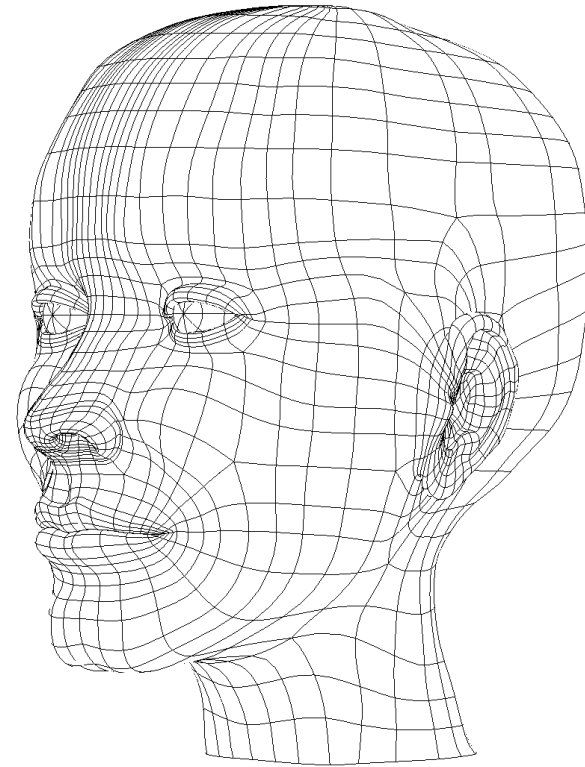
Babuška Forum

September 23rd, 2016



Outline

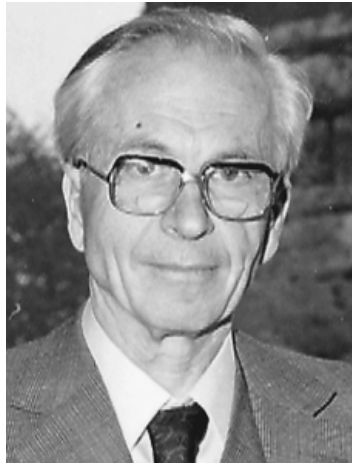
- FEA, since 1956
- IGA, since 2005
- B-splines, NURBS
- Collocation
- Quadrature
- Applications
 - Aortic valves
 - Boiling
 - Ductile fracture
- Summary and comments on new ideas



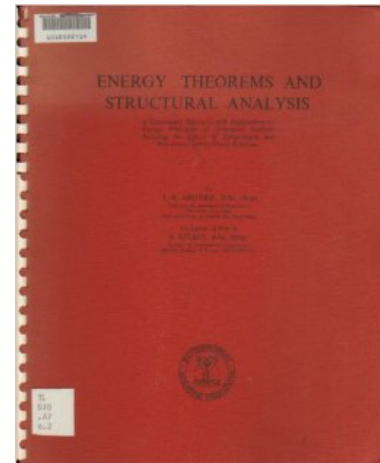
The Finite Element Method Historical Publication Data

The First 30 Years, 1956-1985

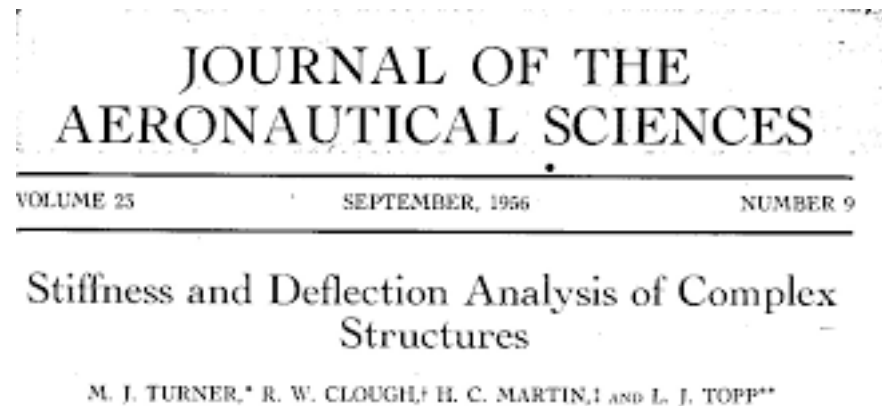
Why 1956?



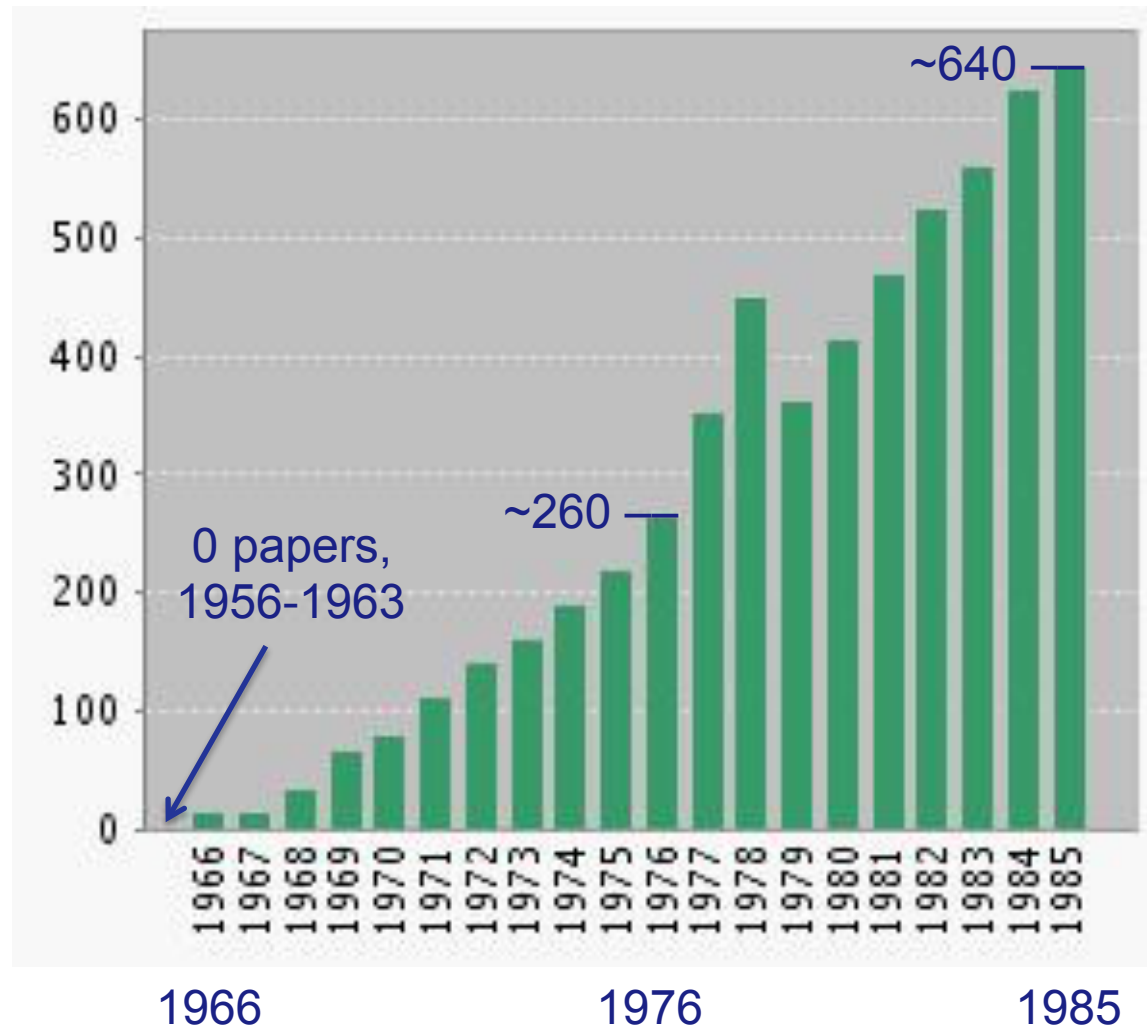
John Argyris, 1913 – 2004



Ray Clough, 1920 –



Number of FE Papers, 1956-1985

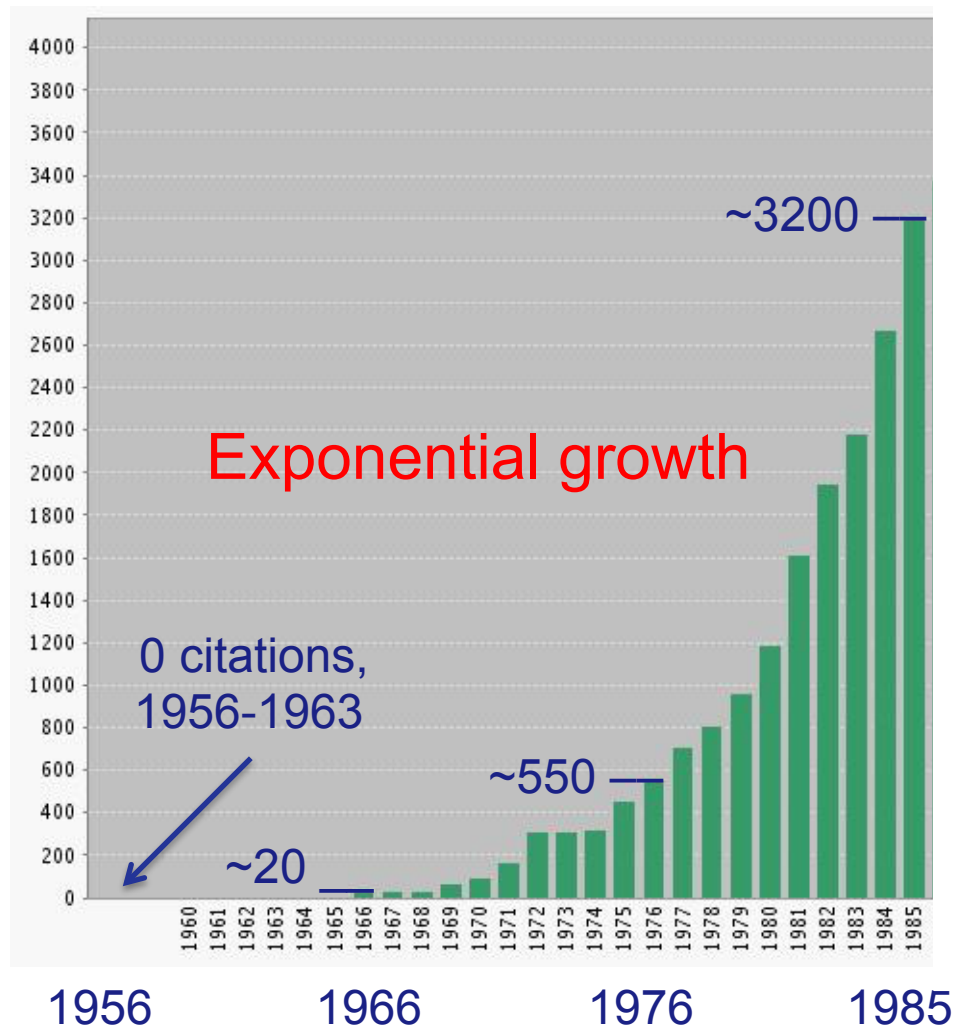


ISI Thomson-Reuters search

All data bases

Topic: Finite Element

Number of FE Citations, 1956-1985



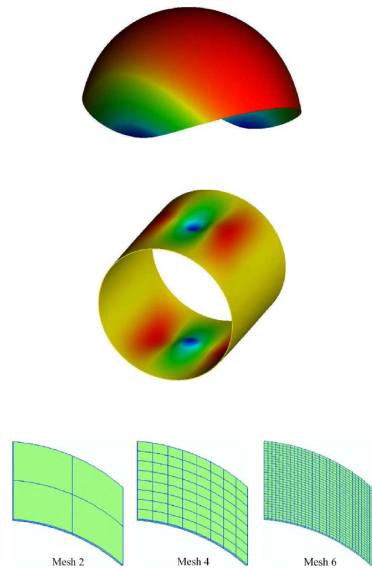
ISI Thomson-Reuters search

All data bases

Topic: Finite Element

Isogeometric Analysis Historical Publication Data

The First 10 Years, 2006-2015



“Isogeometric analysis: CAD, finite elements, NURBS, exact geometry and mesh refinement”

T.J.R. Hughes, J.A. Cottrell, Y. Bazilevs

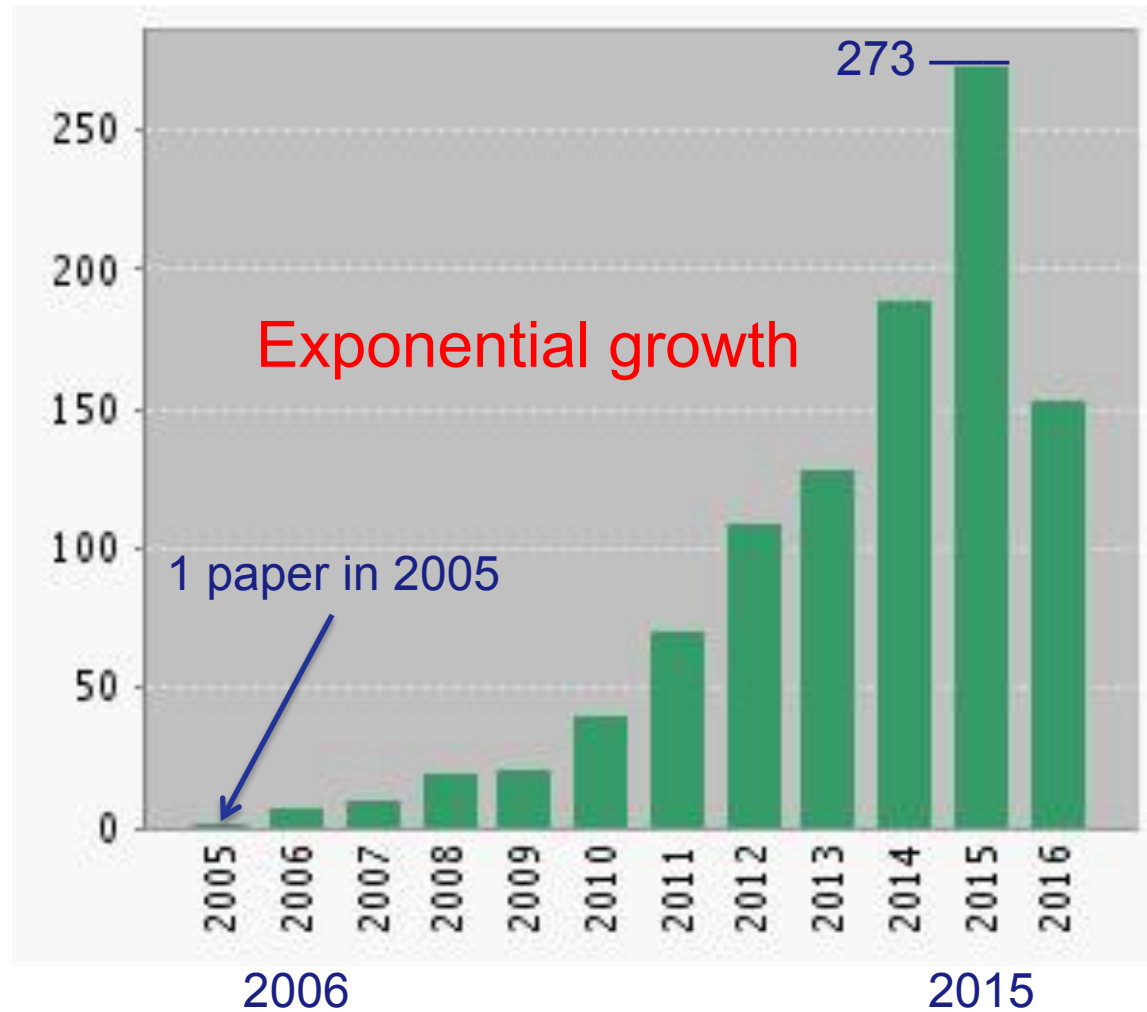
Computer Methods in Applied Mechanics and Engineering

Volume 194, Pages 4135-4195 (Oct. 1, 2005)

Impact:

- *Still* the most downloaded *CMAME* paper
- Google Scholar: 2333 total, 451 last year (September 23, 2016)
- Thomson Reuters: 1128 total, 278 last year (September 23, 2016)

Number of IGA Papers, 2006-2015



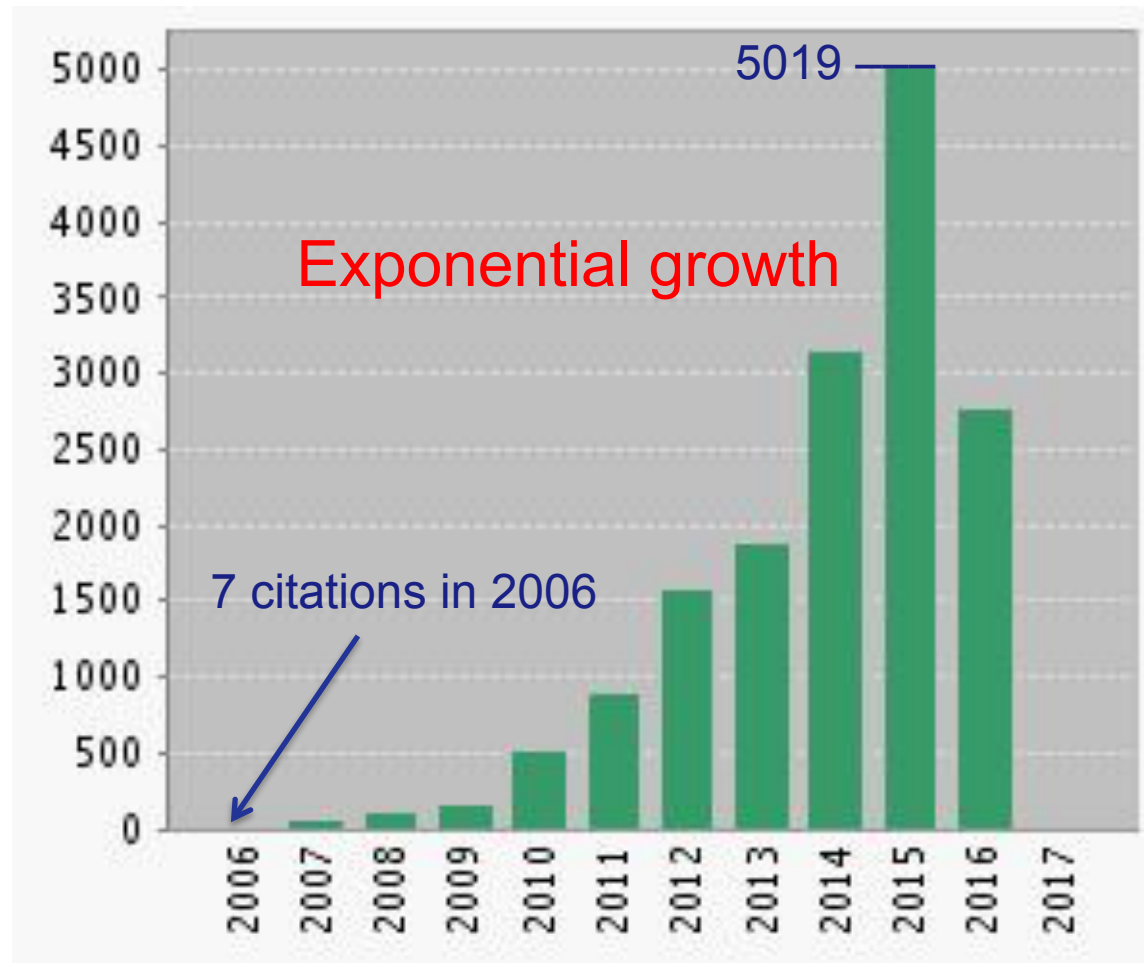
ISI Thomson-Reuters search

All data bases

Topic: Isogeometric Analysis

Date: September 23, 2016

Number of IGA Citations, 2006-2015



2006

2015

ISI Thomson-Reuters search

All data bases

Topic: Isogeometric Analysis

Date: September 23, 2016

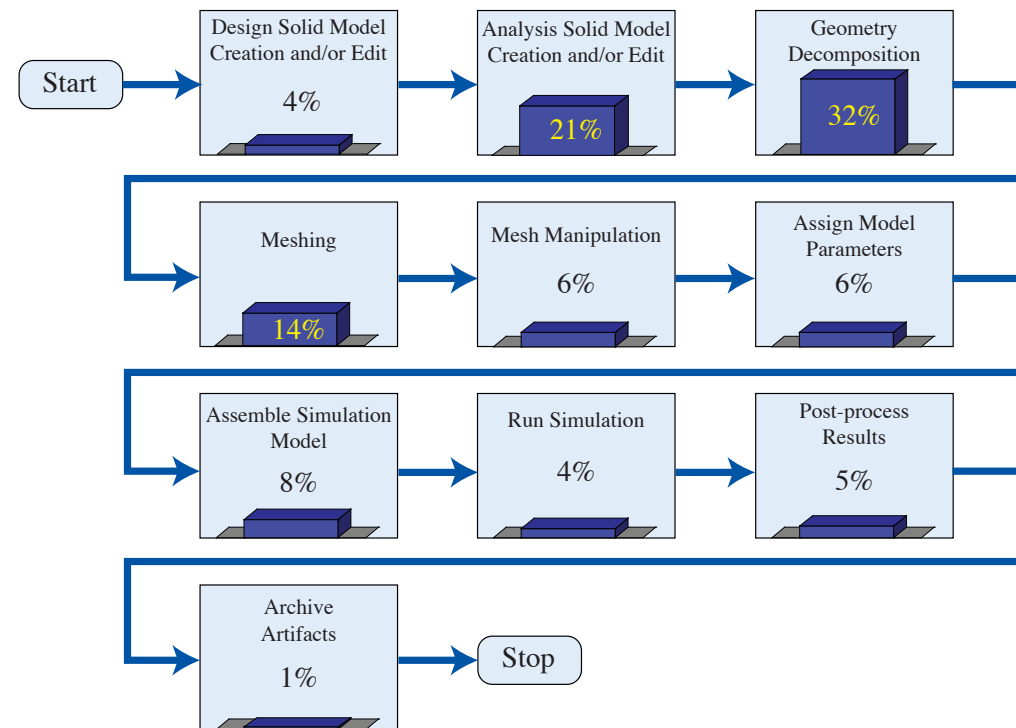
Comparisons are odious*

- Papers per year:
 - IGA 10th year (273) \approx FEA 20th year (260)
- Citations per year:
 - IGA 10th year (5019) $>$ FEA 30th year (3200)

*John Lydgate in his *Debate between the horse, goose, and sheep*, circa 1440

Engineering *Analysis* Process

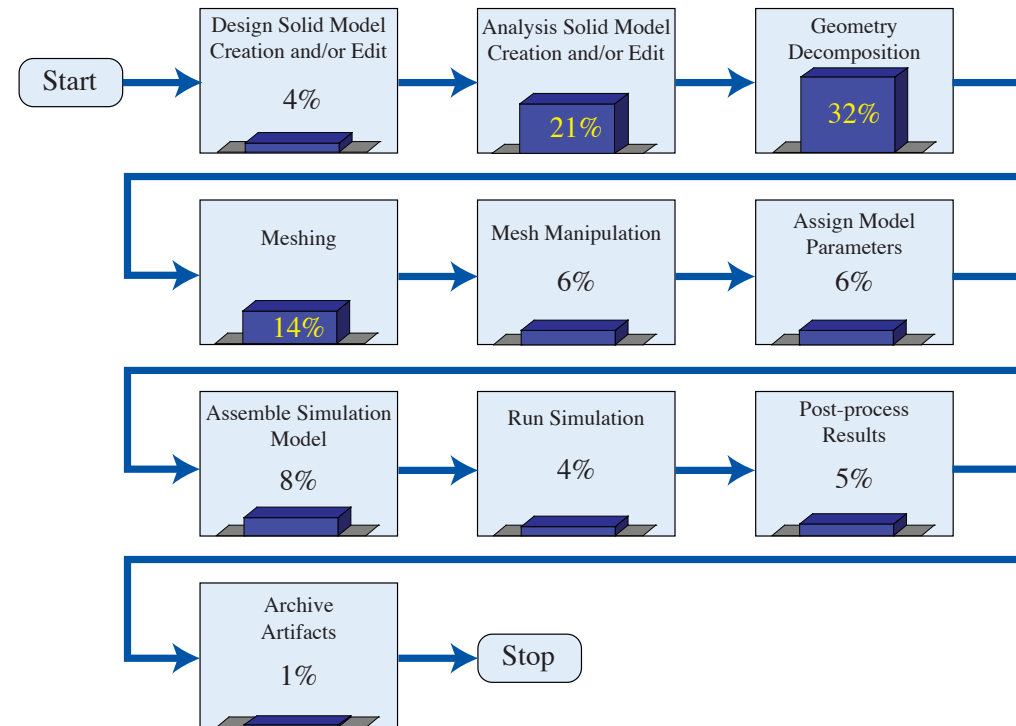
- Finite Element Analysis (FEA) models are created from CAD representations



(Michael Hardwick and Robert Clay,
Sandia National Laboratories)

Engineering *Analysis* Process

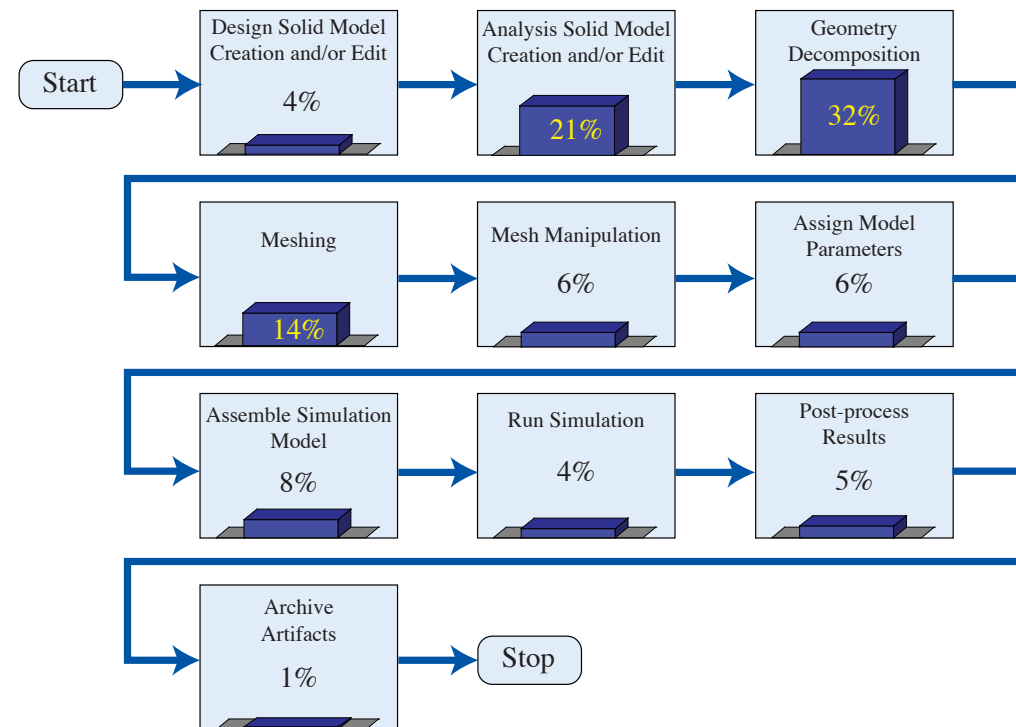
- Finite Element Analysis (FEA) models are created from CAD representations
- Fixing CAD geometry and creating FEA models accounts for more than 80% of overall analysis time and is a major engineering *bottleneck*



(Michael Hardwick and Robert Clay,
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Engineering *Analysis* Process

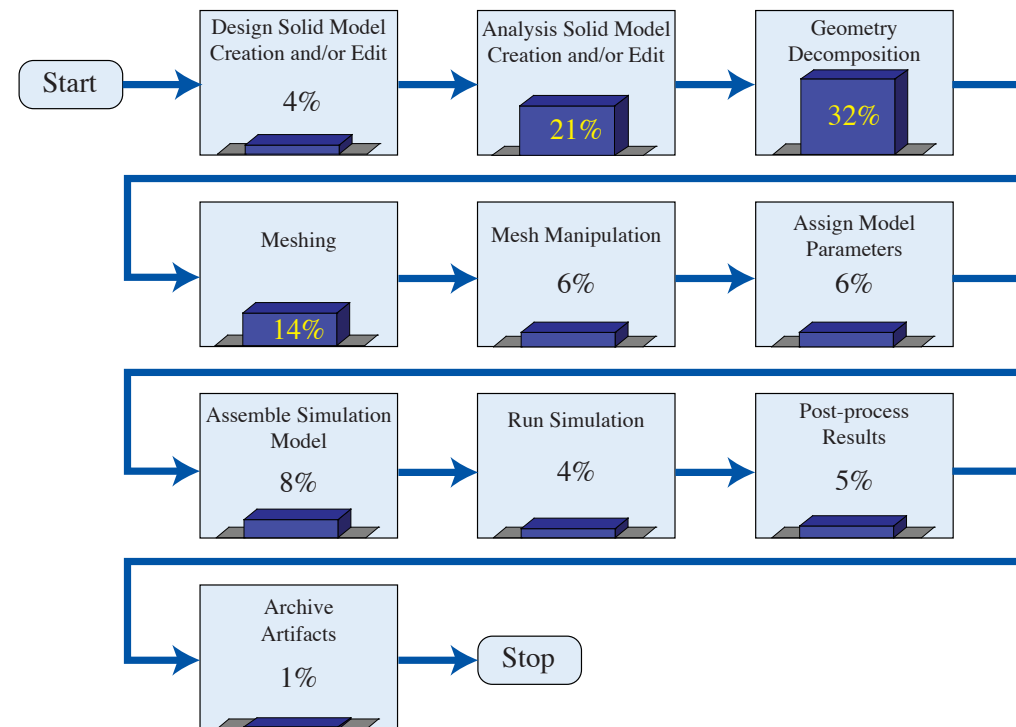
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- The FEA mesh is also only an *approximate* geometry



(Michael Hardwick and Robert Clay,
Sandia National Laboratories)

Engineering *Analysis* Process

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(Michael Hardwick and Robert Clay,
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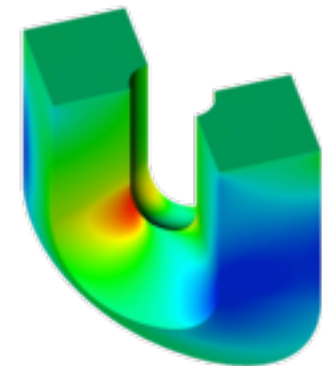
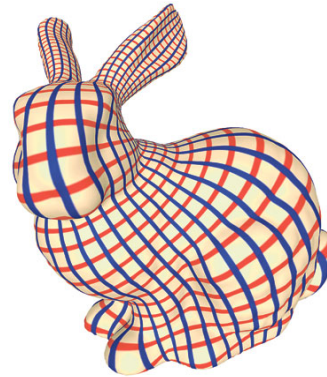
Objectives

- Reconstitute analysis within *CAD geometry*
- *Simplify* analysis model development thereby
- *Integrate* design and analysis

Isogeometric Analysis

Isogeometric Analysis

- Based on technologies (e.g., NURBS, T-splines, etc.) from *computational geometry* used in:
 - Design
 - Animation
 - Graphic art
 - Visualization
- Includes standard FEA as a special case, but offers other possibilities:
 - Precise and efficient geometric modeling
 - Simplified mesh refinement
 - Smooth basis functions with compact support
 - Superior approximation properties
 - *Integration* of design and analysis



Isogeometric Analysis (NURBS, T-Splines, SubD, etc.)

FEA

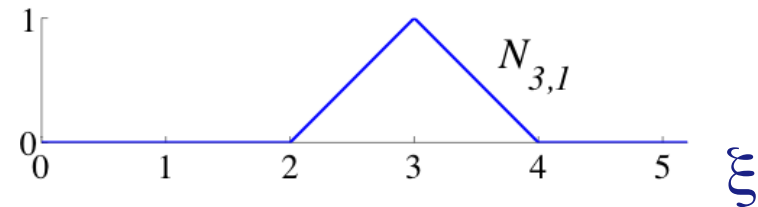
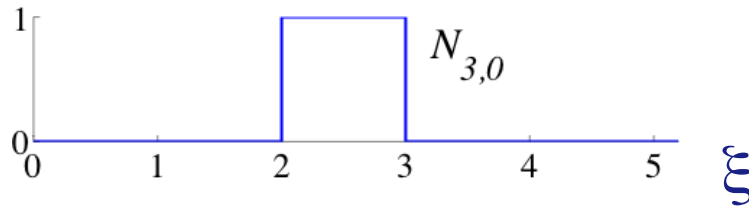
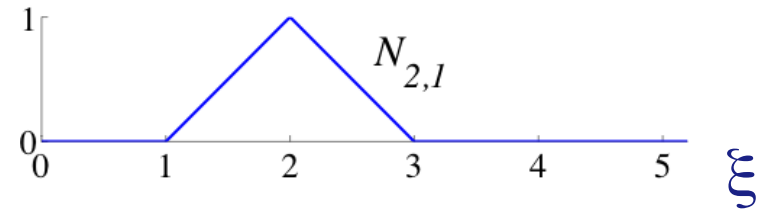
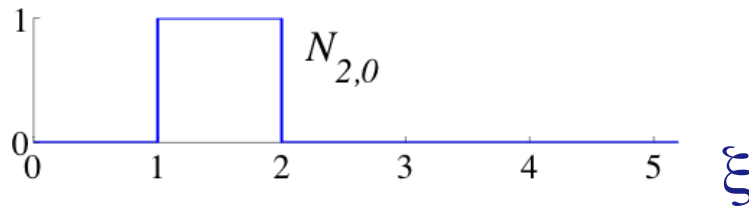
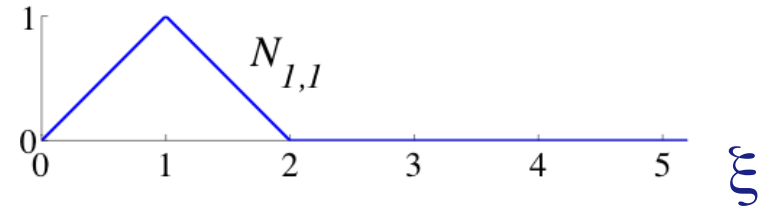
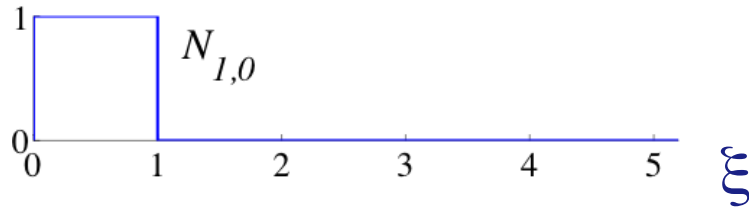
h-, *p*-refinement

k-refinement

B-spline Basis Functions

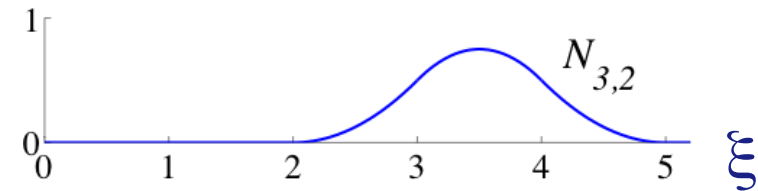
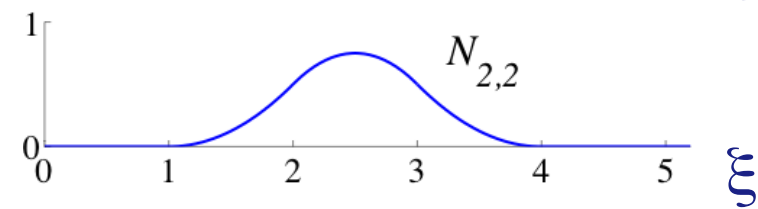
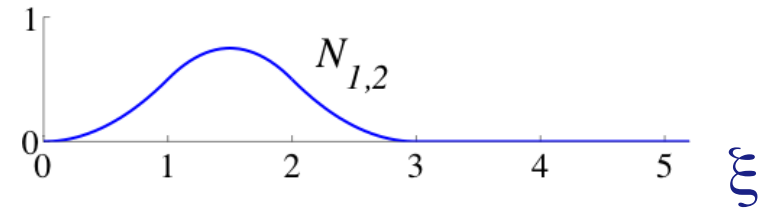
$$N_{i,0}(\xi) = \begin{cases} 1 & \text{if } \xi_i \leq \xi < \xi_{i+1}, \\ 0 & \text{otherwise} \end{cases}$$

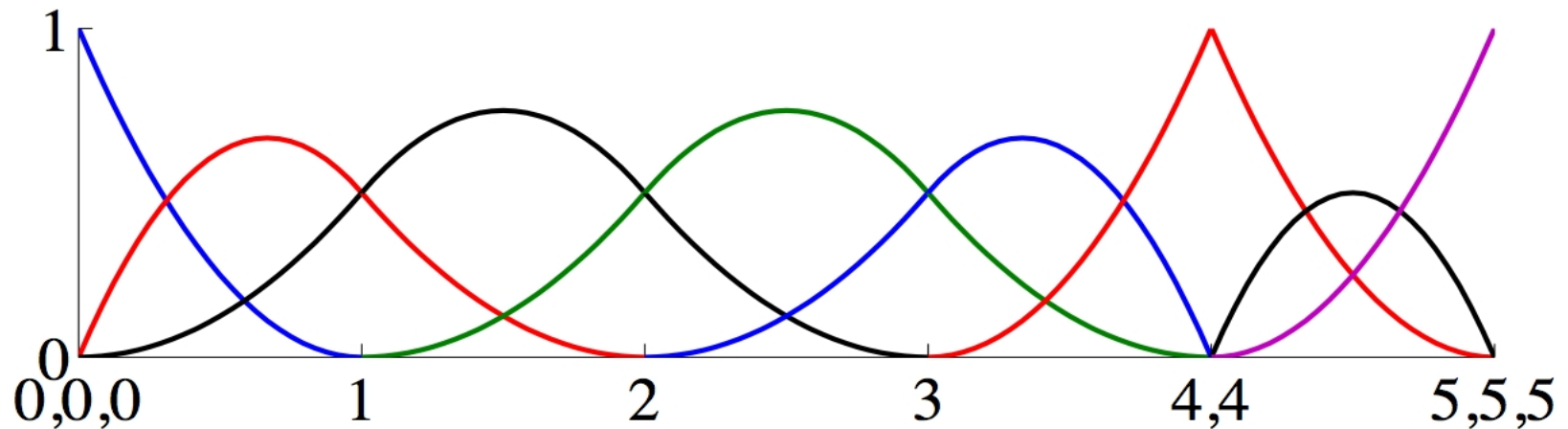
$$N_{i,p}(\xi) = \frac{\xi - \xi_i}{\xi_{i+p} - \xi_i} N_{i,p-1}(\xi) + \frac{\xi_{i+p+1} - \xi}{\xi_{i+p+1} - \xi_{i+1}} N_{i+1,p-1}(\xi)$$



B-spline basis functions of order 0, 1, 2 for a uniform knot vector:

$$\mathbf{E} = \{0, 1, 2, 3, 4, \dots\}$$

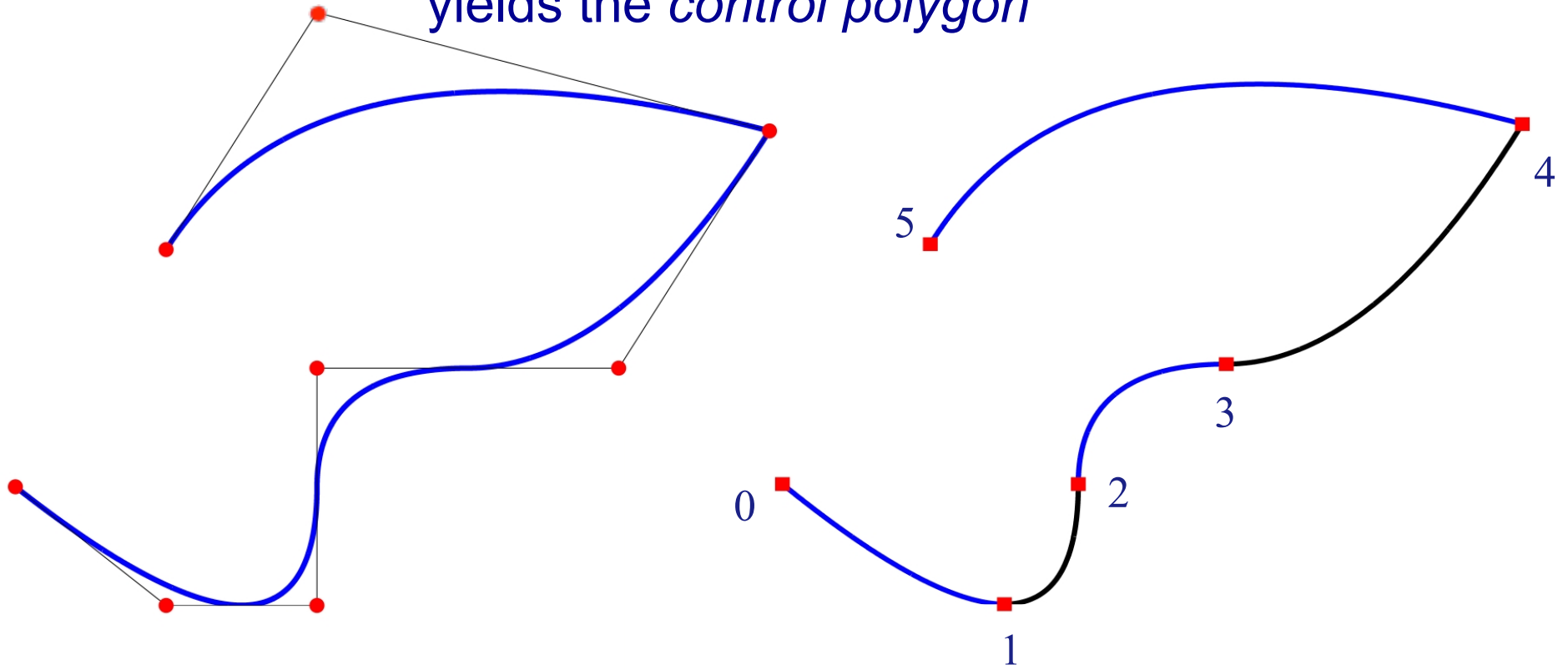




Quadratic ($p=2$) basis functions for an
open, non-uniform knot vector:

$$\Xi = \{0,0,0,1,2,3,4,4,5,5,5\}$$

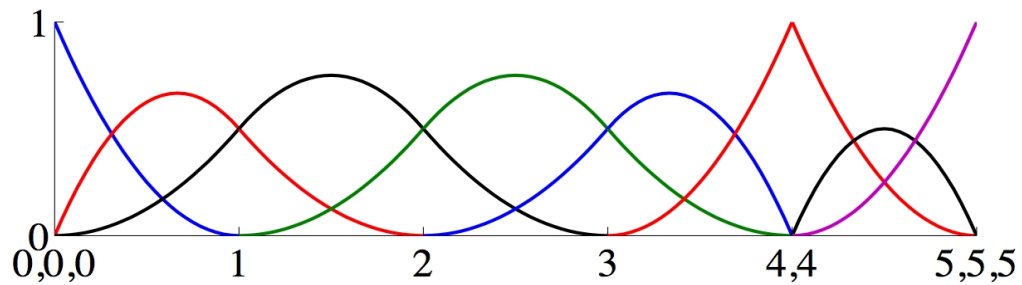
Linear interpolation of control points yields the *control polygon*



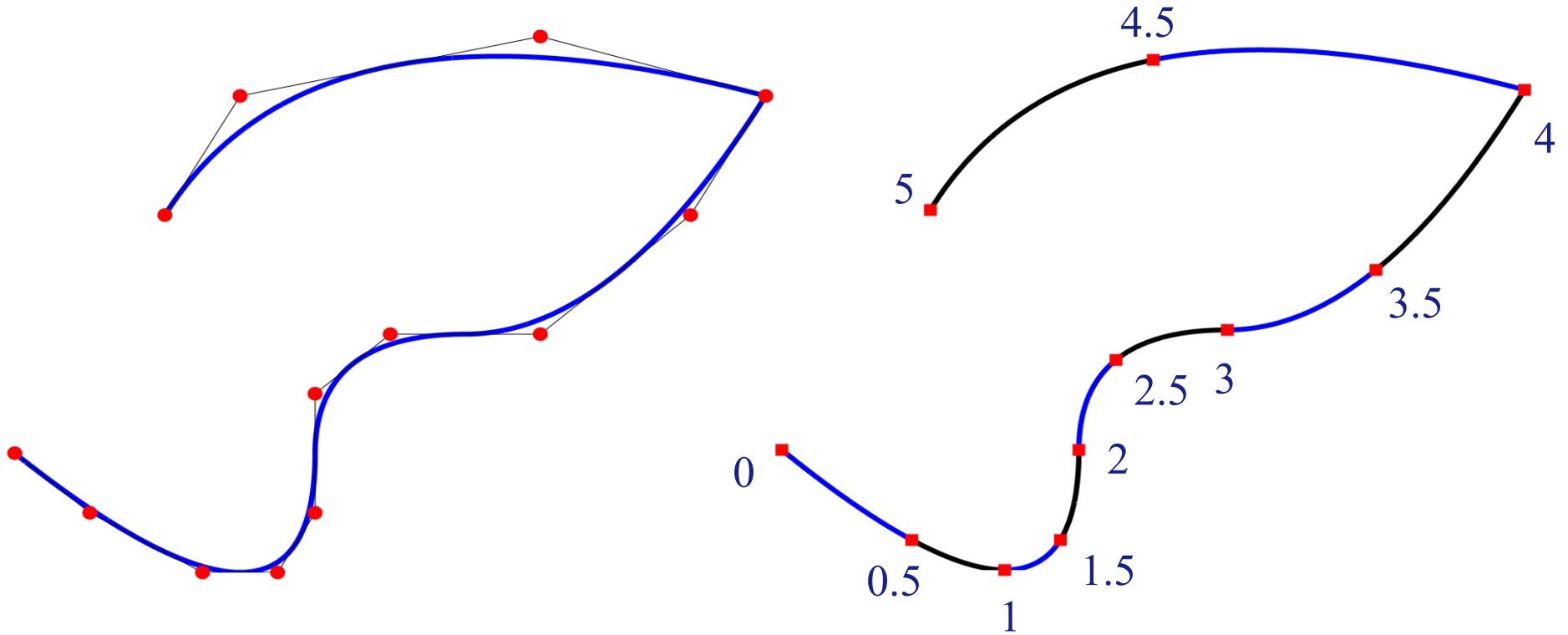
● - control points

■ - knots

Quadratic basis



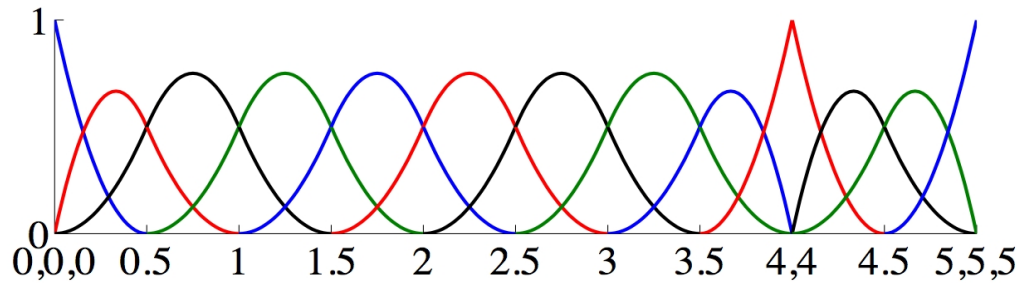
h-refined Curve



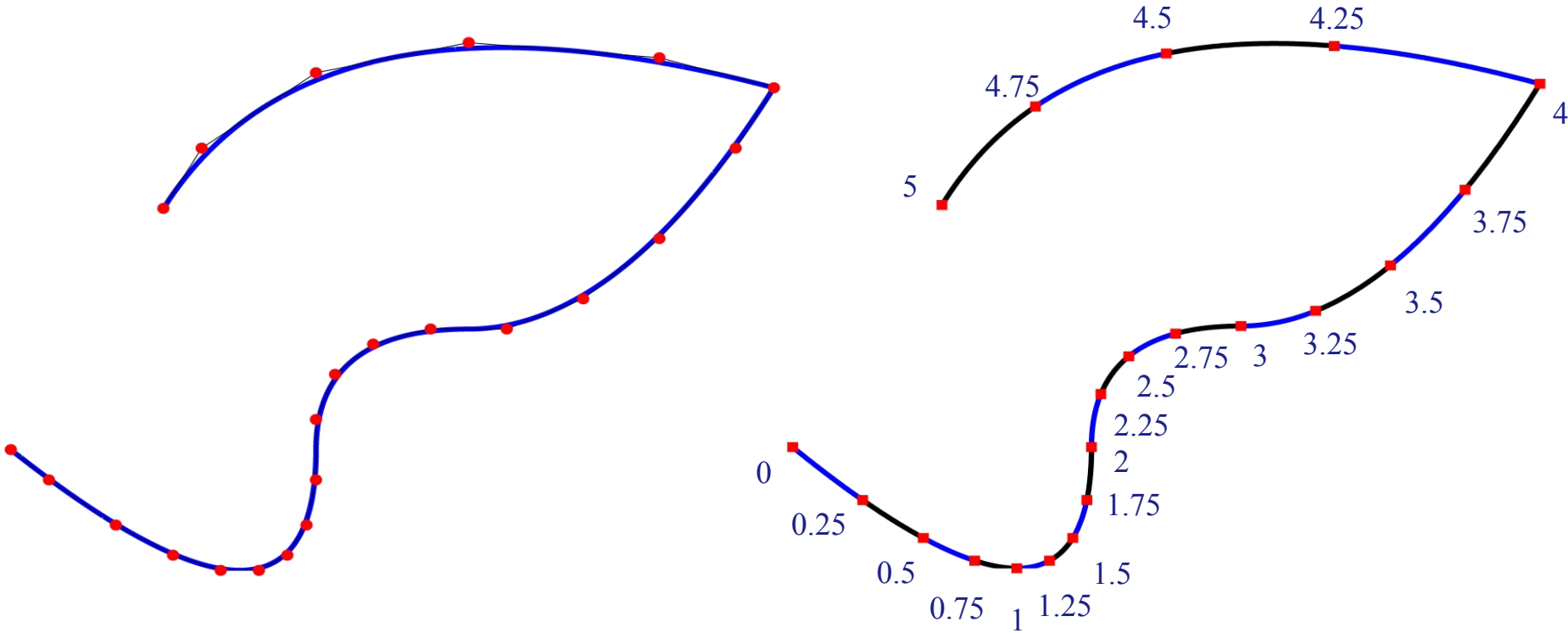
● - control points

■ - knots

Quadratic basis



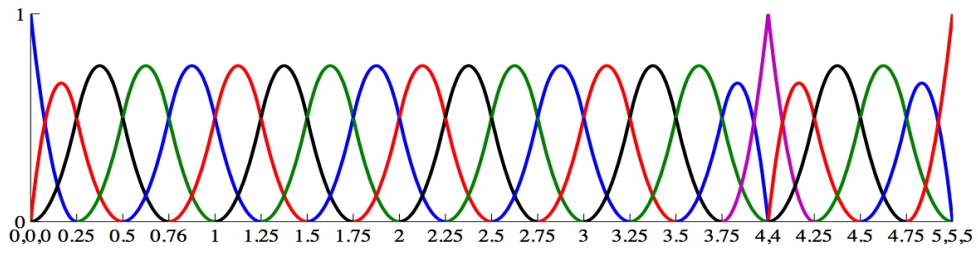
Further *h*-refined Curve



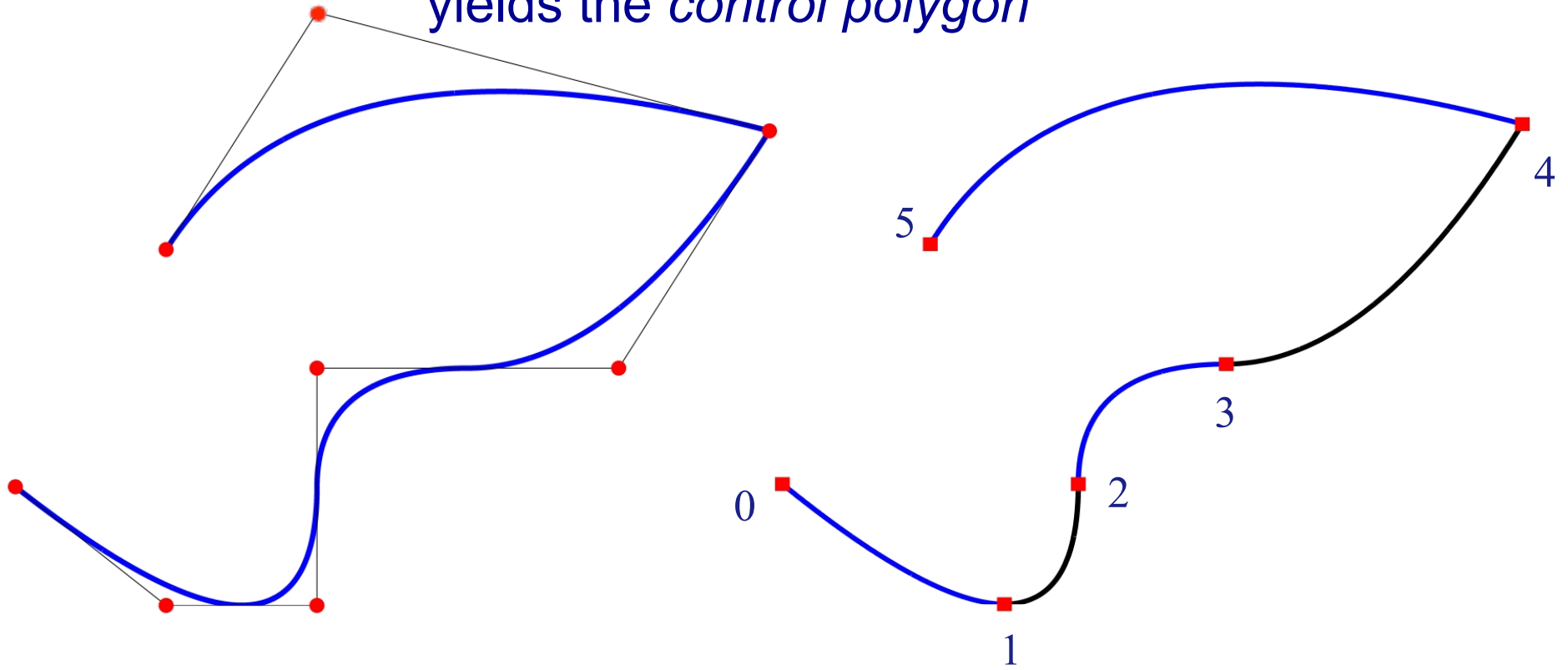
● - control points

■ - knots

Quadratic basis



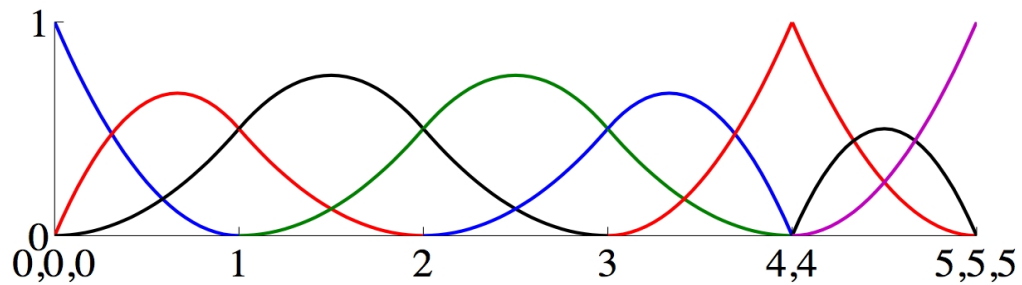
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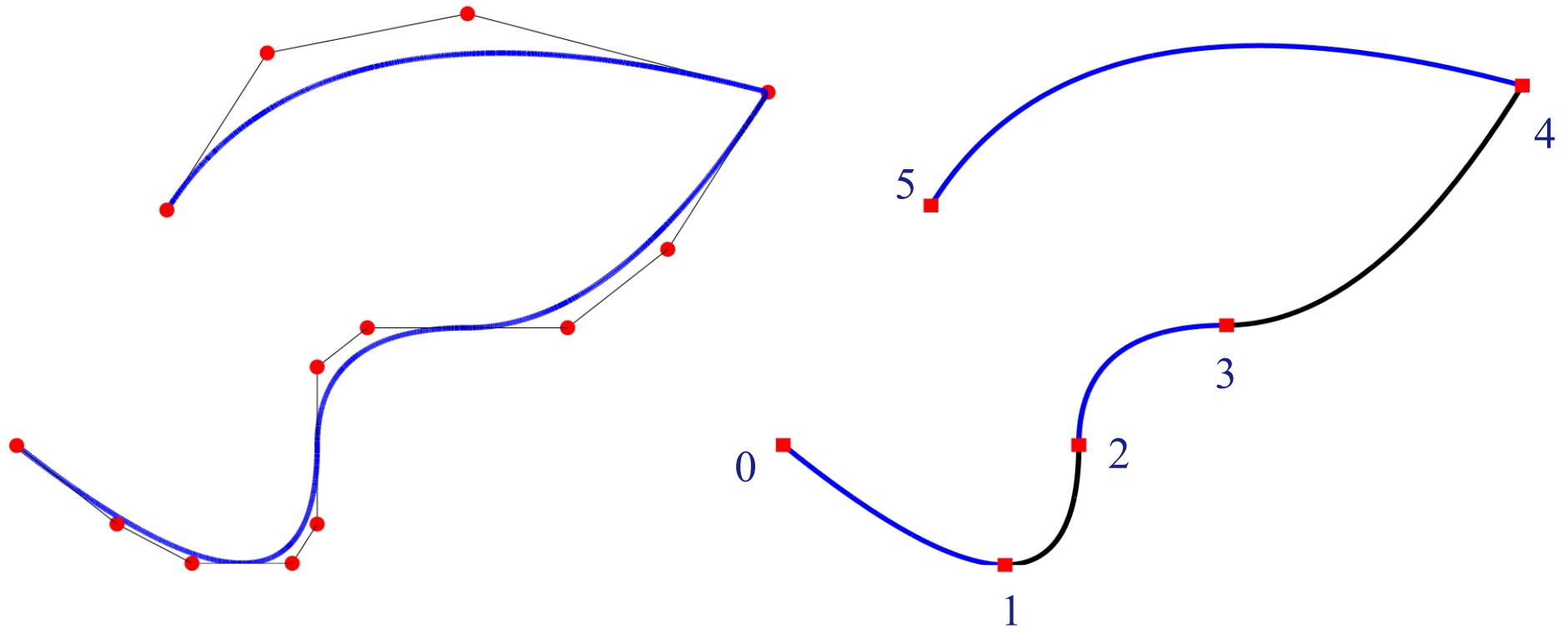
● - control points

■ - knots

Quadratic basis



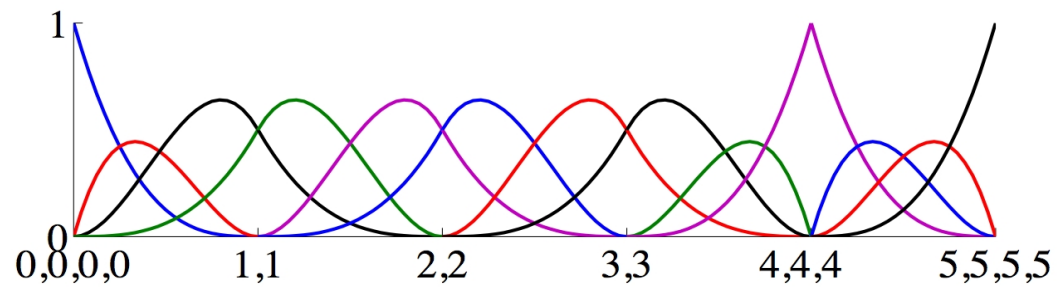
Cubic p -refined Curve



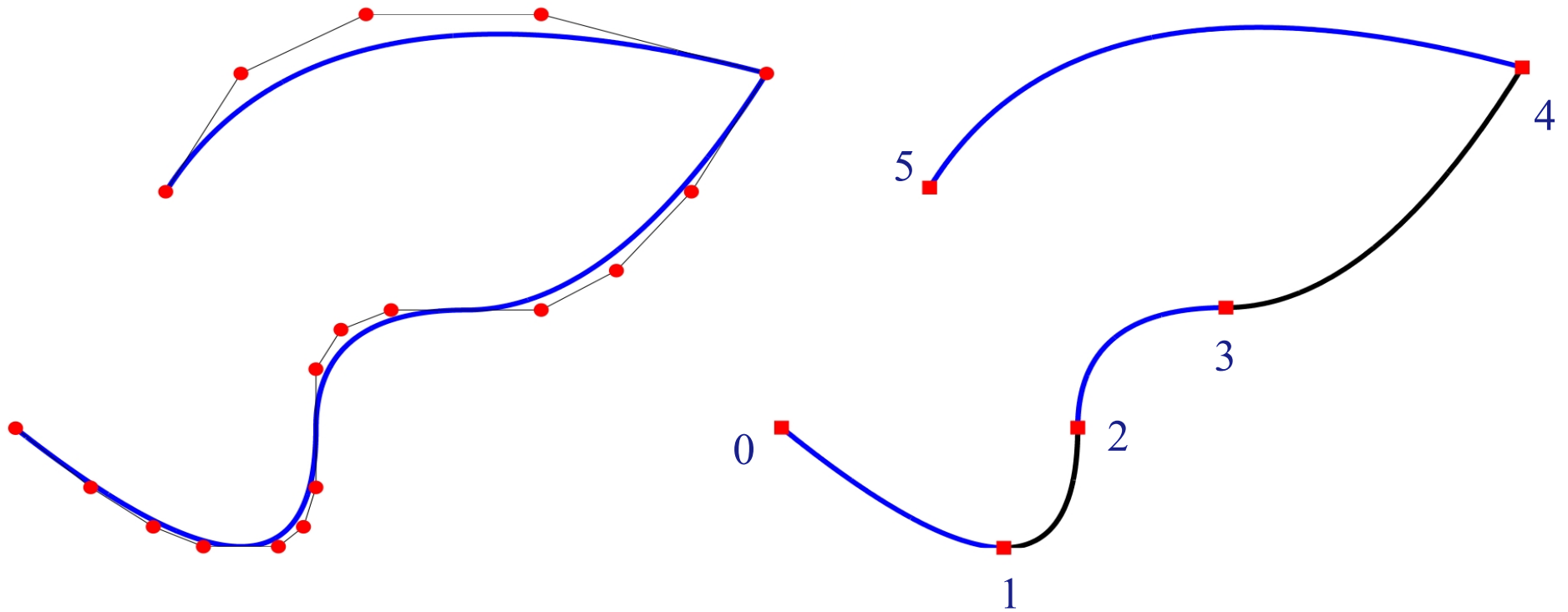
● - control points

■ - knots

Cubic basis



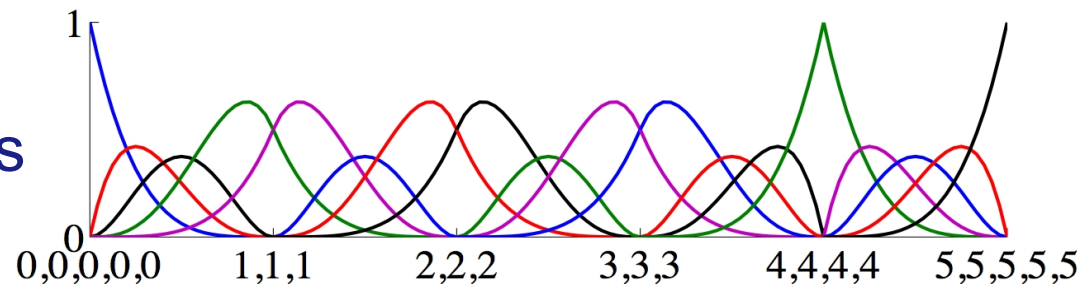
Quartic p -refined Curve



● - control points

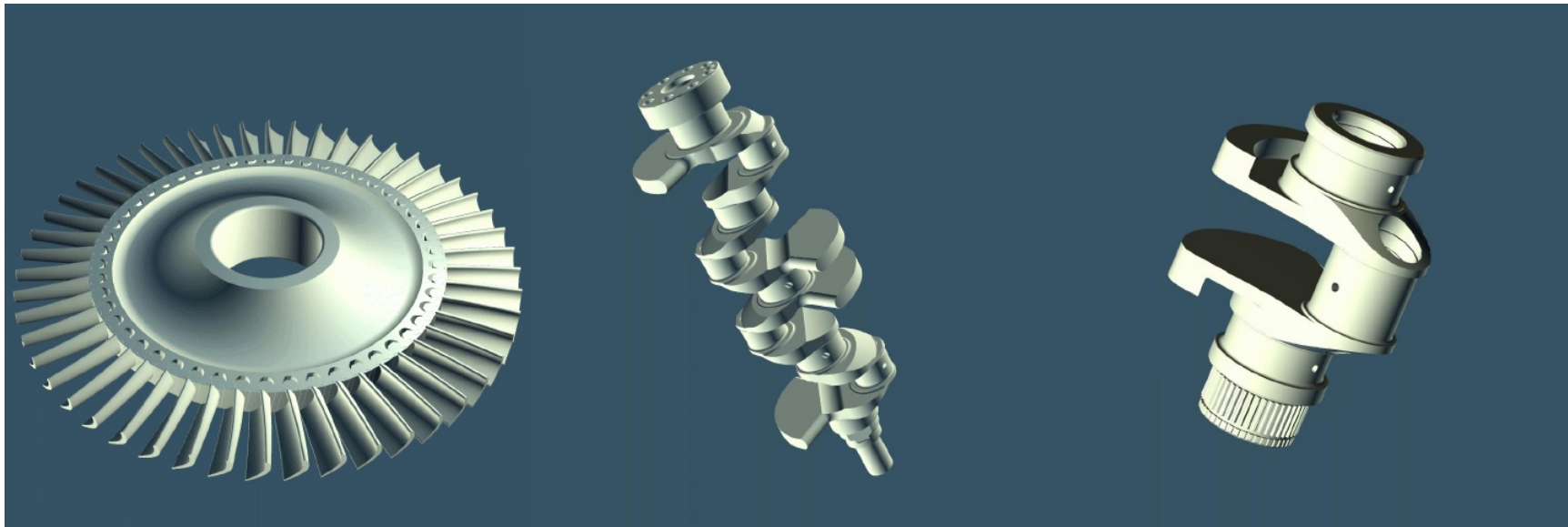
■ - knots

Quartic basis

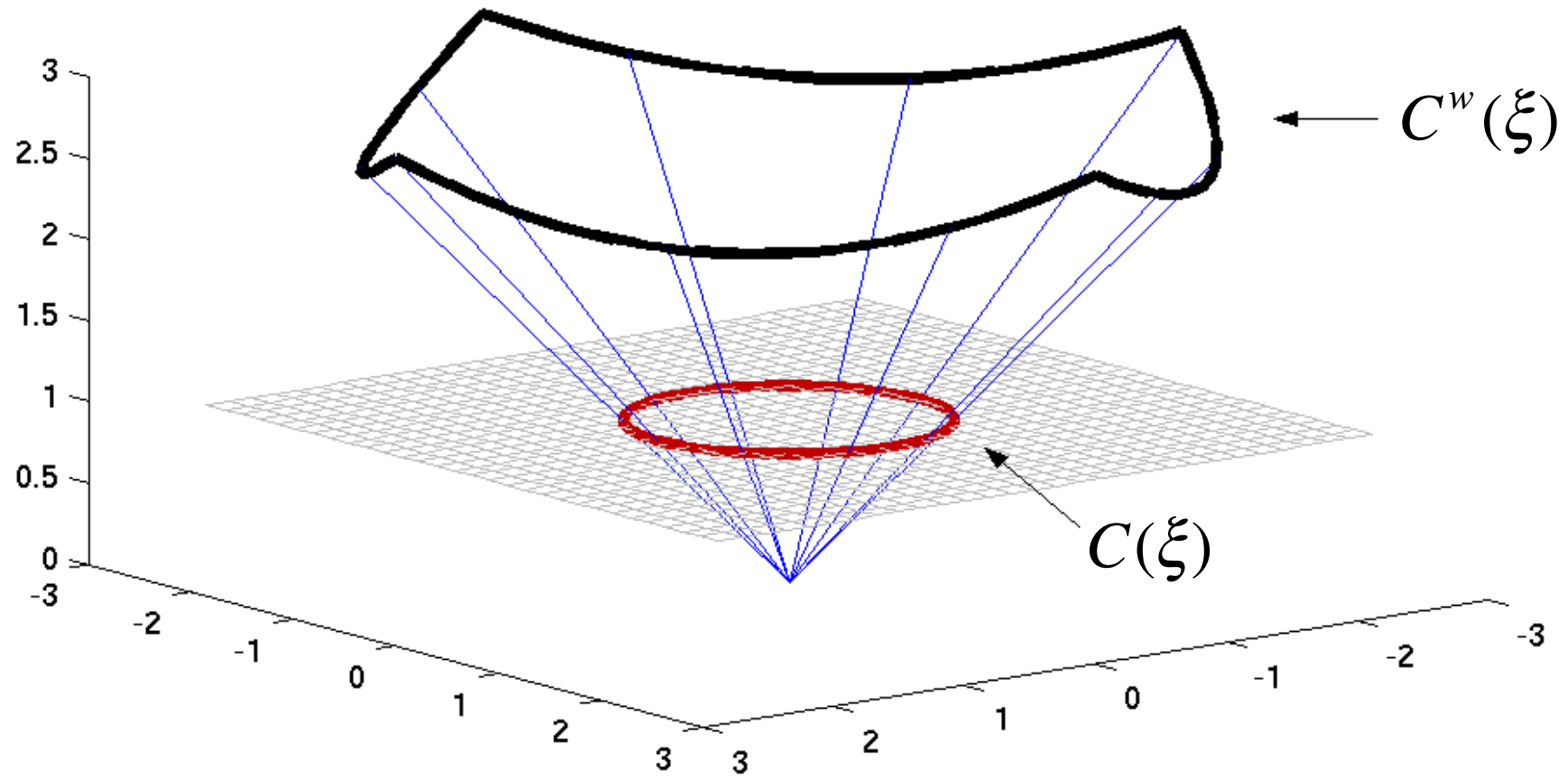


Non-Uniform Rational B-Splines

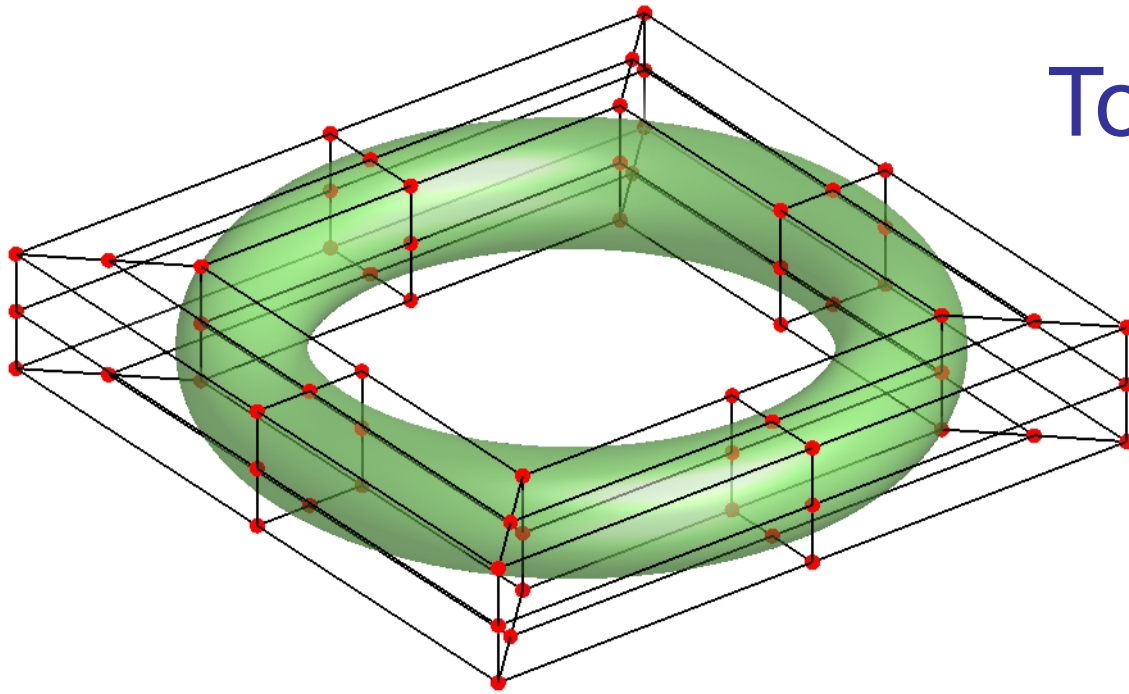
- NURBS are the most commonly used computer aided geometric design (CAGD) technology in engineering



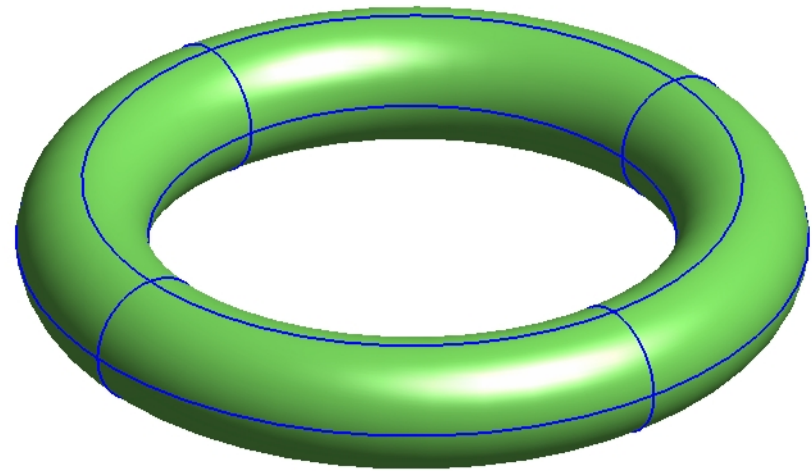
Circle from 3D Piecewise Quadratic Curves



Toroidal Surface

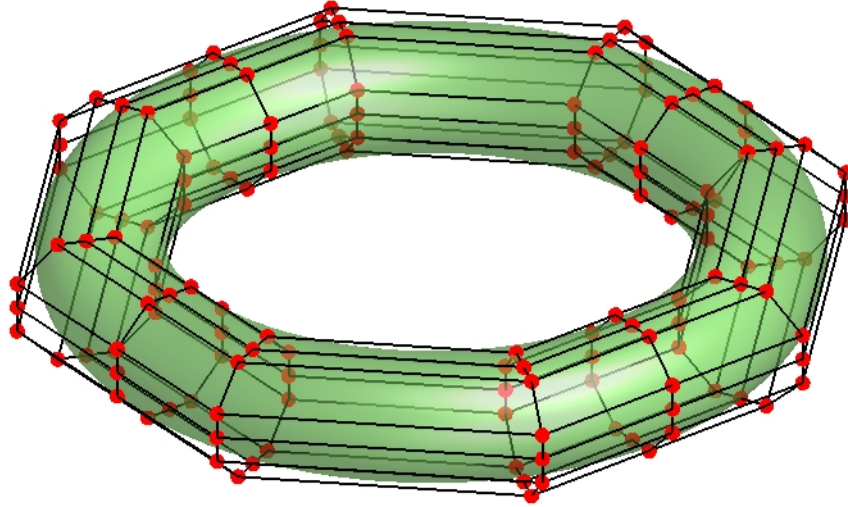


Control net

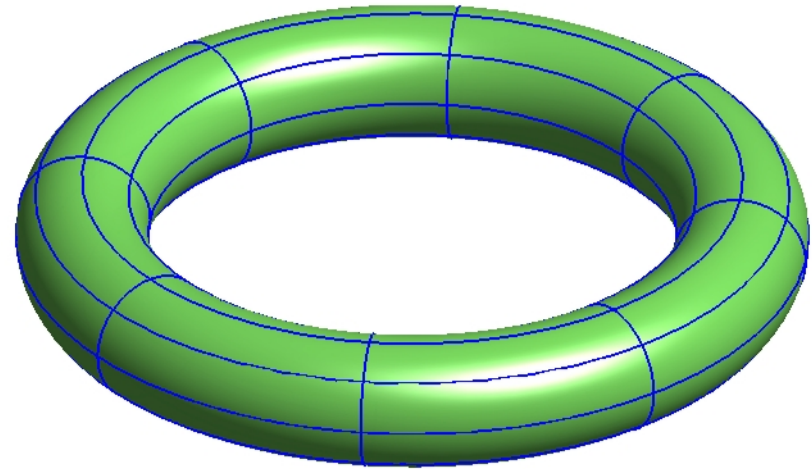


Mesh

h-refined Surface

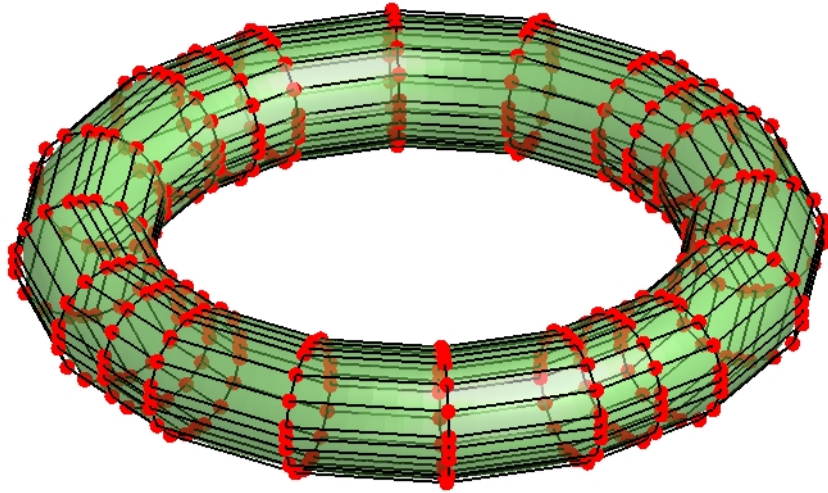


Control net

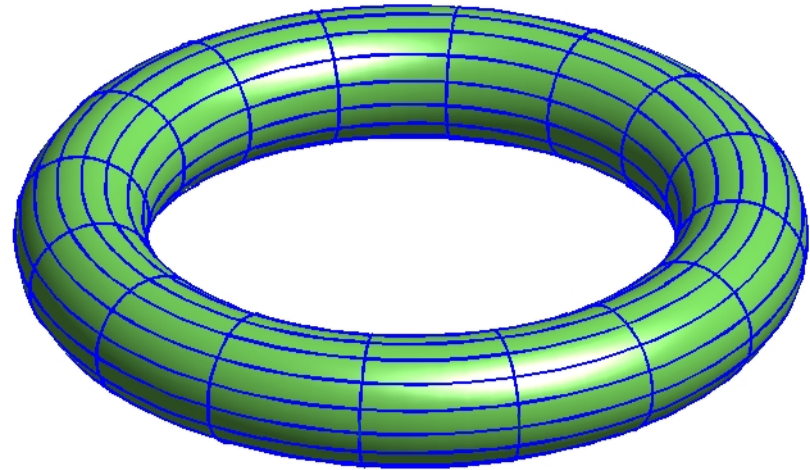


Mesh

Further h -refined
Surface

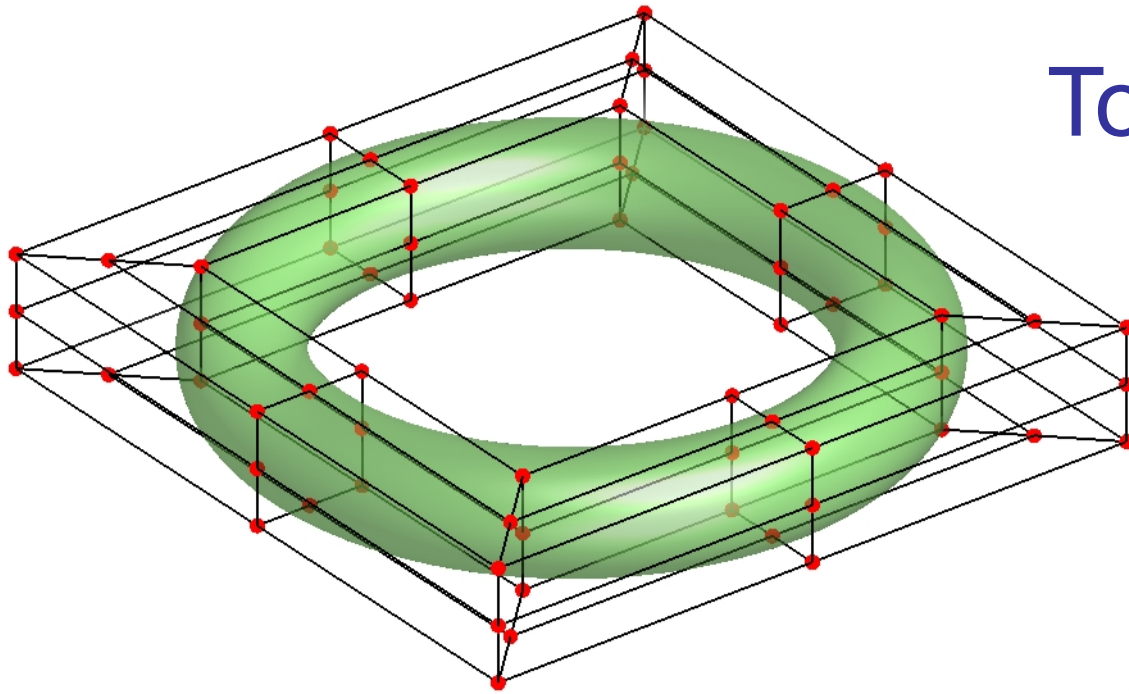


Control net

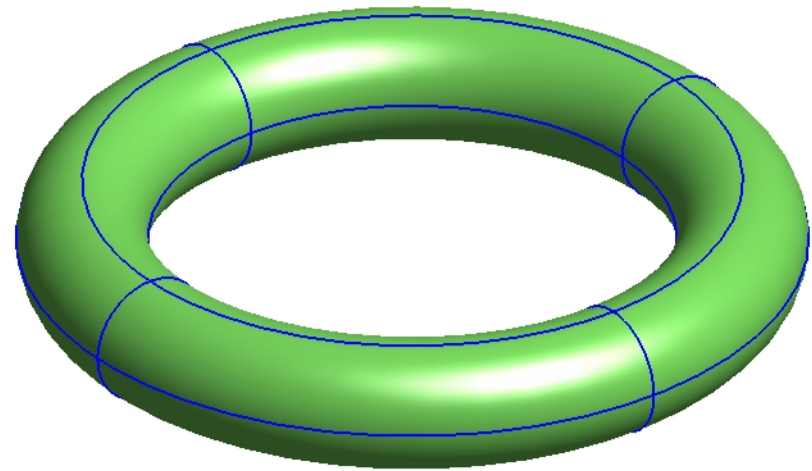


Mesh

Toroidal Surface

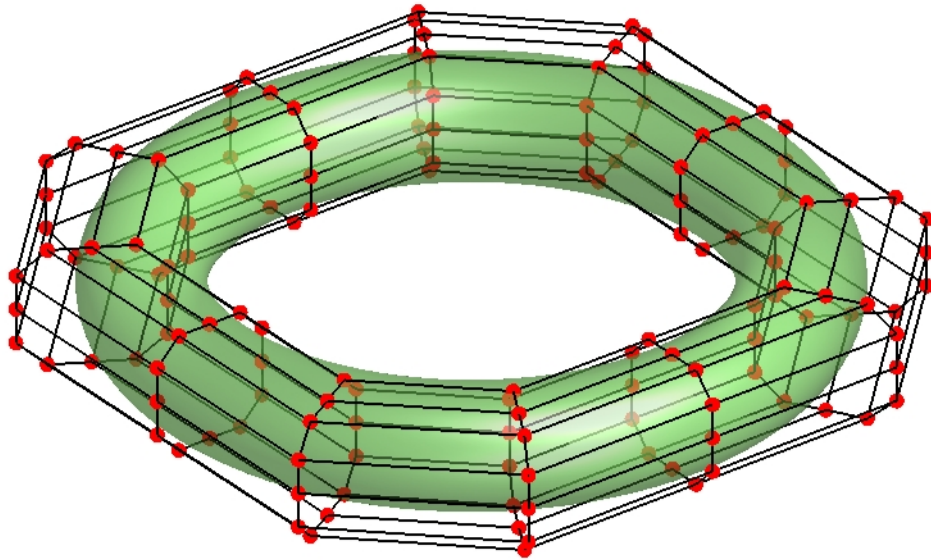


Control net

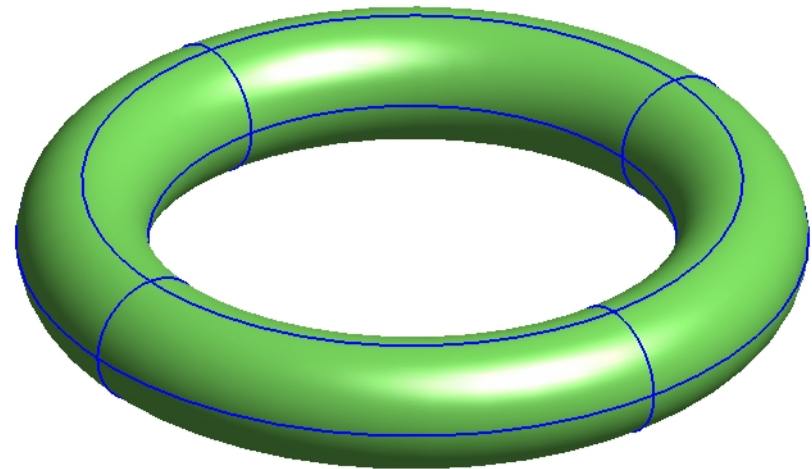


Mesh

Cubic p -refined Surface

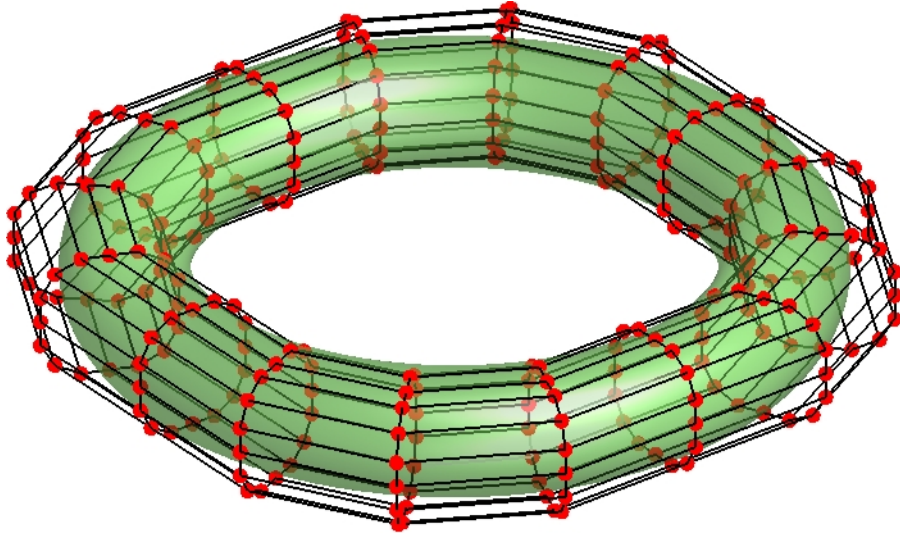


Control net

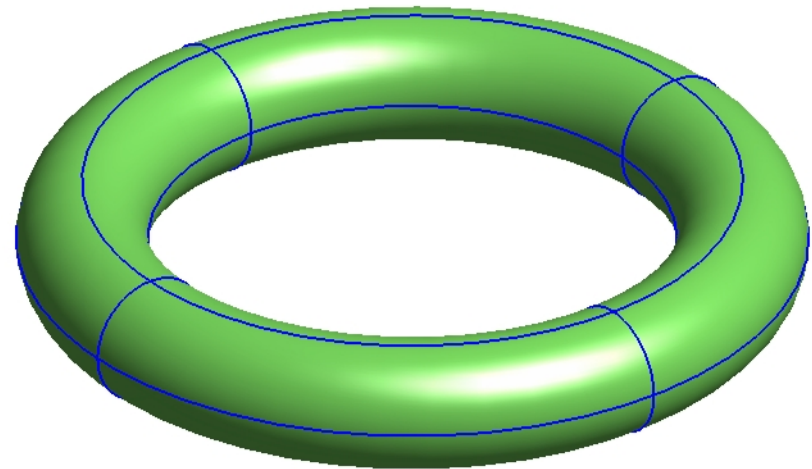


Mesh

Quartic p -refined Surface

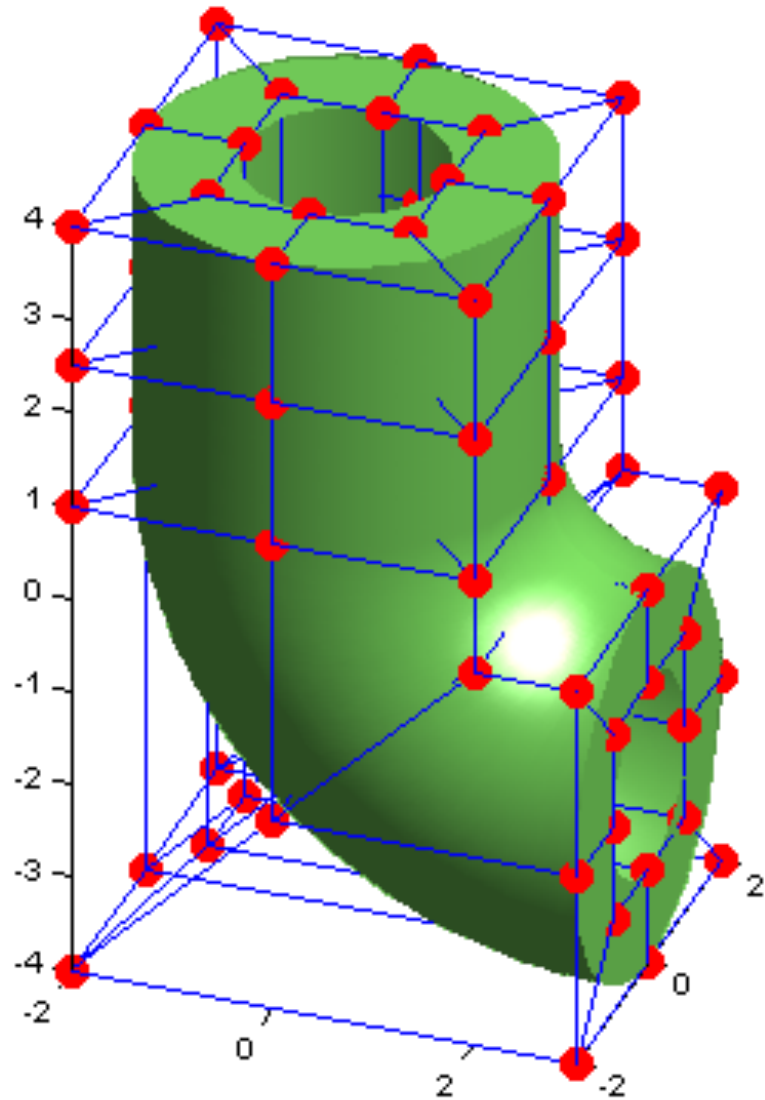


Control net

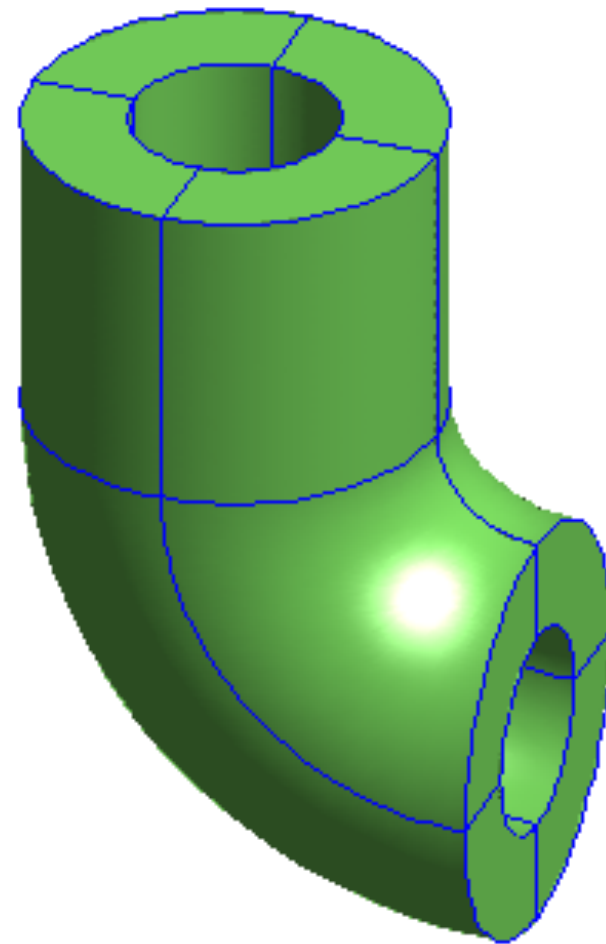


Mesh

Control Net



Mesh



Finite Element Analysis and NURBS-based Isogeometric Analysis

- | |
|-------------------------------------|
| ■ Compact support |
| ■ Partition of unity |
| ■ Affine covariance |
| ■ Isoparametric concept |
| ■ Patch tests satisfied |
| ■ Error estimates in Sobolev norms* |

*Y. Bazilevs, L. Beirão da Veiga, J.A. Cottrell, TJRH, & G. Sangalli, 2006

An Examination of the Helmholtz Pollution Effect for FEM and NURBS

Problem Statement

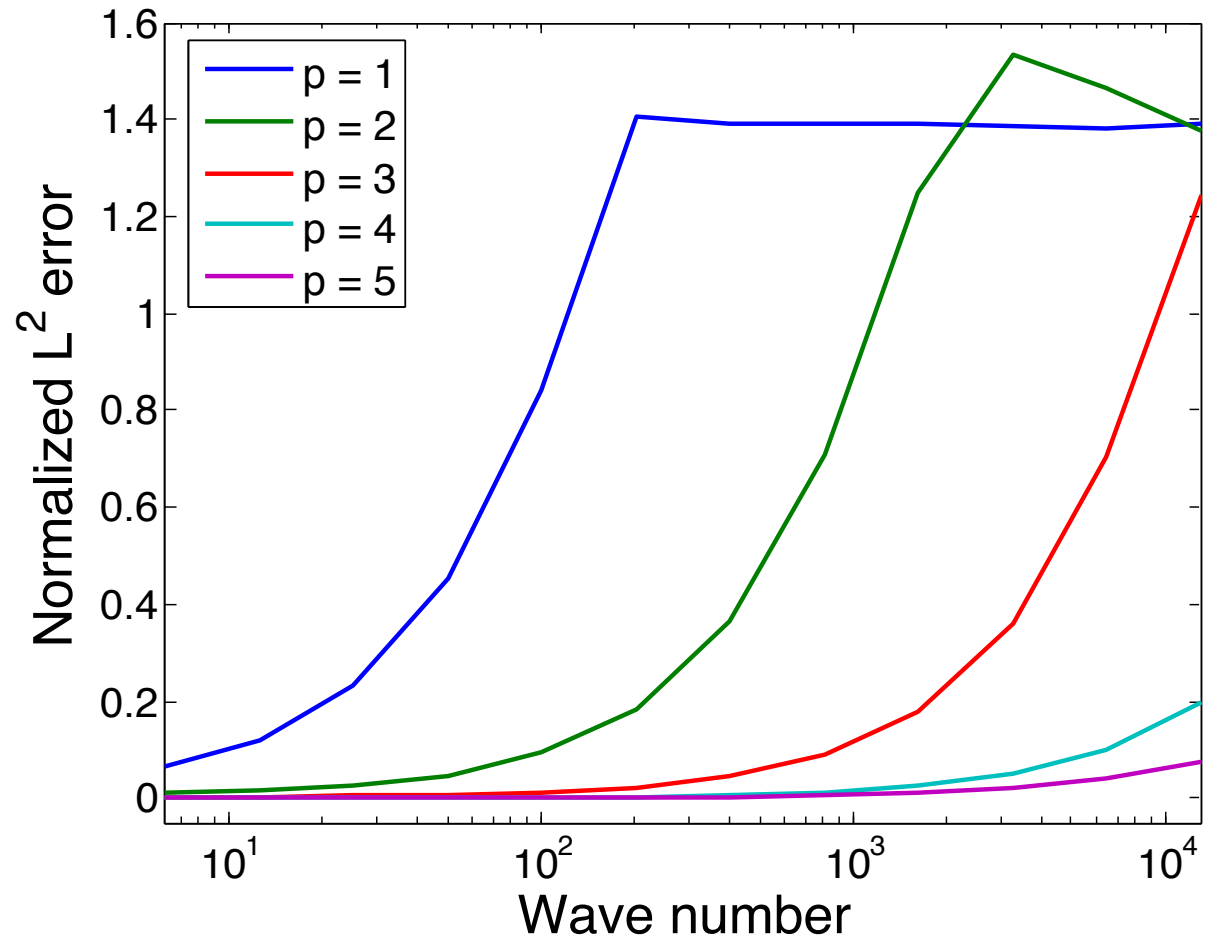
Model Problem:

$$u''(x) + k^2 u(x) = 0 \text{ on } (0,1)$$
$$u(0) = 1$$
$$u'(1) - iku(1) = 0$$

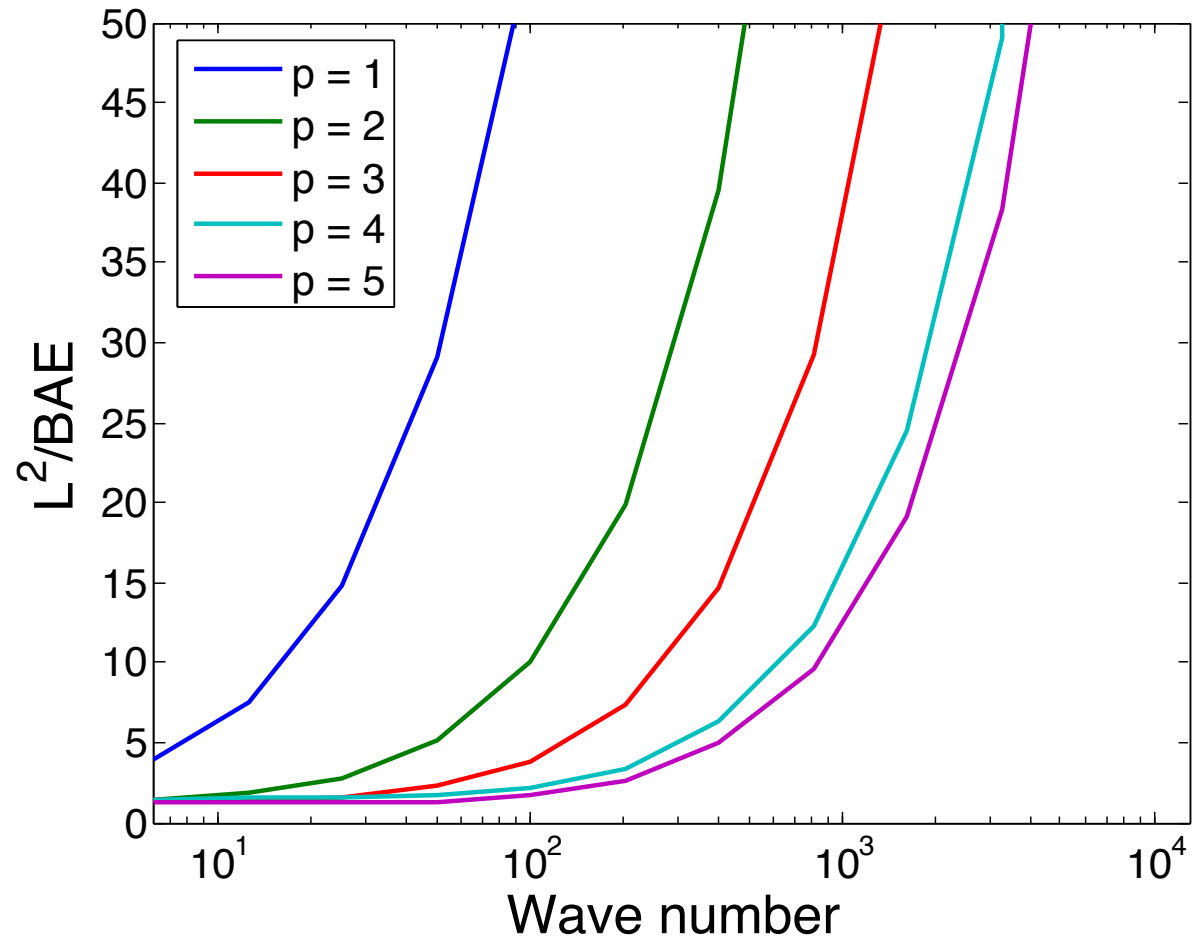
Exact Solution:

$$u(x) = \exp(ikx)$$

Pollution: FEM

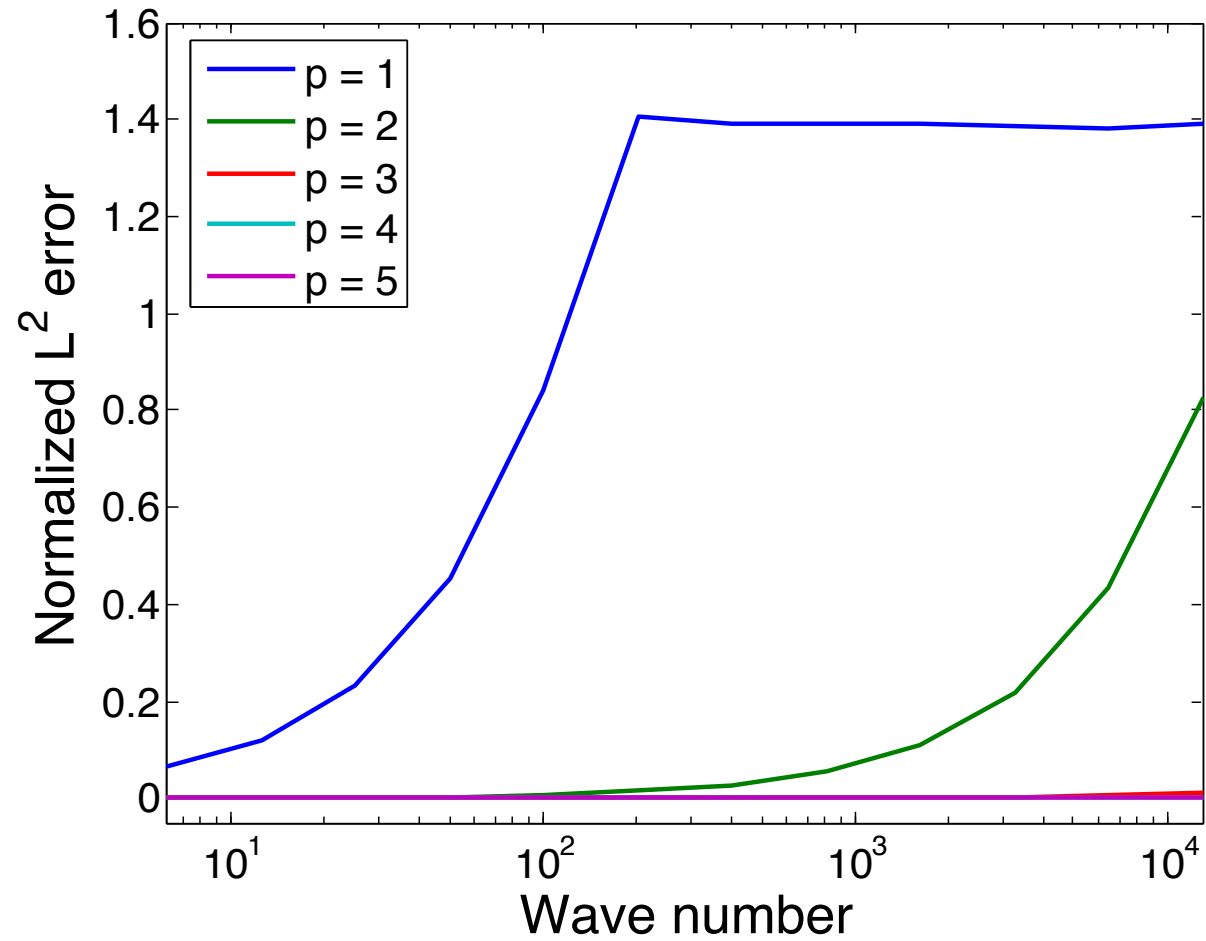


Pollution: FEM

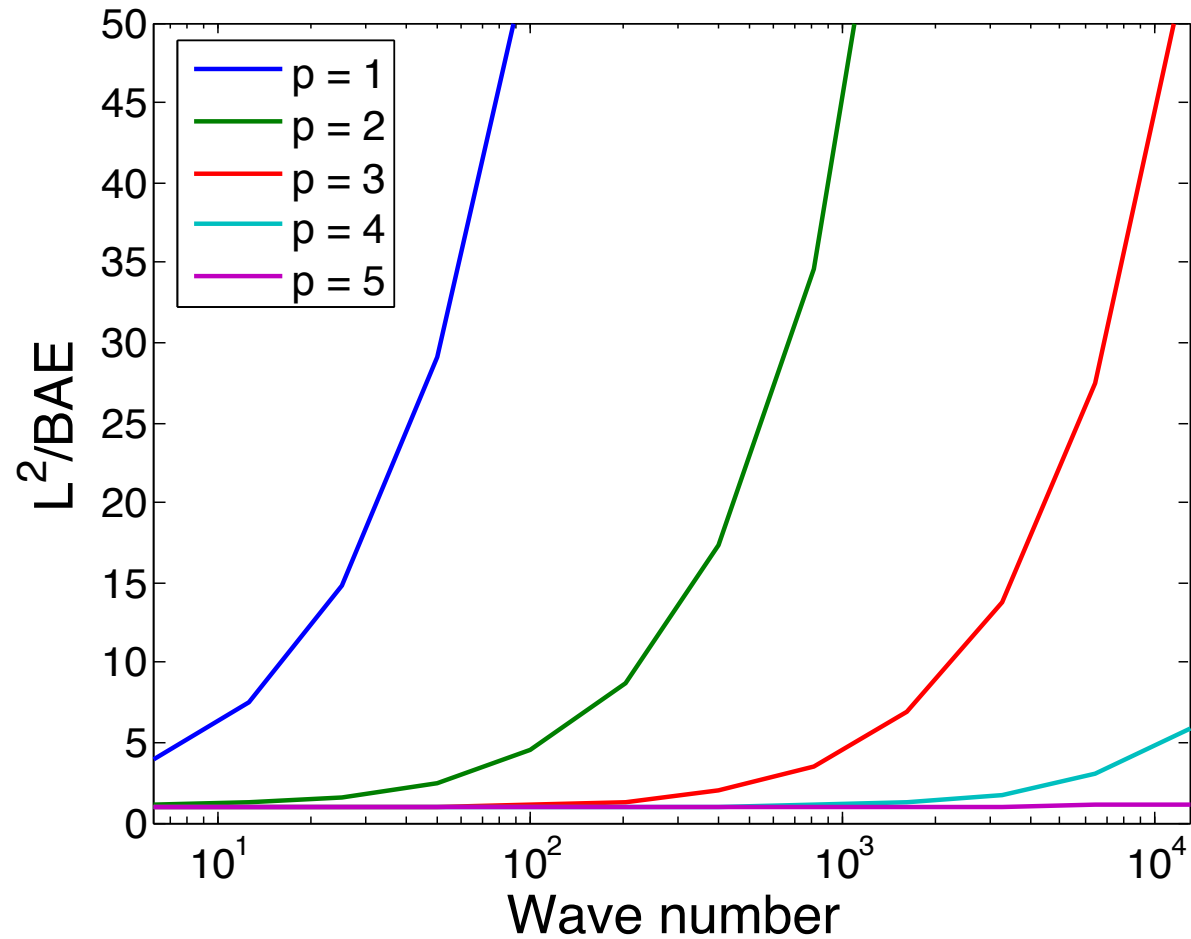


BAE: Best Approximation Error

Pollution: NURBS

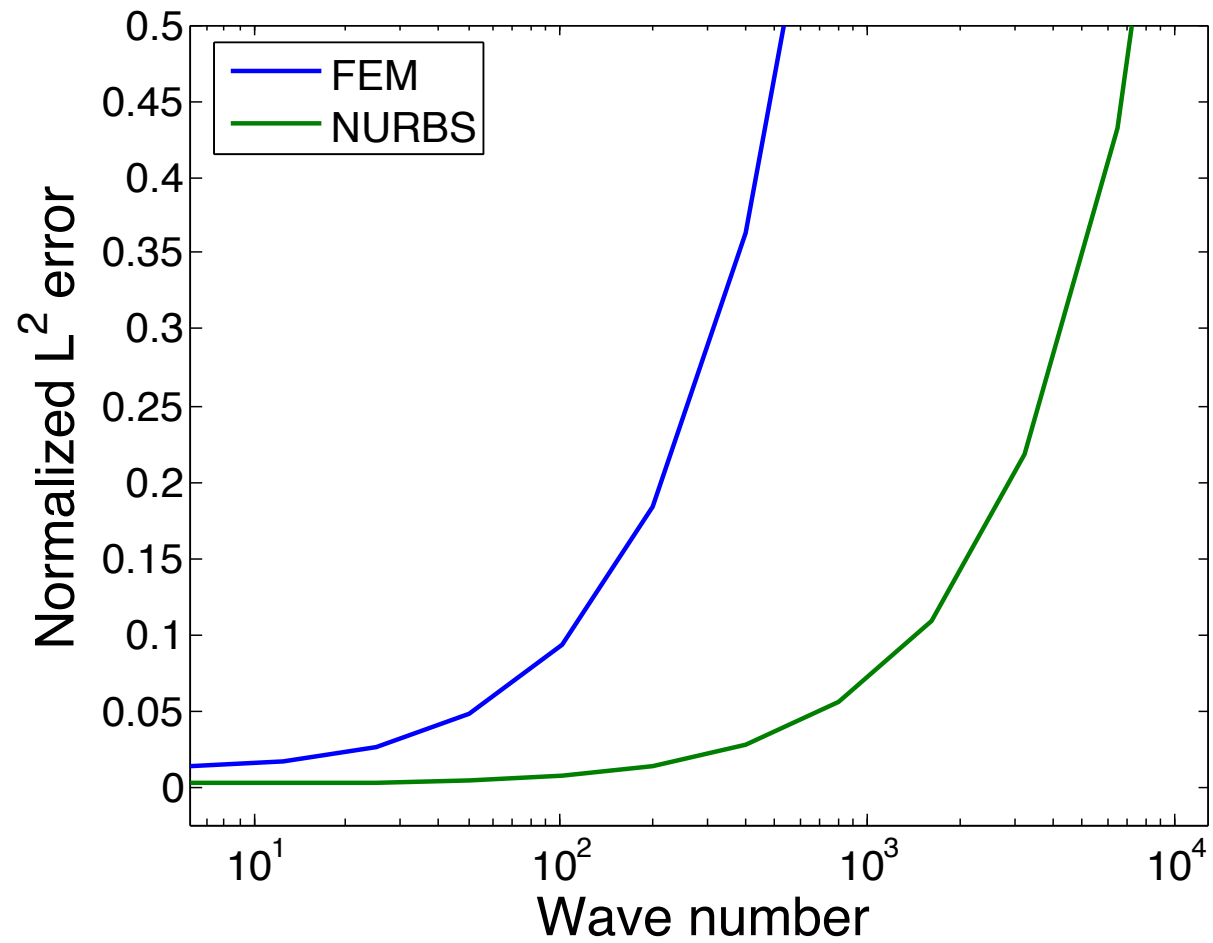


Pollution: NURBS

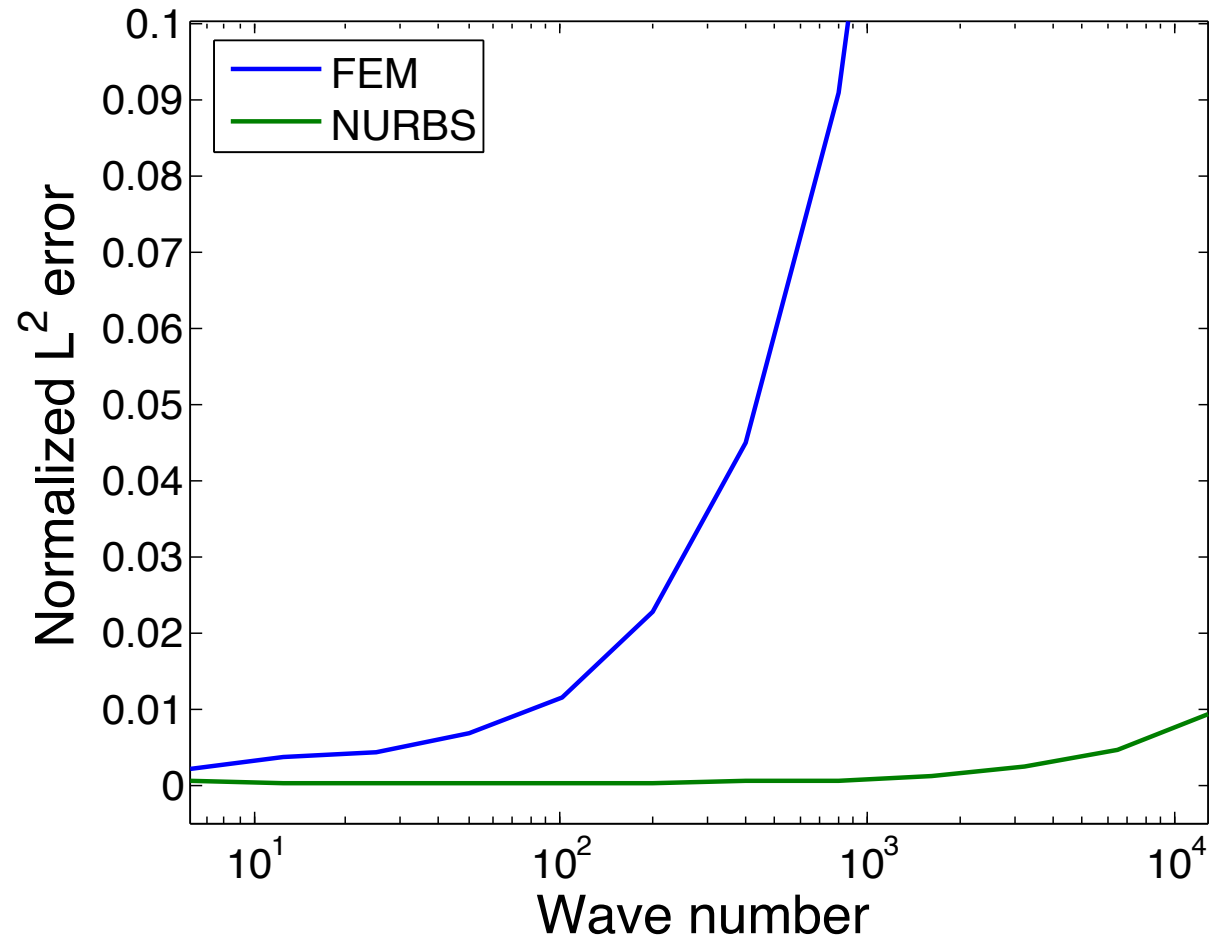


BAE: Best Approximation Error

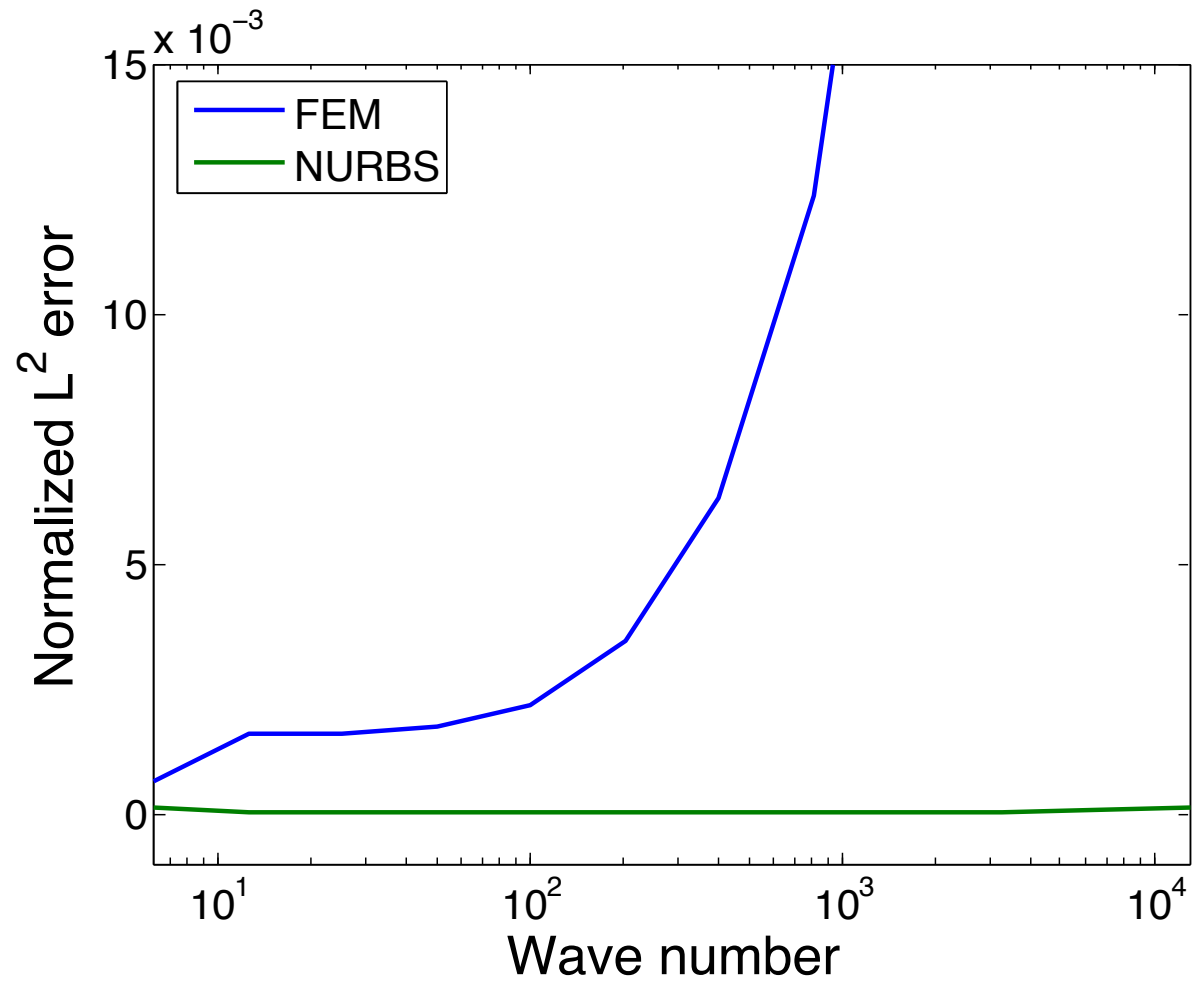
Pollution: Degree 2 Comparison



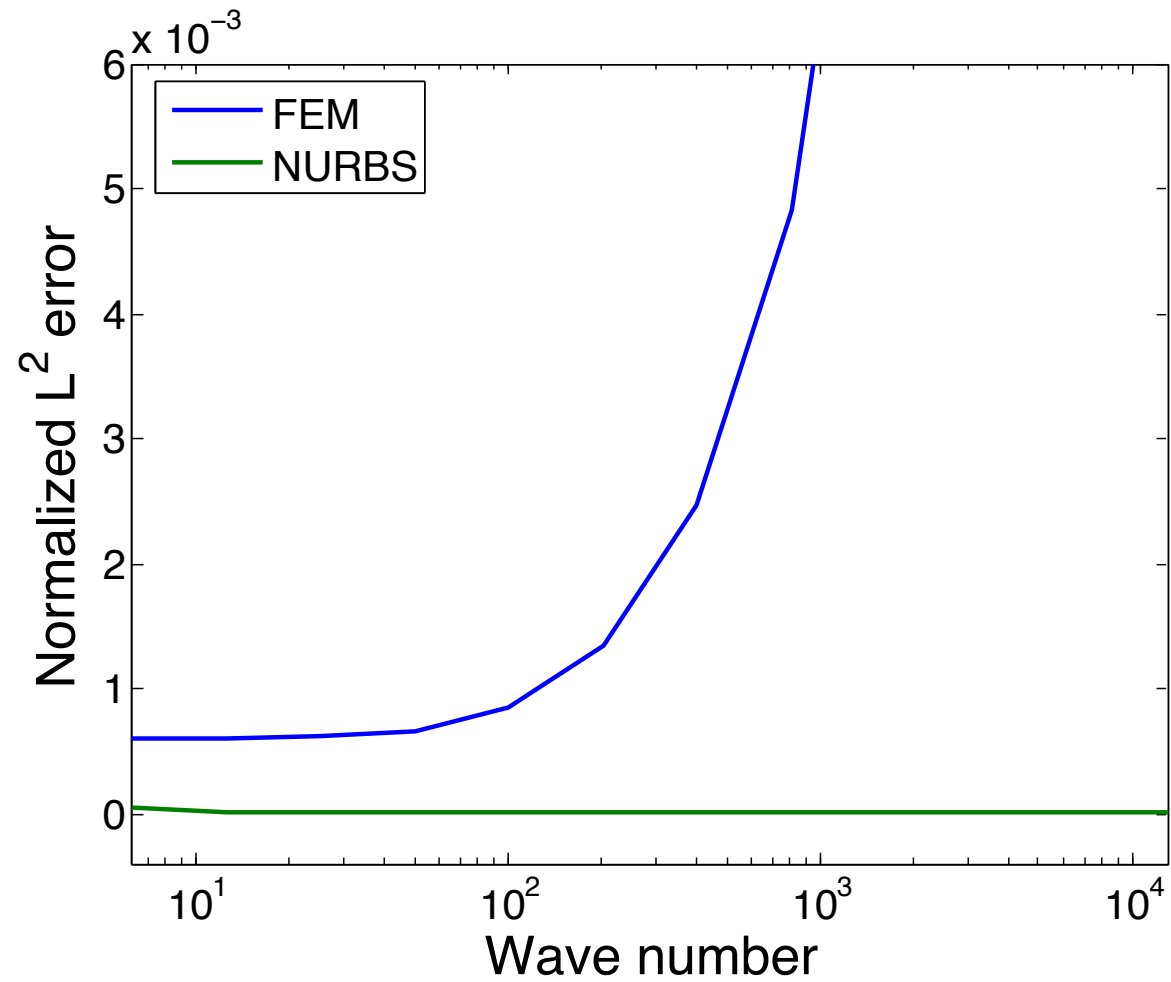
Pollution: Degree 3 Comparison



Pollution: Degree 4 Comparison

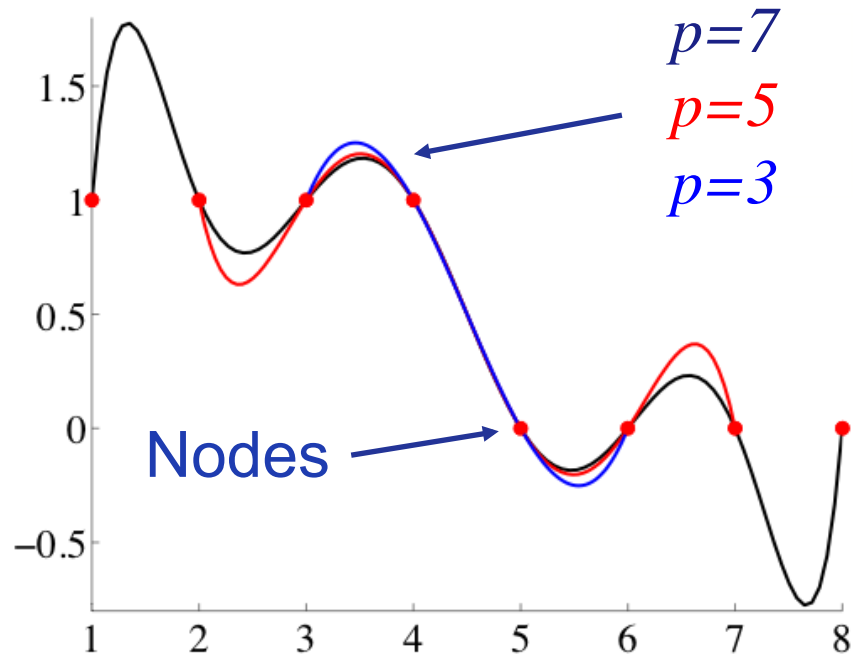


Pollution: Degree 5 Comparison

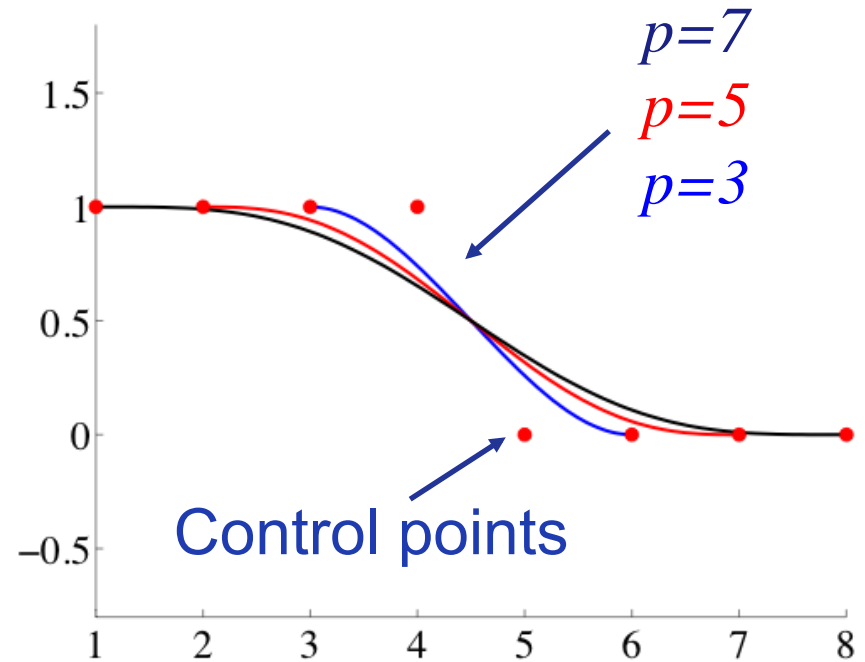


Variation Diminishing Property

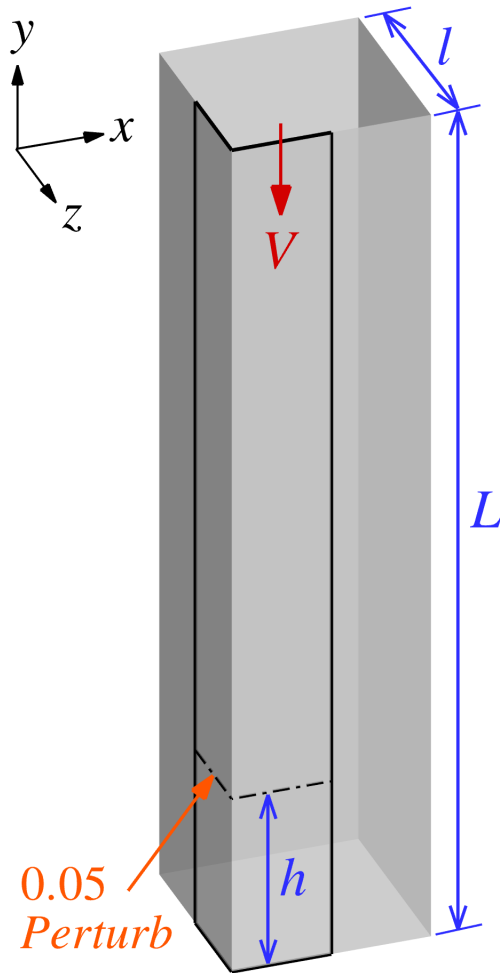
Lagrange polynomials



NURBS



Square Tube Buckling

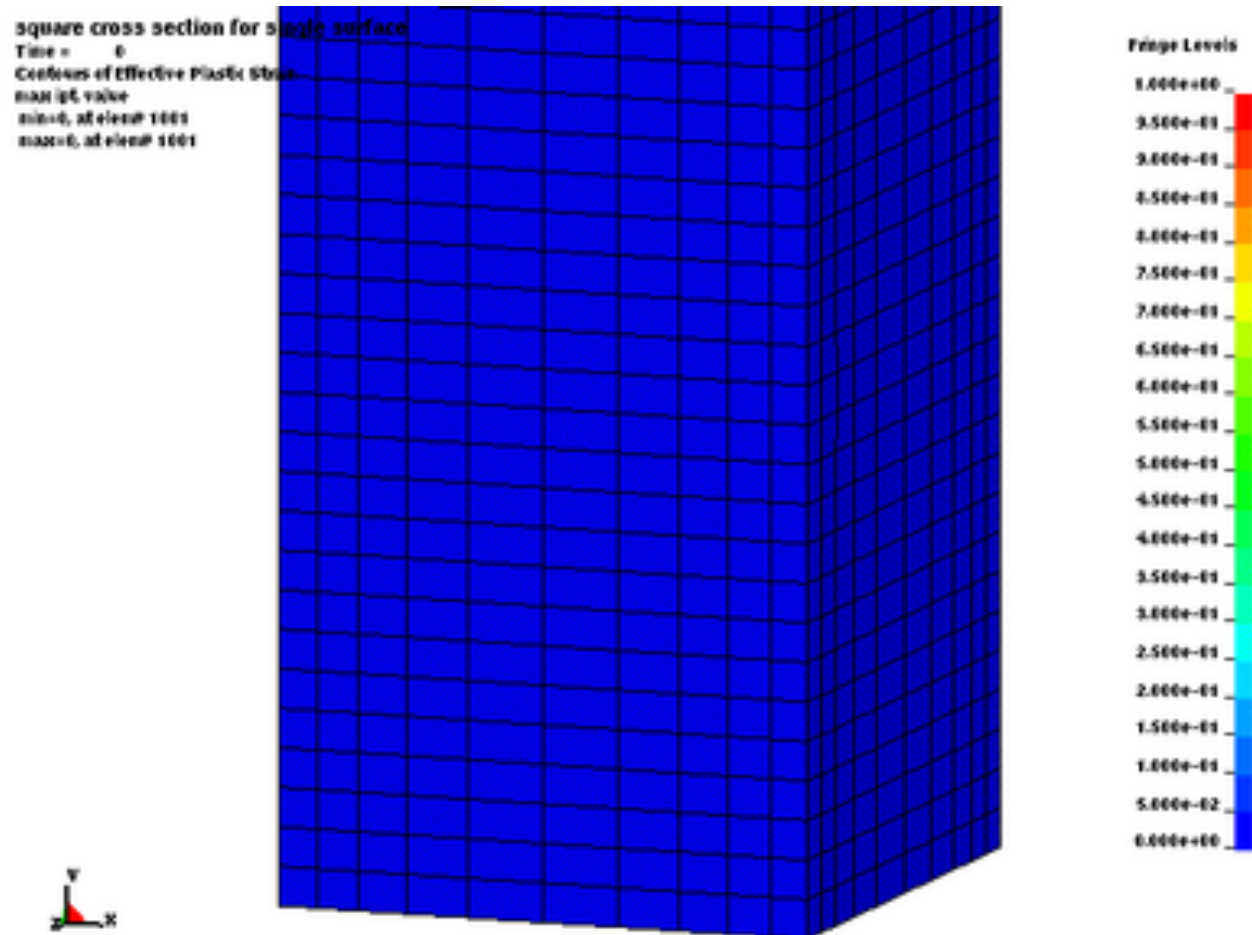


- Standard benchmark for automobile crashworthiness
- Quarter symmetry
- Perturbation to initiate buckling mode
- J_2 plasticity with linear isotropic hardening

(LS DYNA, D. Benson *et al.*)

Smooth Functions are Robust

C^3 quartics in LS DYNA



IGA and Collocation

1. Use the *strong* variational form of the equations.
2. One quadrature point per node/control point.
3. The ultimate reduced quadrature method.
4. 1D theoretical result*: $O(p-1)$ in $W^{2,\infty}$ for all p (optimal).
5. Observed numerically in multi-D*:
 $O(p)$ in L^∞ and $W^{1,\infty}$ for p even
 $O(p-1)$ in L^∞ and $W^{1,\infty}$ for p odd

*F. Auricchio, L. B. Da Veiga, T. J. R. Hughes, A. Reali, and G. Sangalli, "ISOGEOOMETRIC COLLOCATION METHODS," *Mathematical Models and Methods in Applied Sciences*, vol. 20, no. 11, pp. 2075–2107, Nov. 2010.
<http://www.worldscientific.com/doi/abs/10.1142/S0218202510004878>

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5. Observed numerically in multi-D*:
 $O(p)$ in L^∞ and $W^{1,\infty}$ for p even (optimal)
 $O(p-1)$ in L^∞ and $W^{1,\infty}$ for p odd

*F. Auricchio, L. B. Da Veiga, T. J. R. Hughes, A. Reali, and G. Sangalli, "ISOGEOOMETRIC COLLOCATION METHODS," *Mathematical Models and Methods in Applied Sciences*, vol. 20, no. 11, pp. 2075–2107, Nov. 2010.
<http://www.worldscientific.com/doi/abs/10.1142/S0218202510004878>

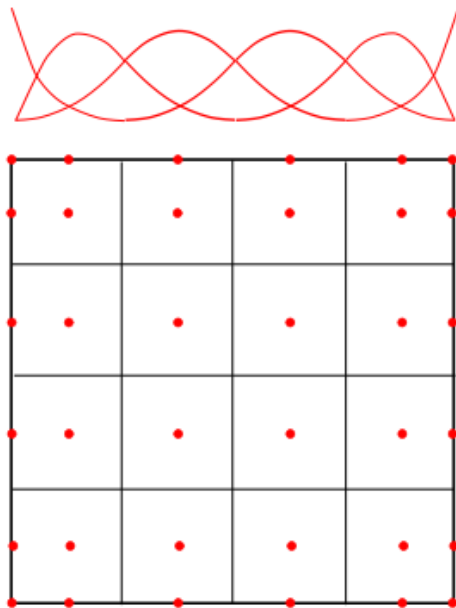
IGA and Collocation

1. Use the *strong* variational form of the equations.
2. One quadrature point per node/control point.
3. The ultimate reduced quadrature method.
4. 1D theoretical result*: $O(p-1)$ in $W^{2,\infty}$ for all p (optimal).
5. Observed numerically in multi-D*:
 $O(p)$ in L^∞ and $W^{1,\infty}$ for p even (optimal)
 $O(p-1)$ in L^∞ and $W^{1,\infty}$ for p odd (suboptimal)

*F. Auricchio, L. B. Da Veiga, T. J. R. Hughes, A. Reali, and G. Sangalli, "ISOGEOOMETRIC COLLOCATION METHODS," *Mathematical Models and Methods in Applied Sciences*, vol. 20, no. 11, pp. 2075–2107, Nov. 2010.
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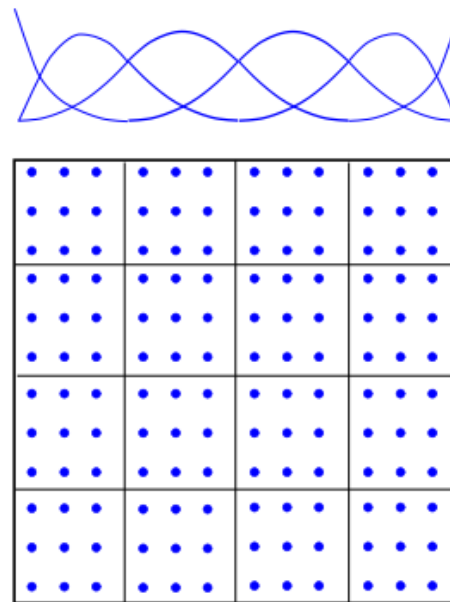
Quadrature points for $p = 2$

Isogeometric collocation (IGA-C)



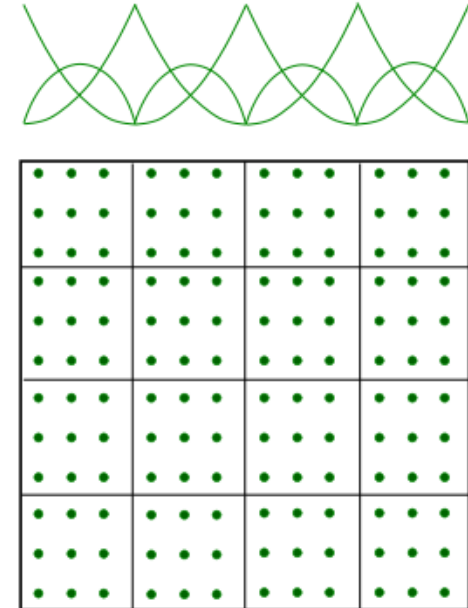
Greville points

Isogeometric Galerkin (IGA-G)



3 X 3 Gauss

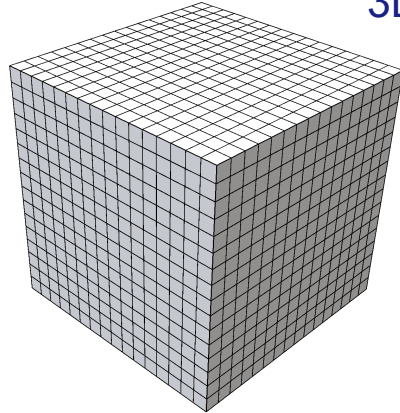
C^0 Finite Elements (FEA-G)



3 X 3 Gauss

Benchmark problem: Linear elasticity in 3D

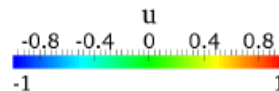
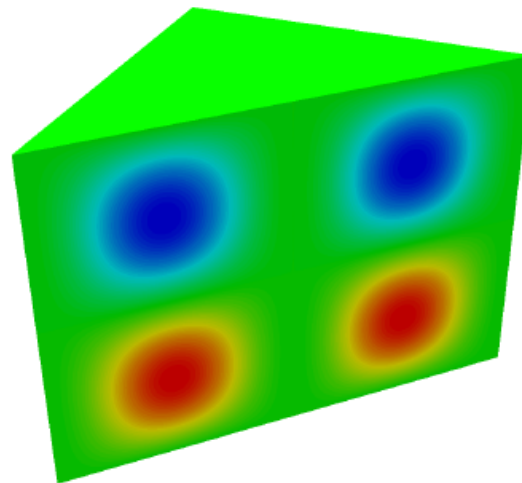
3D domain



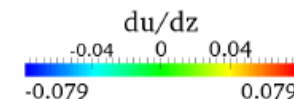
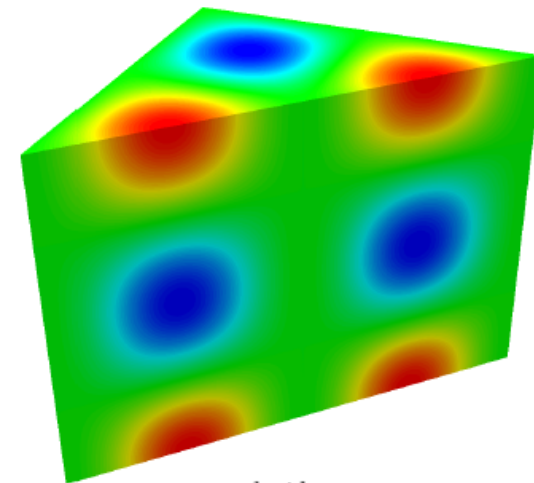
Exact solution:

$$u = v = w = \sin(2\pi x) \sin(2\pi y) \sin(2\pi z)$$

Displacement field u

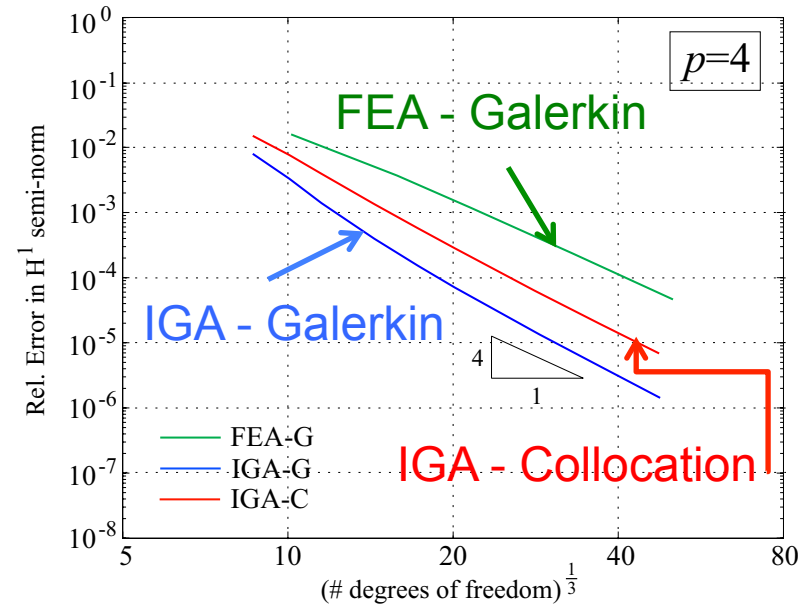
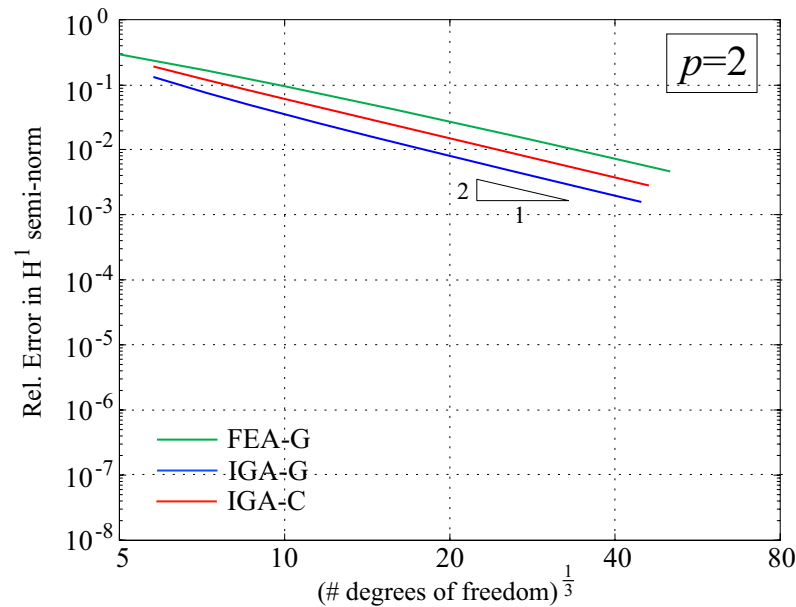


Derivative du/dz



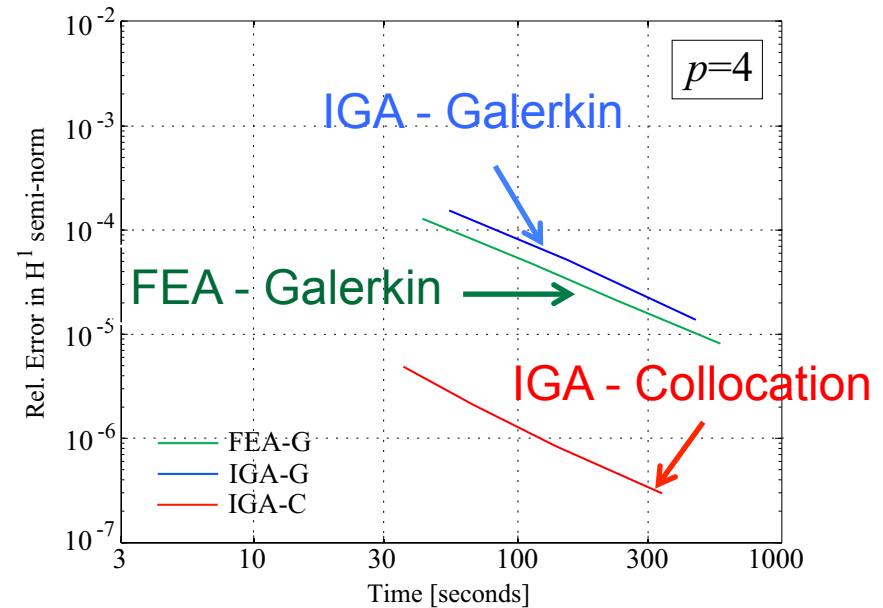
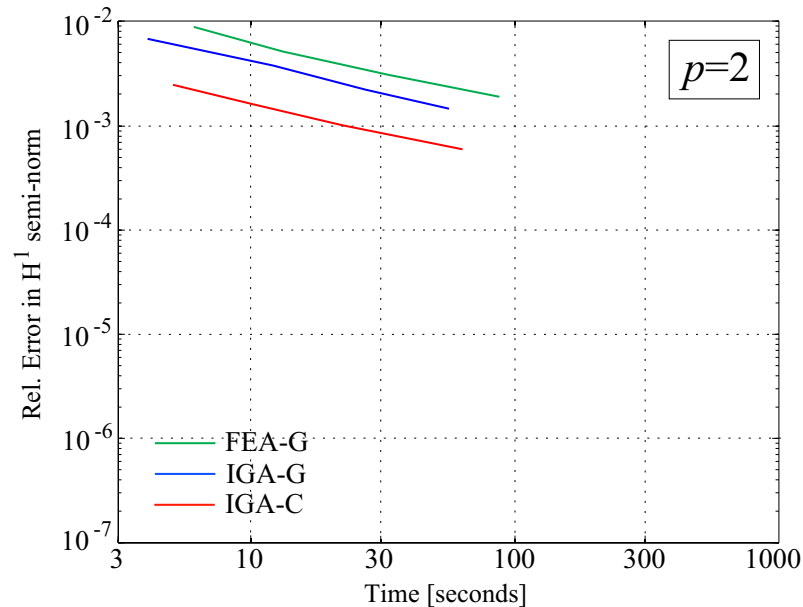
D. Schillinger, J. A. Evans, A. Reali, M. A. Scott, and T. J. R. Hughes, "Isogeometric collocation: Cost comparison with Galerkin methods and extension to adaptive hierarchical NURBS discretizations," *Computer Methods in Applied Mechanics and Engineering*, vol. 267, pp. 170–232, Dec. 2013. <http://www.sciencedirect.com/science/article/pii/S004578251300193X>

Error in H^1 semi-norm vs. number of DOF



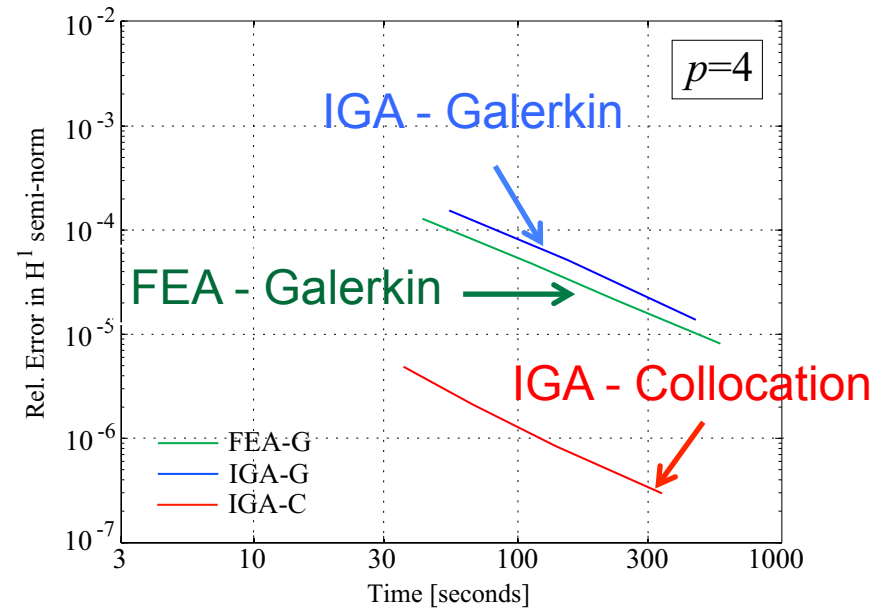
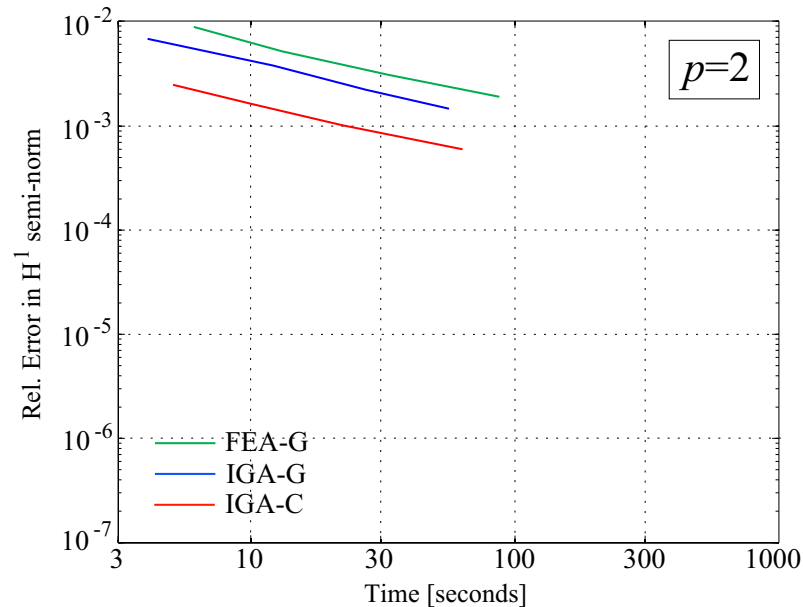
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Error in H^1 semi-norm vs. computing time



D. Schillinger, J. A. Evans, A. Reali, M. A. Scott, and T. J. R. Hughes, "Isogeometric collocation: Cost comparison with Galerkin methods and extension to adaptive hierarchical NURBS discretizations," *Computer Methods in Applied Mechanics and Engineering*, vol. 267, pp. 170–232, Dec. 2013. <http://www.sciencedirect.com/science/article/pii/S004578251300193X>

Error in H^1 semi-norm vs. computing time



Speed-up: 25 times

D. Schillinger, J. A. Evans, A. Reali, M. A. Scott, and T. J. R. Hughes, "Isogeometric collocation: Cost comparison with Galerkin methods and extension to adaptive hierarchical NURBS discretizations," *Computer Methods in Applied Mechanics and Engineering*, vol. 267, pp. 170–232, Dec. 2013. <http://www.sciencedirect.com/science/article/pii/S004578251300193X>

Breakthrough in IGA Collocation

- “The Variational Collocation Method,” H. Gomez, L. De Lorenzis, *CMAME*, accepted, 2016.

Breakthrough in IGA Collocation

- “The Variational Collocation Method,” H. Gomez, L. De Lorenzis, *CMAME*, accepted, 2016.
- There exist collocation points, so-called *Cauchy-Galerkin points*, that produce the Galerkin solution exactly, for all p , odd as well as even.

Breakthrough in IGA Quadrature

- “Fast Formation of Isogeometric Galerkin Matrices by Weighted Quadrature,” F. Calabrò, G. Sangalli, and M. Tani, *CMAME*, accepted, 2016.
- <http://arxiv.org/abs/1605.01238v1>

Breakthrough in IGA Quadrature

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- <http://arxiv.org/abs/1605.01238v1>
- Much greater efficiency for Galerkin matrices than classical element-by-element implementation.

Breakthrough in IGA Quadrature

- Example:
 - Formation and assembly of a Galerkin mass matrix.

Breakthrough in IGA Quadrature

- Example:
 - Formation and assembly of a Galerkin mass matrix.
 - 20^3 Bézier element mesh.

Breakthrough in IGA Quadrature

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 - Time = 62 hours.

Breakthrough in IGA Quadrature

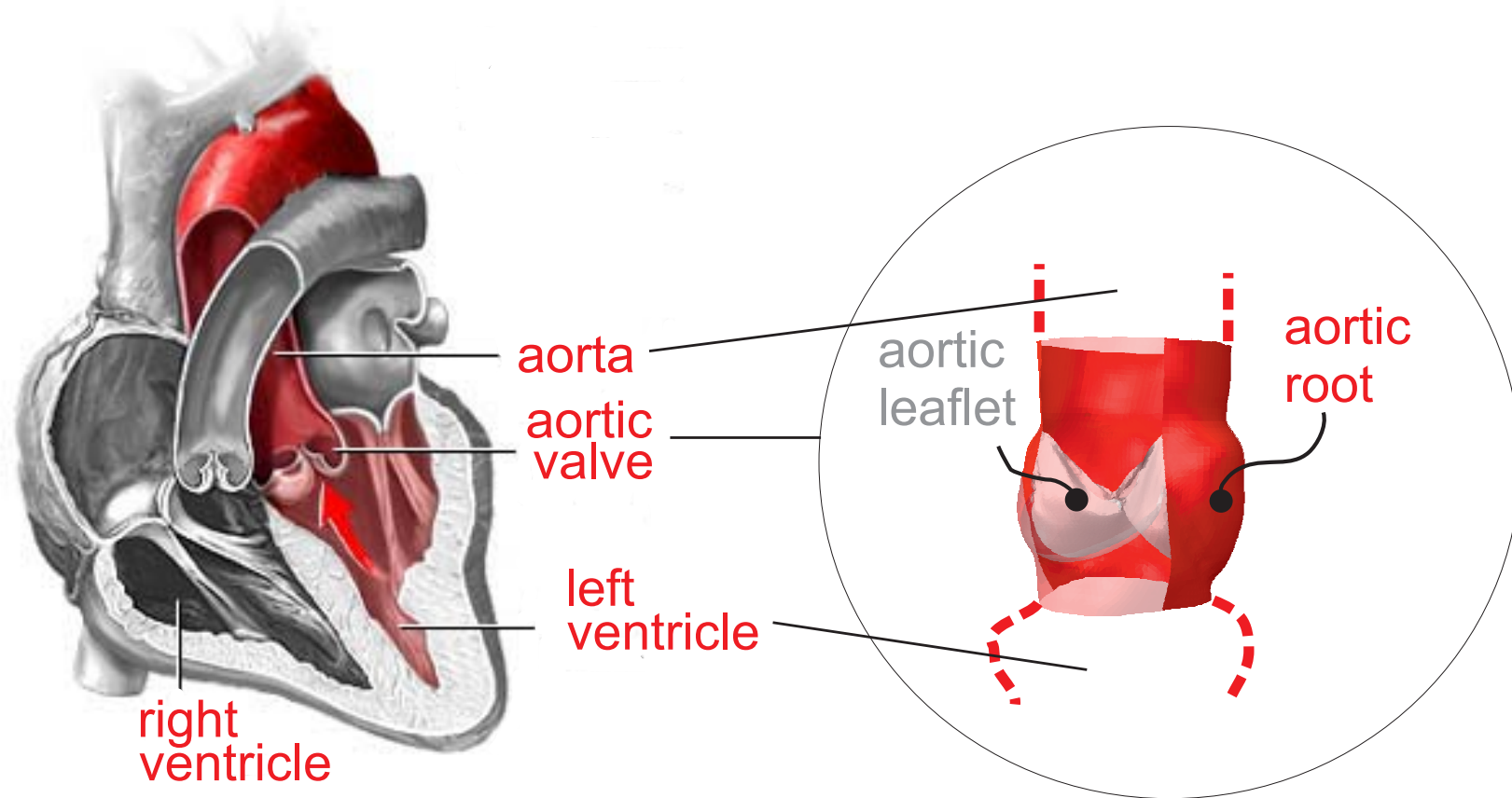
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 - New procedure = **27 seconds!**

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 - **Speedup factor > 8,000!**

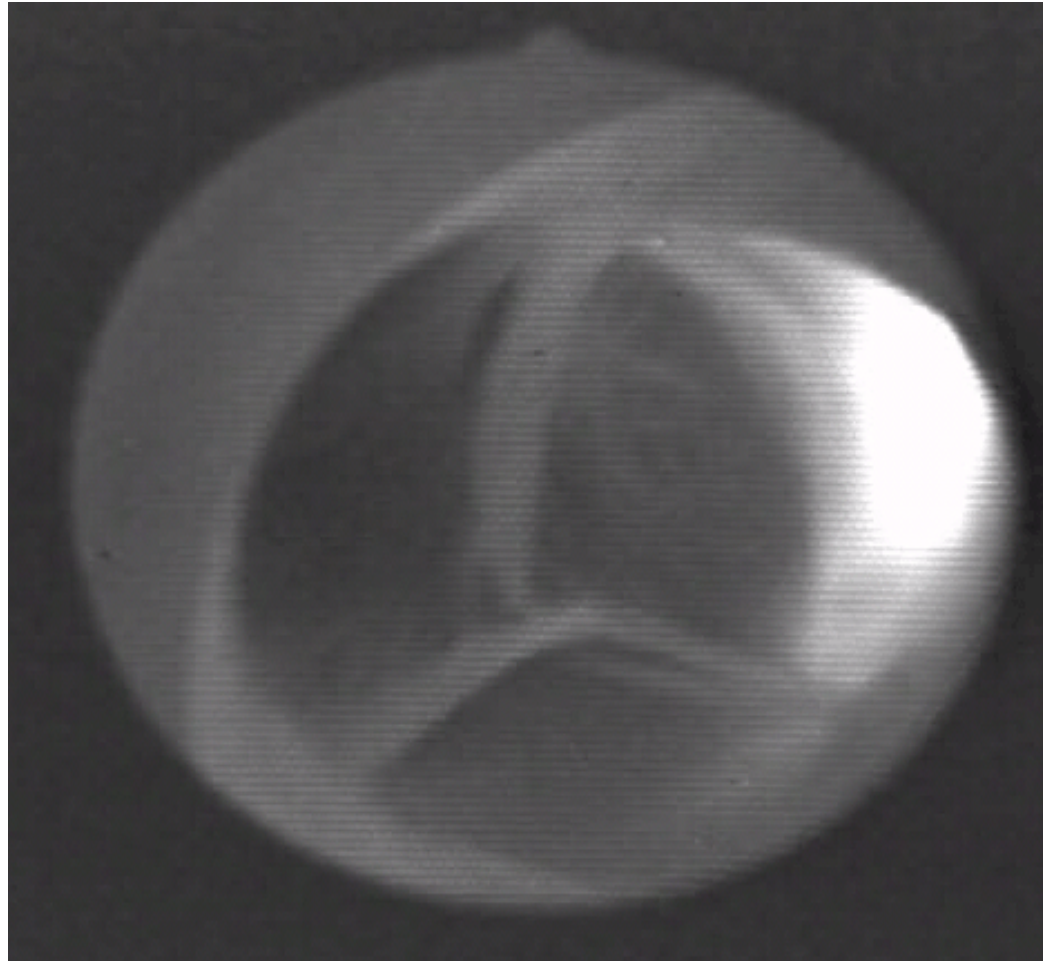
Applications

Aortic Valve

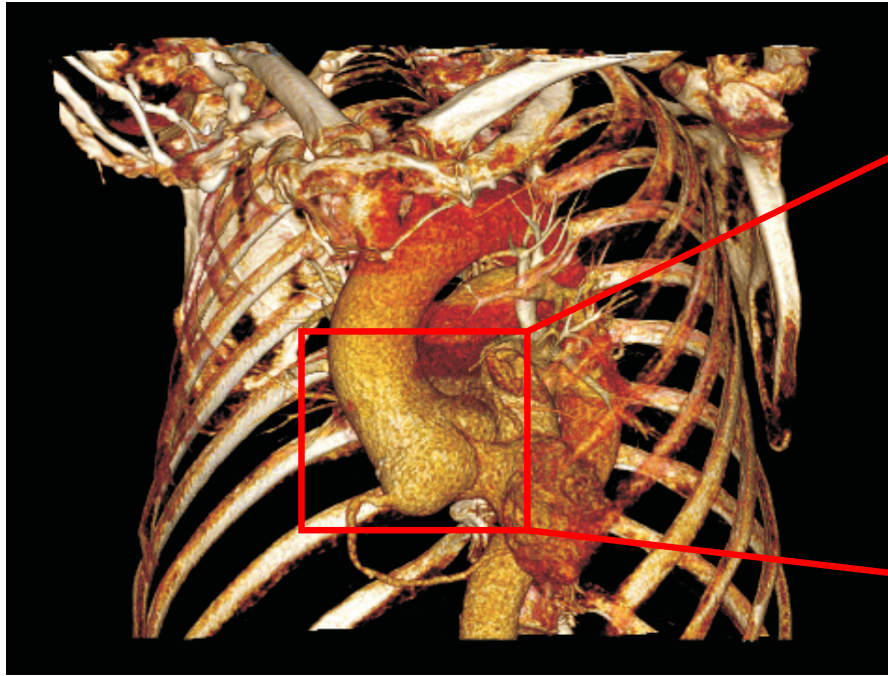


“Patient-specific isogeometric structural analysis of aortic valve closure,” S. Morganti, F. Auricchio, D. Benson, F.I. Gambarin, S. Hartmann, T.J.R.H., A. Reali, *CMAME*, 2015.

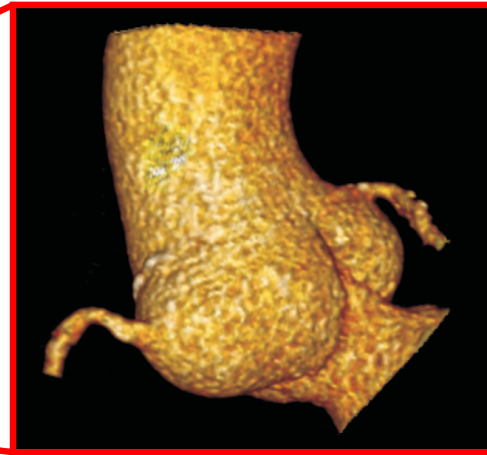
Aortic Valve



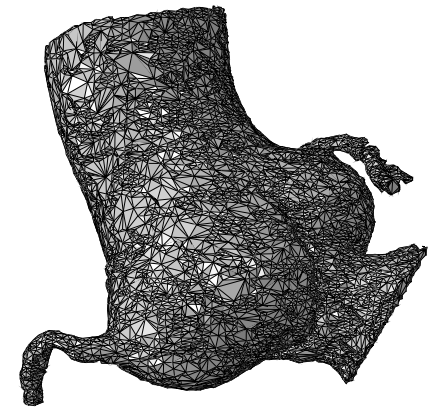
CTA to STL file



(a)



(b)



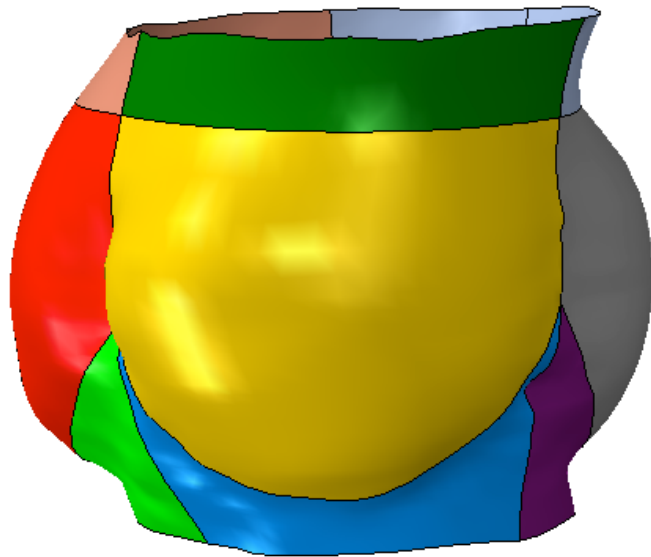
(c)

(a) Primary 3D reconstruction obtained using OsiriX

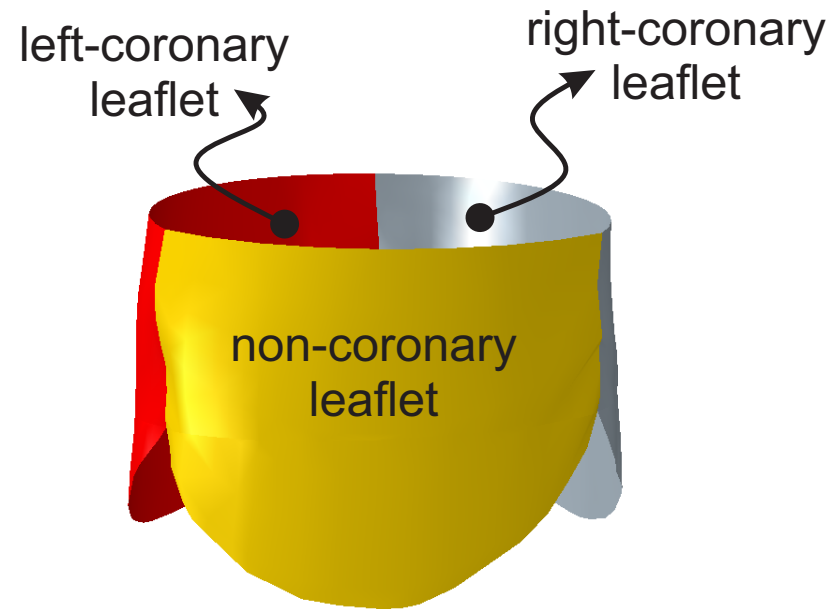
(b) 3D specific reconstruction of the aortic root after cropping and segmentation

(c) STL representation of the extracted region of interest.

Multi-patch aortic valve geometry

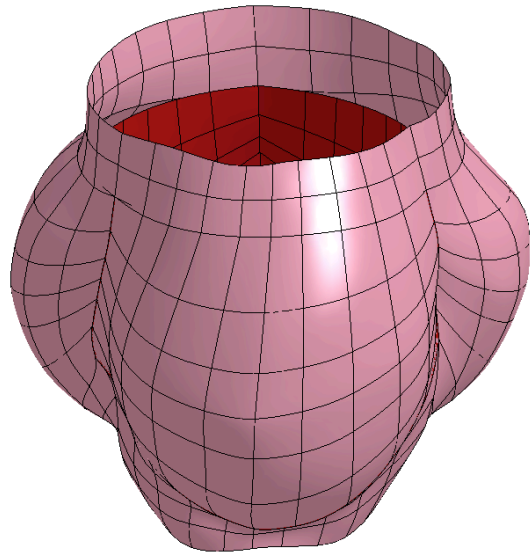


Aortic root subdivided into nine NURBS patches

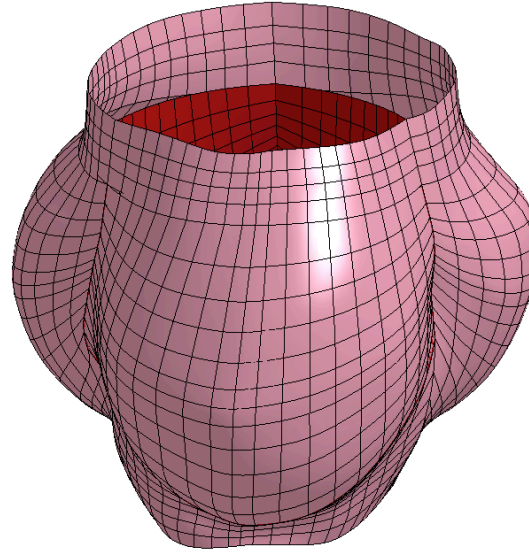


Each leaflet represented by a single NURBS patch

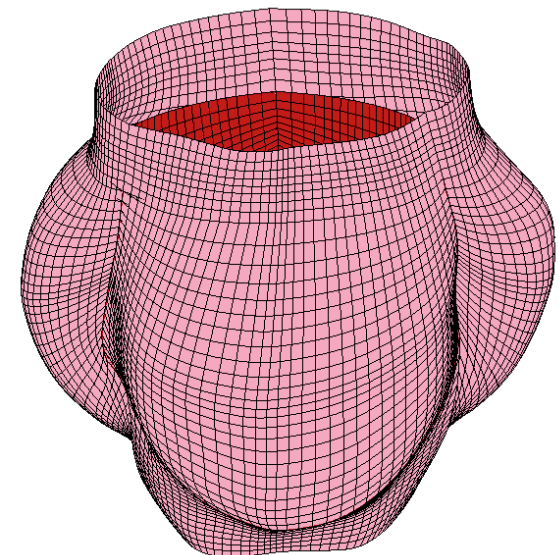
NURBS meshes for patient-specific aortic root and leaflets



Coarse mesh
(762 control points)



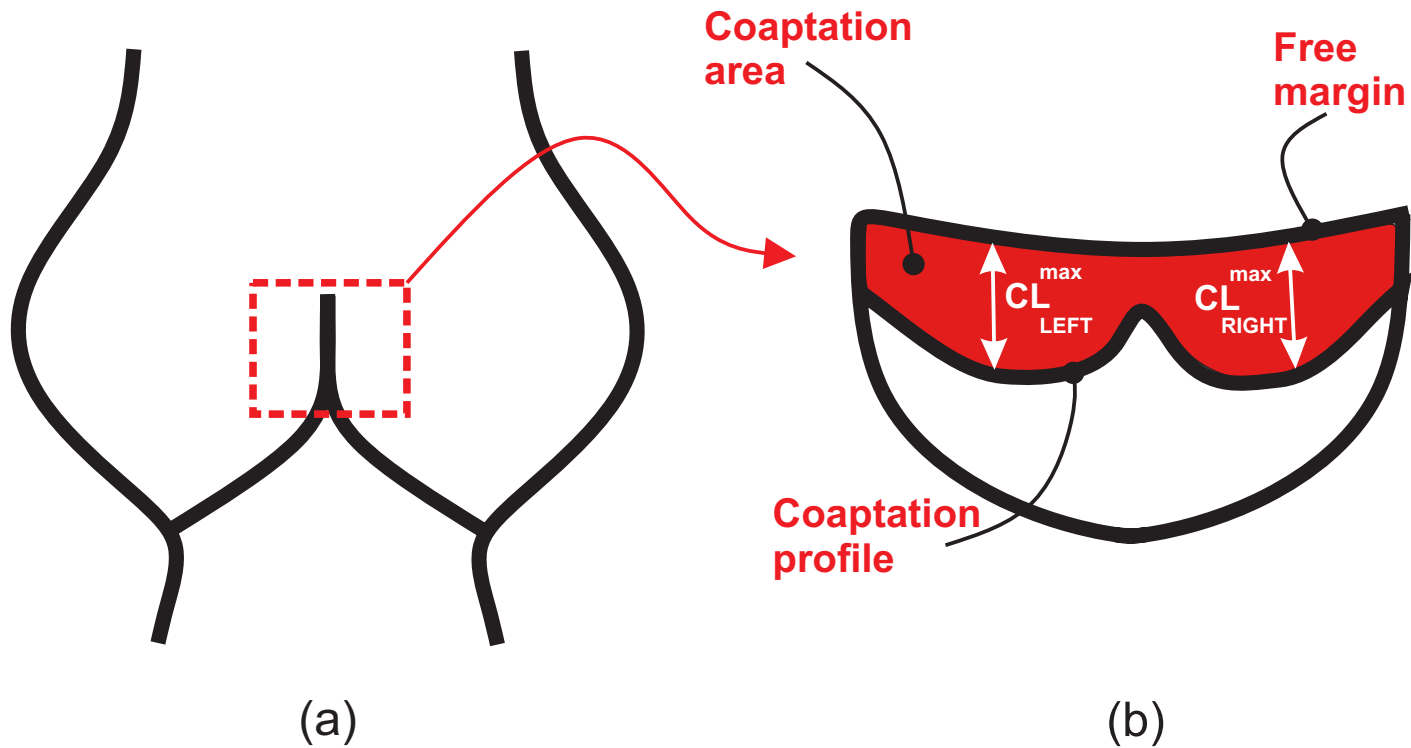
Medium mesh
(2890 control points)



Fine mesh
(9396 control points).

1. Reissner-Mindlin shell theory for the aortic root.
2. Kirchhoff-Love rotation-free shell theory for the aortic valve leaflets.

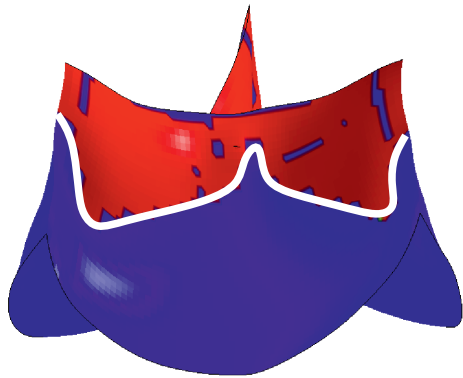
Coaptation Profile



(a) Longitudinal section of the aortic valve during diastole

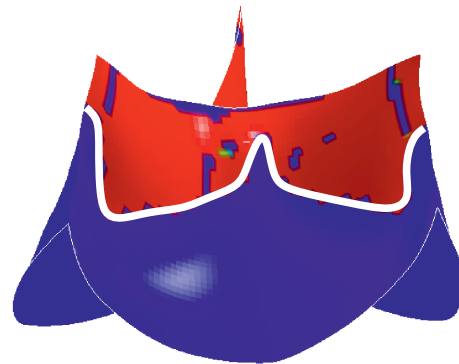
(b) Coaptation area, the leaflet free margin, and coaptation profile for one leaflet

IGA: Coaptation Profile with LS-DYNA



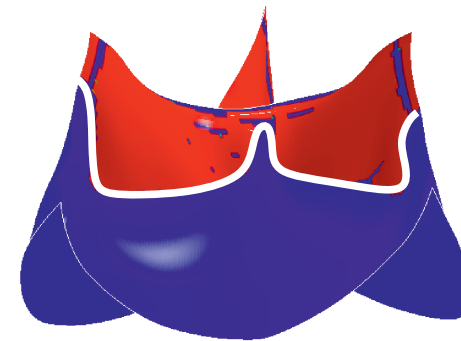
(a)

(a) 762 nodes



(b)

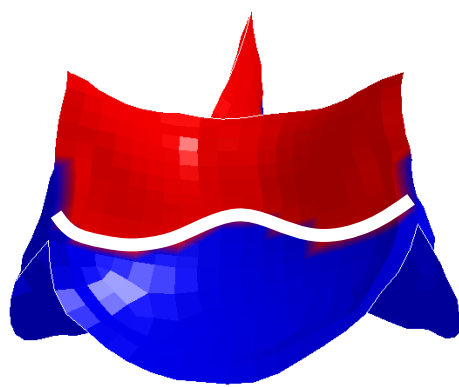
(b) 2890 nodes



(c)

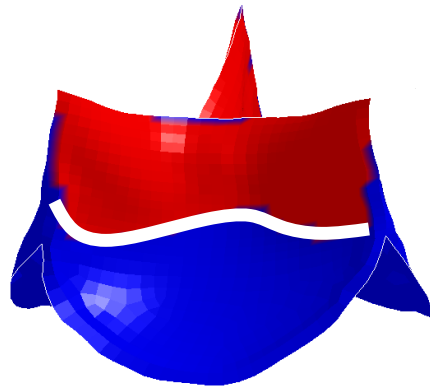
(c) 9396 nodes

FEA*: Coaptation Profile with LS-DYNA



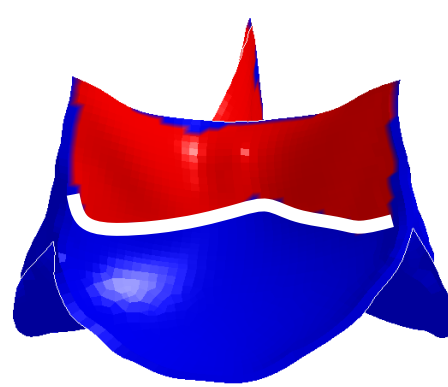
(a)

(a) 6446 nodes



(b)

(b) 14329 nodes

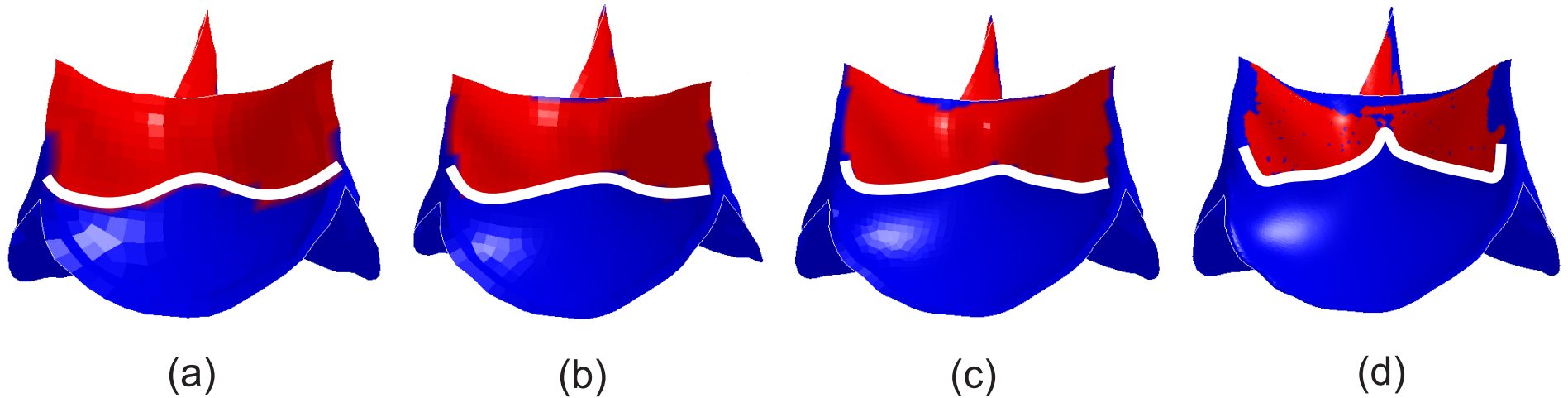


(c)

(c) 37972 nodes

*Belytschko-Tsay four-node Reissner-Mindlin shell finite elements

FEA*: Coaptation Profile with LS-DYNA



(a) 6446 nodes

(b) 14329 nodes

(c) 37972 nodes

(d) 153646 nodes

*Belytschko-Tsay four-node Reissner-Mindlin shell finite elements

Coaptation length for IGA and FEA

Analysis	# nodes	# DOF	Coaptation Length	
			CL _{max} ^(left) [mm]	CL _{max} ^(right) [mm]
IGA	762	3708	9.30	9.40
	2890	19476	9.25	9.40
	9396	50496	9.30	9.35
FEA	1112	6672	11.1	12.8
	3117	18702	10.8	10.2
	6446	38676	10.4	9.80
	14329	85974	9.70	9.70
	37972	227832	9.45	9.50
	153646	921876	9.30	9.35

Solution times for comparable accuracy

Analysis	# Nodes	# CPUs	Time step	# Increments	Total analysis time
IGA	762	12	2.30e-07	4347390	1h 15m
FEA	153646	12	2.65e-08	37787314	550h 23m

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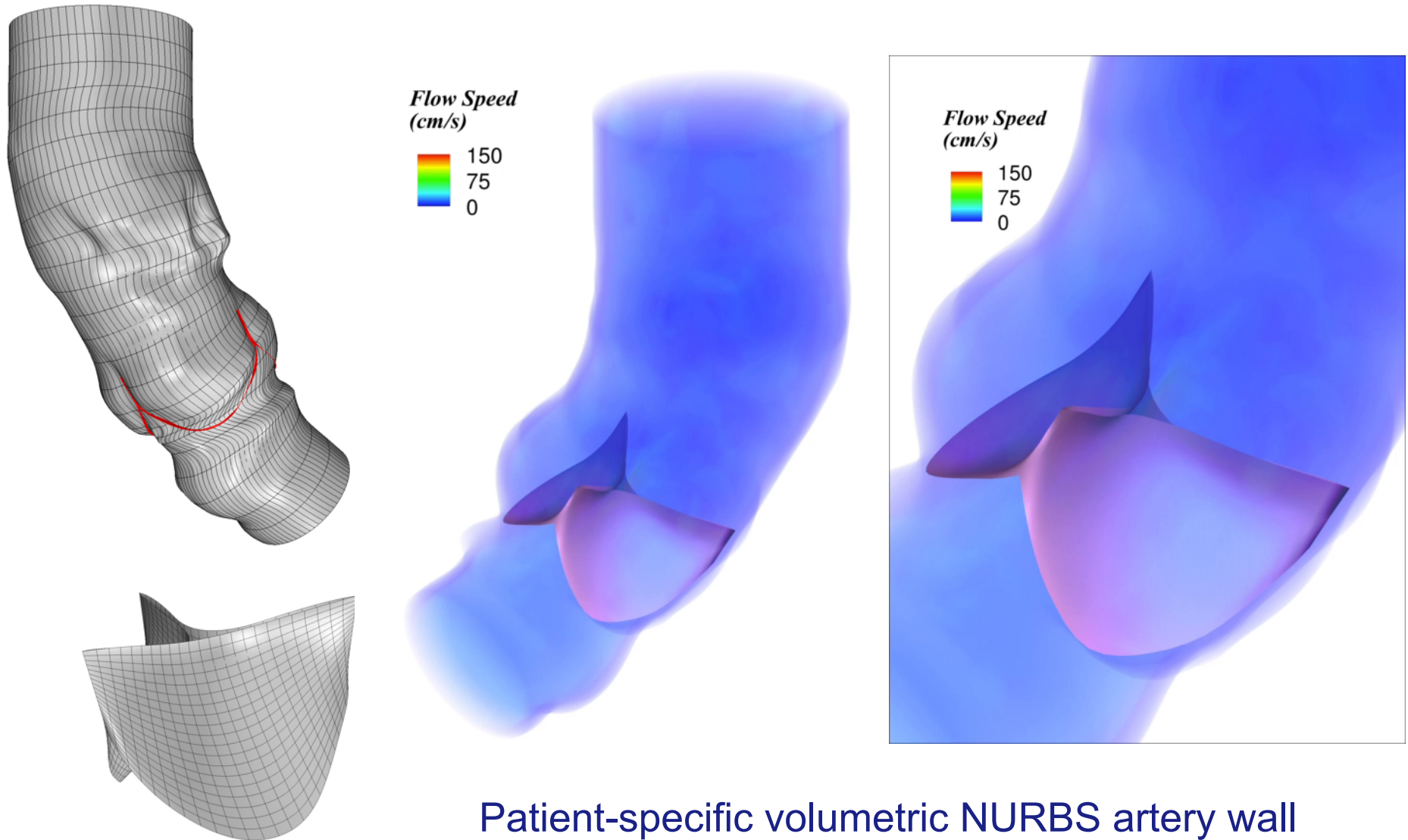
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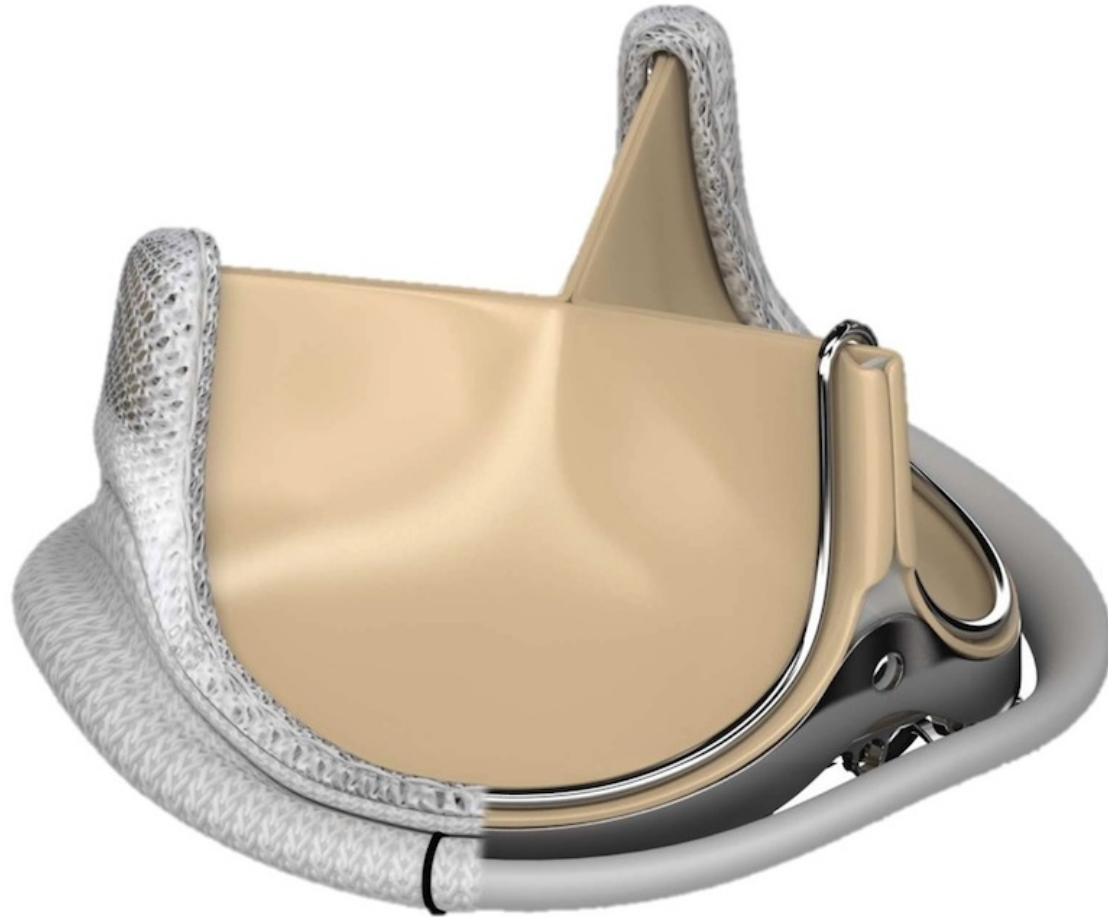
Why is IGA so much faster than traditional FEA?

1. Much more accurate per degree of freedom.
2. Efficient dynamics, e.g., large time steps.
3. Quality of contact surface provided by smooth geometry and smooth basis functions.

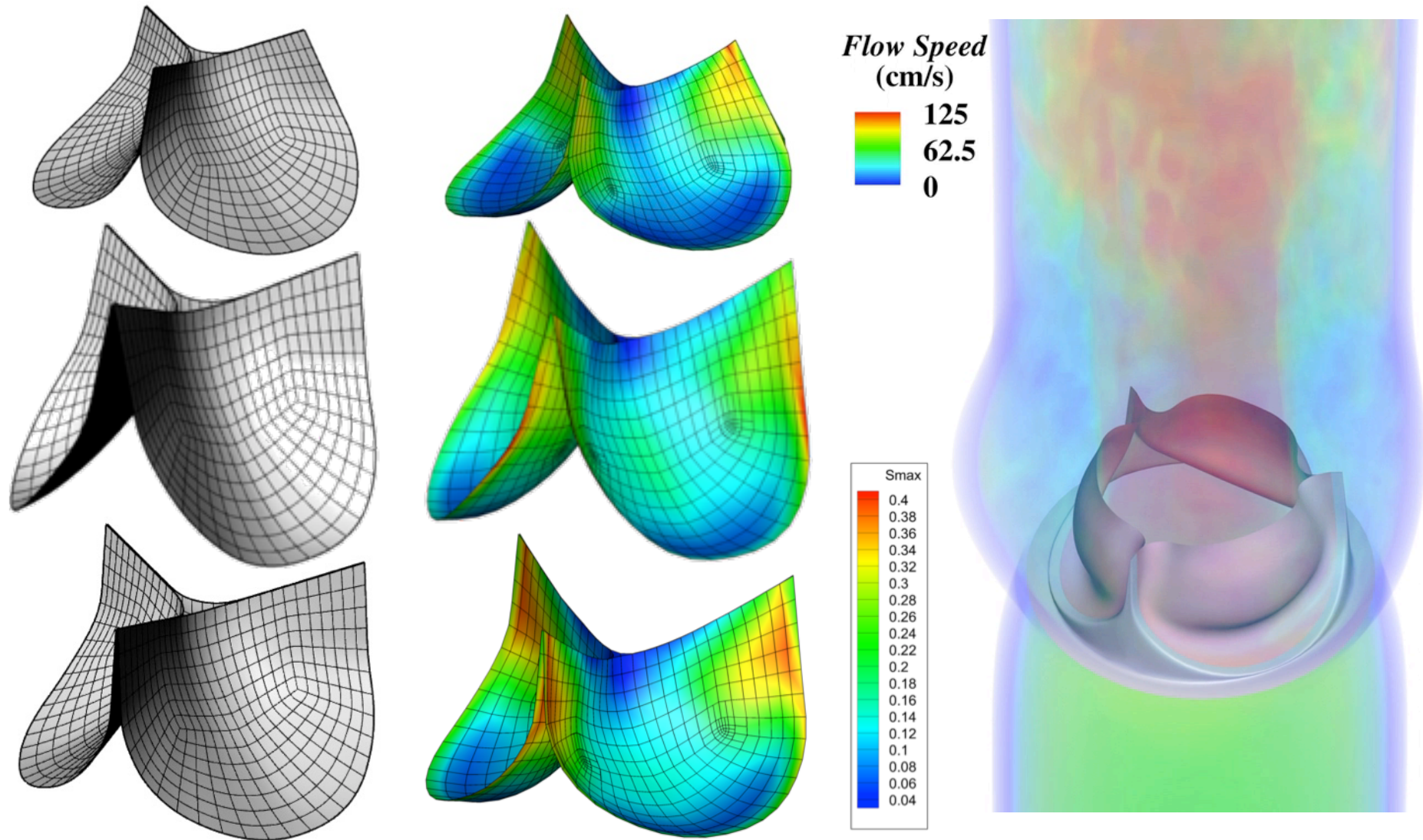
ALE / Immersed Kirchhoff-Love Shell



Bioprosthetic Heart Valve



ALE / Immersed Kirchhoff-Love Shell



Static closing analysis of different designs

M.-C. Hsu, A. Herrema, et al., 2015

Volumetric NURBS artery wall

+ M. Sacks, D. Kamensky, et al., 2015

Boiling

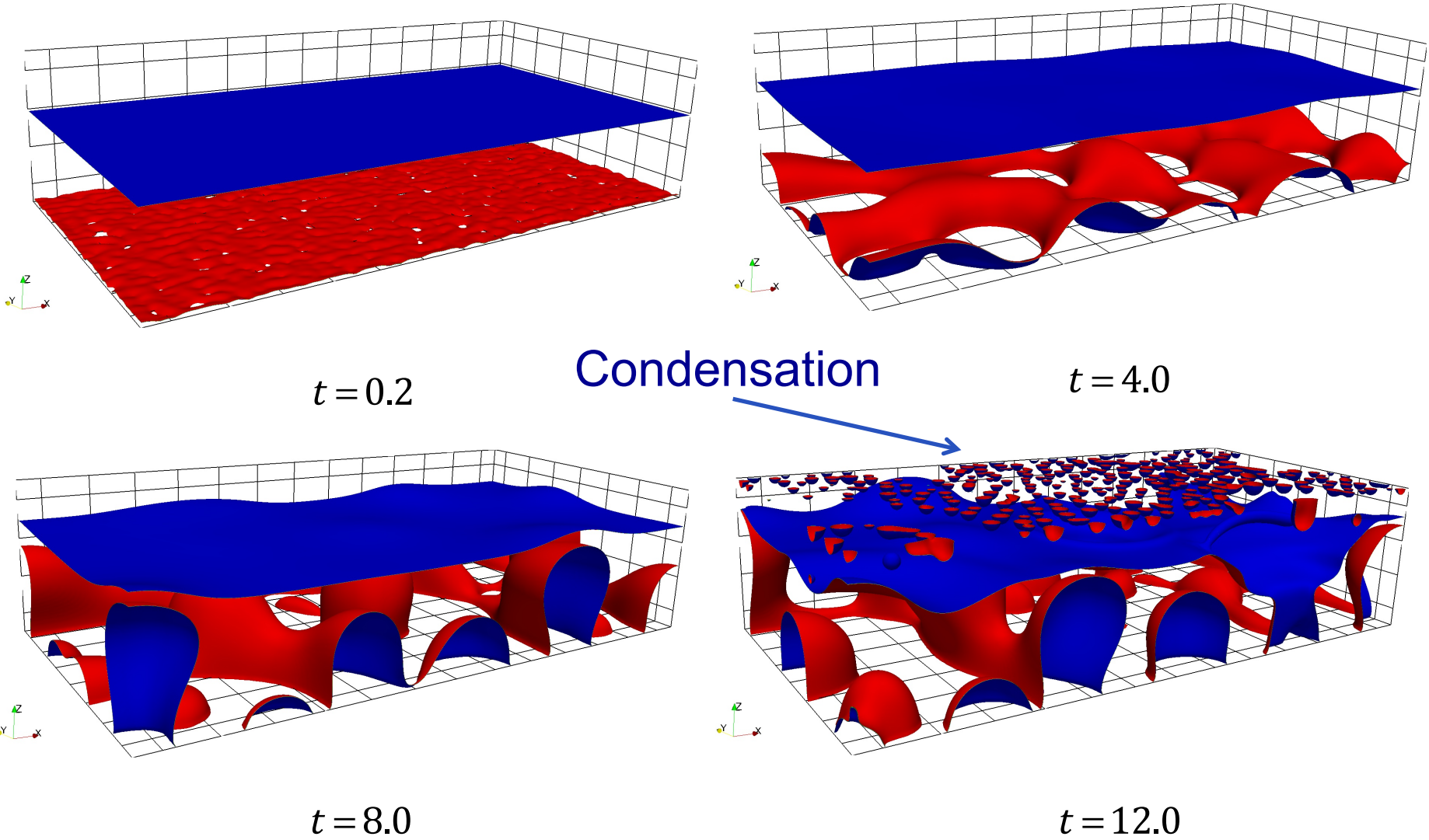
- NOVA, a science TV show:
 - Does mathematics explain the physical world?
- One man's opinion:
 - “No! One of the things it cannot simulate is boiling”



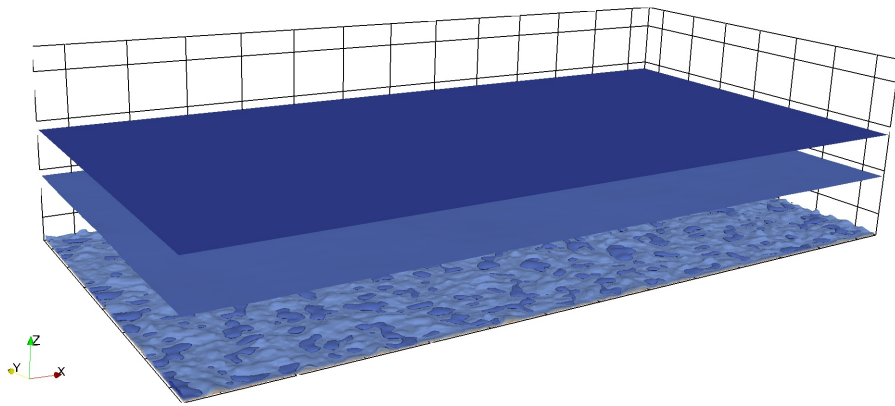
Ju Liu does not agree

- Navier-Stokes-Korteweg equations – 3rd derivatives

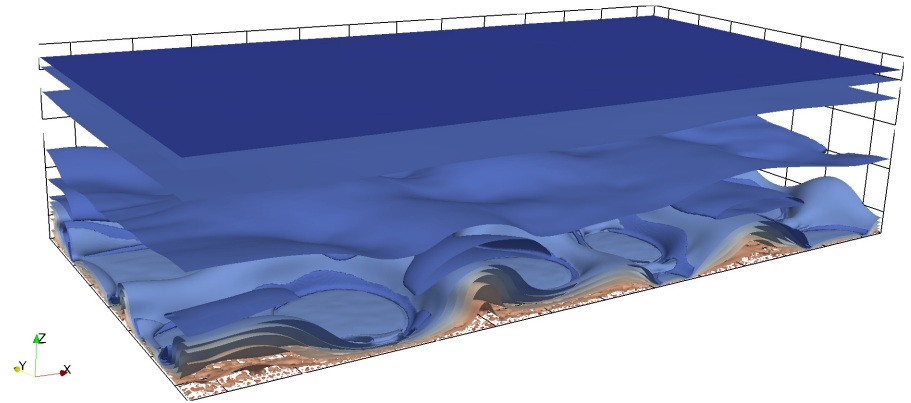
Three-dimensional Boiling (J. Liu et al.)



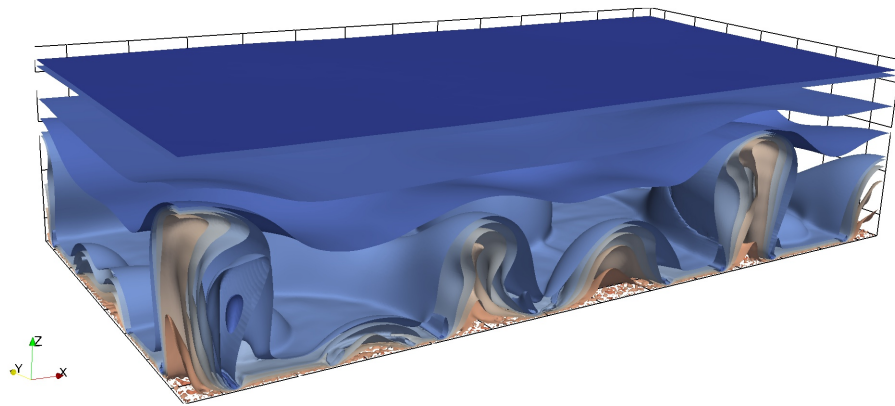
Three-dimensional Boiling (J. Liu et al.)



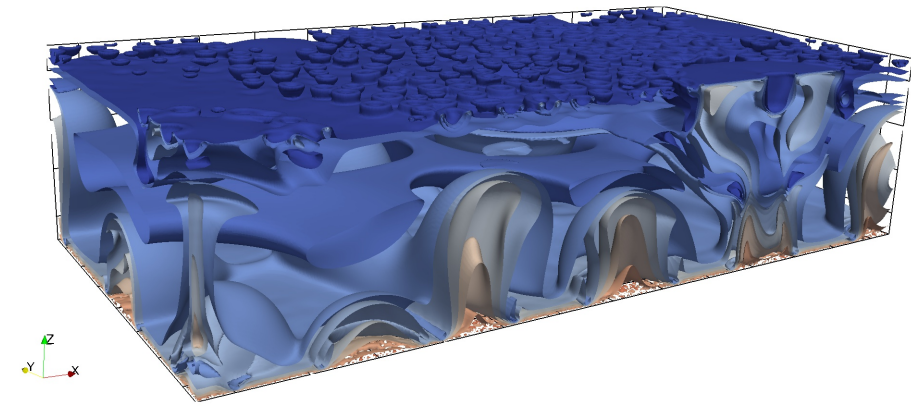
$t = 0.2$



$t = 4.0$

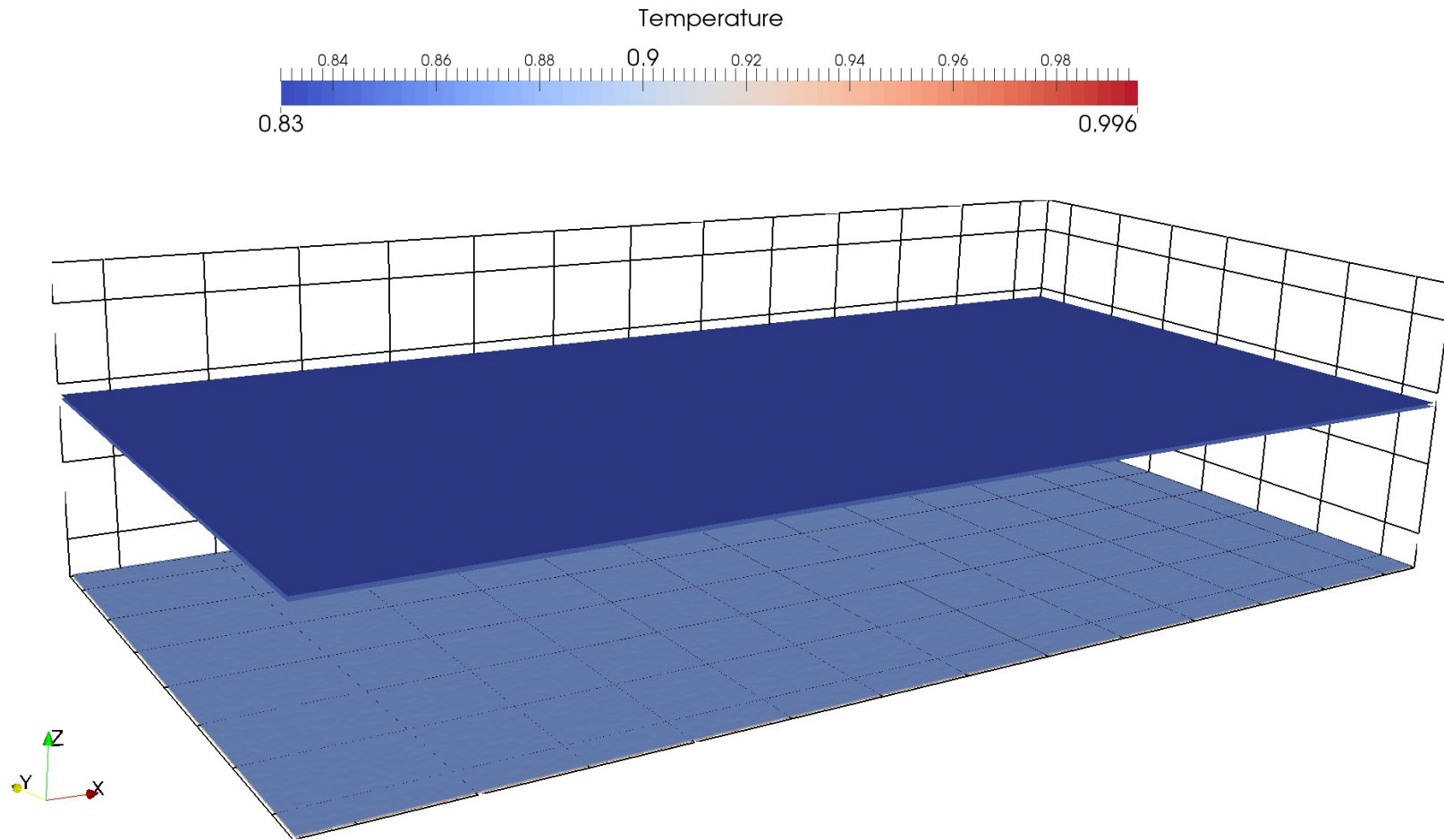


$t = 8.0$



$t = 12.0$

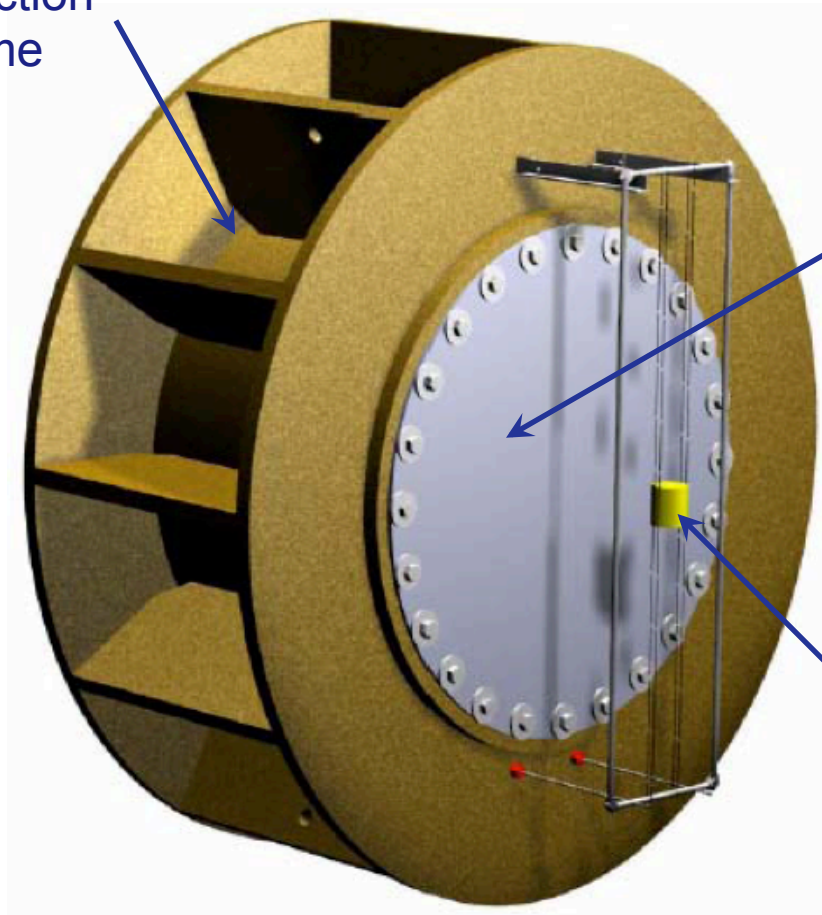
Three-dimensional Boiling (J.Liu et al.)



Ductile Fracture

Circular Plate Subject to Impulse Load

Reaction
Frame



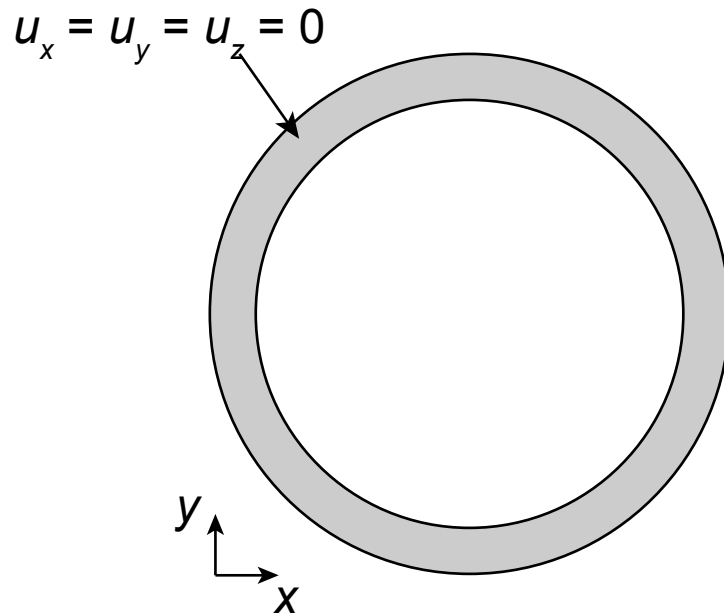
Test
Plate

Charge

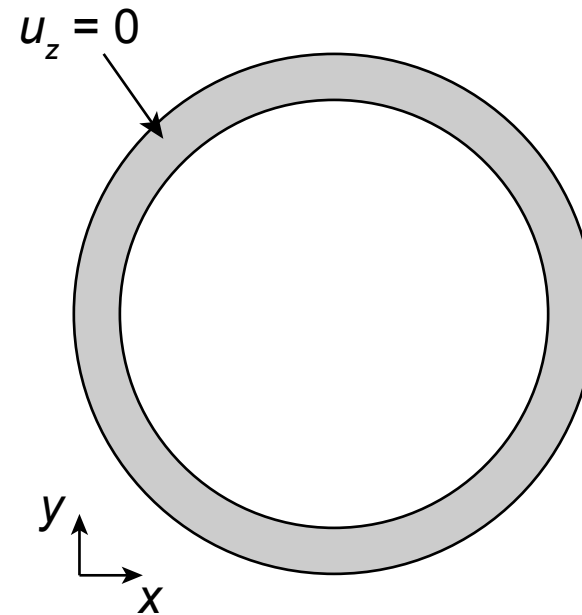


Figures from K.G. Webster, *Investigation of Close Proximity Underwater Explosion Effects on a Ship-Like Structure Using the Multi-Material Arbitrary Lagrangian Eulerian Finite Element Method*, Master's Thesis, Virginia Polytechnic Institute and State University, 2007.

Displacement Boundary Conditions



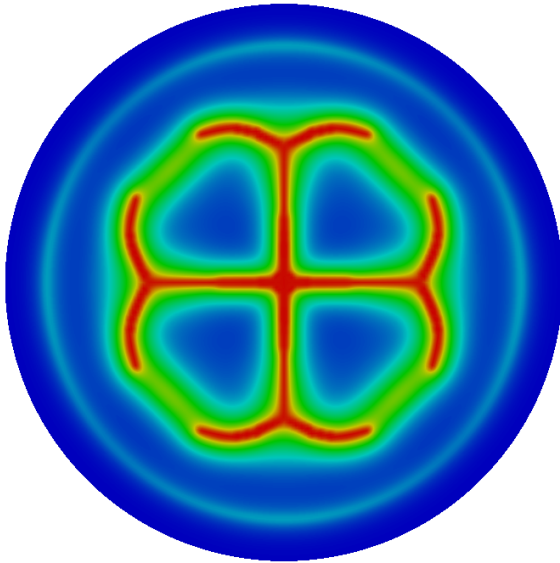
Clamped BC: No displacement in any direction on outer ring



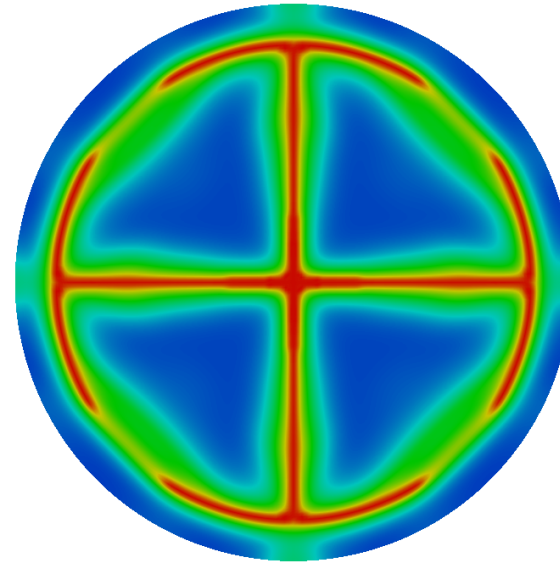
Sliding BC: No displacement on outer ring in z -direction

Comparison of BCs

Clamped

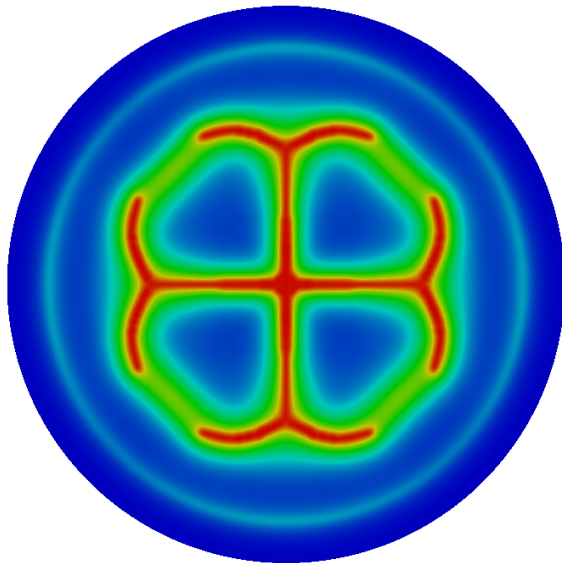


Sliding

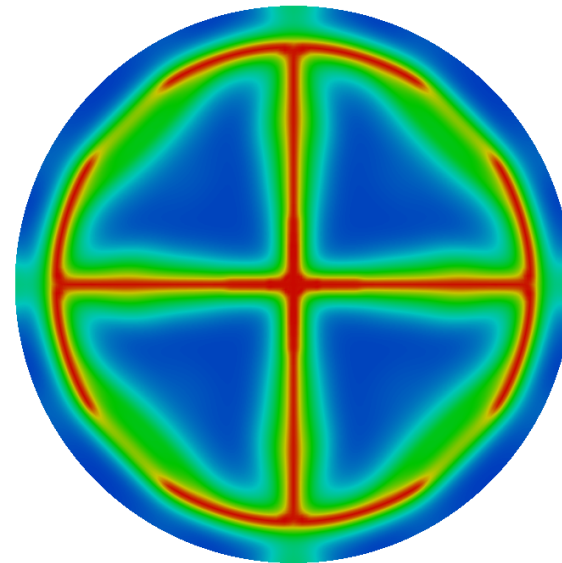


Comparison of BCs

Clamped

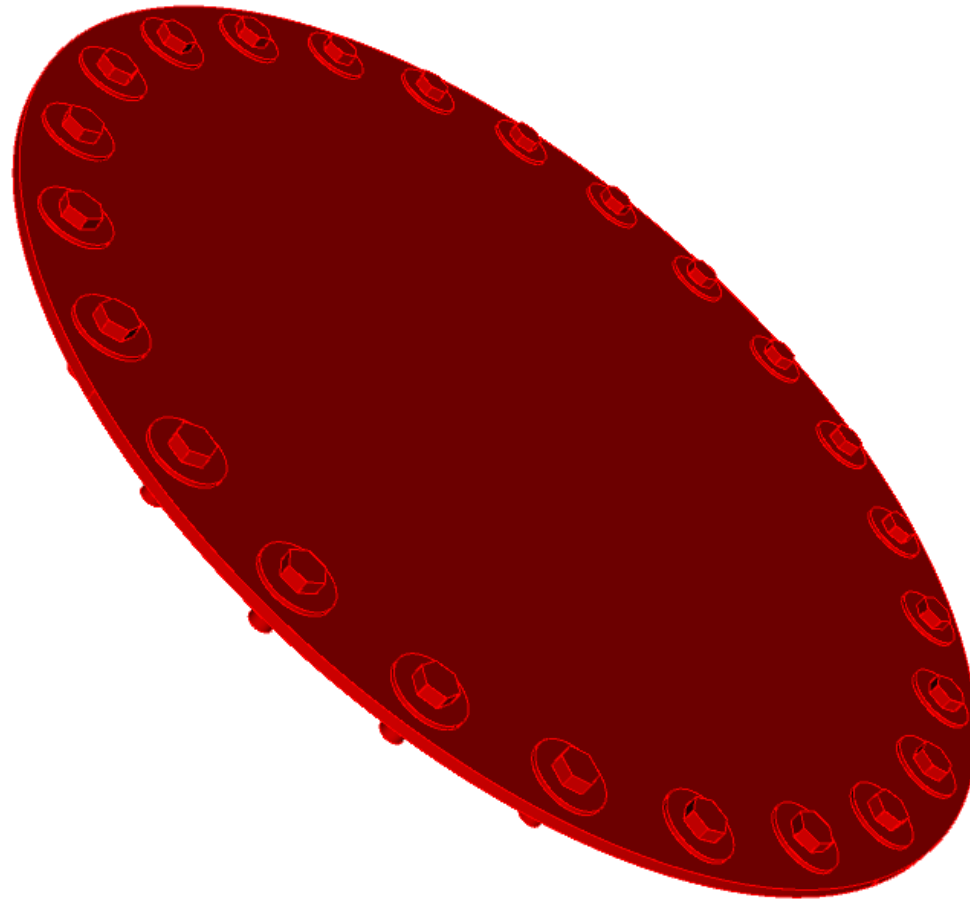


Sliding



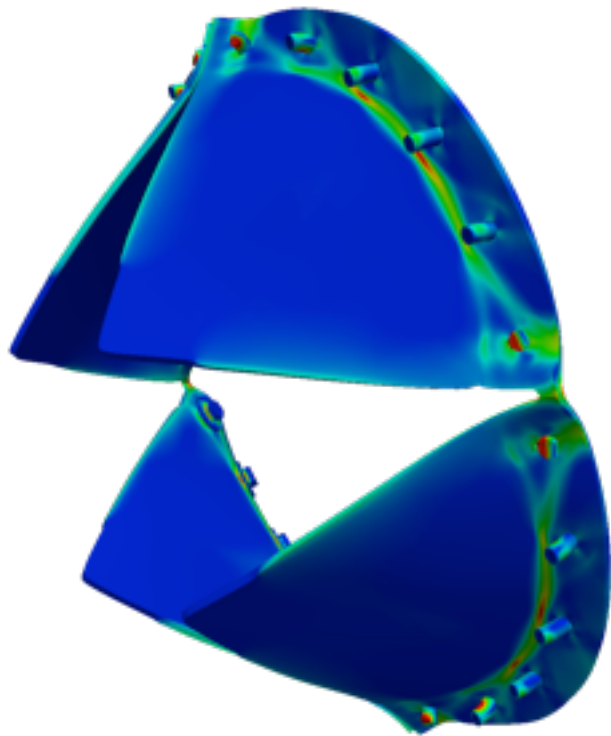
“Everything should be made as simple as possible, but not simpler.” A. Einstein (?)

NURBS Circular Plate Model*



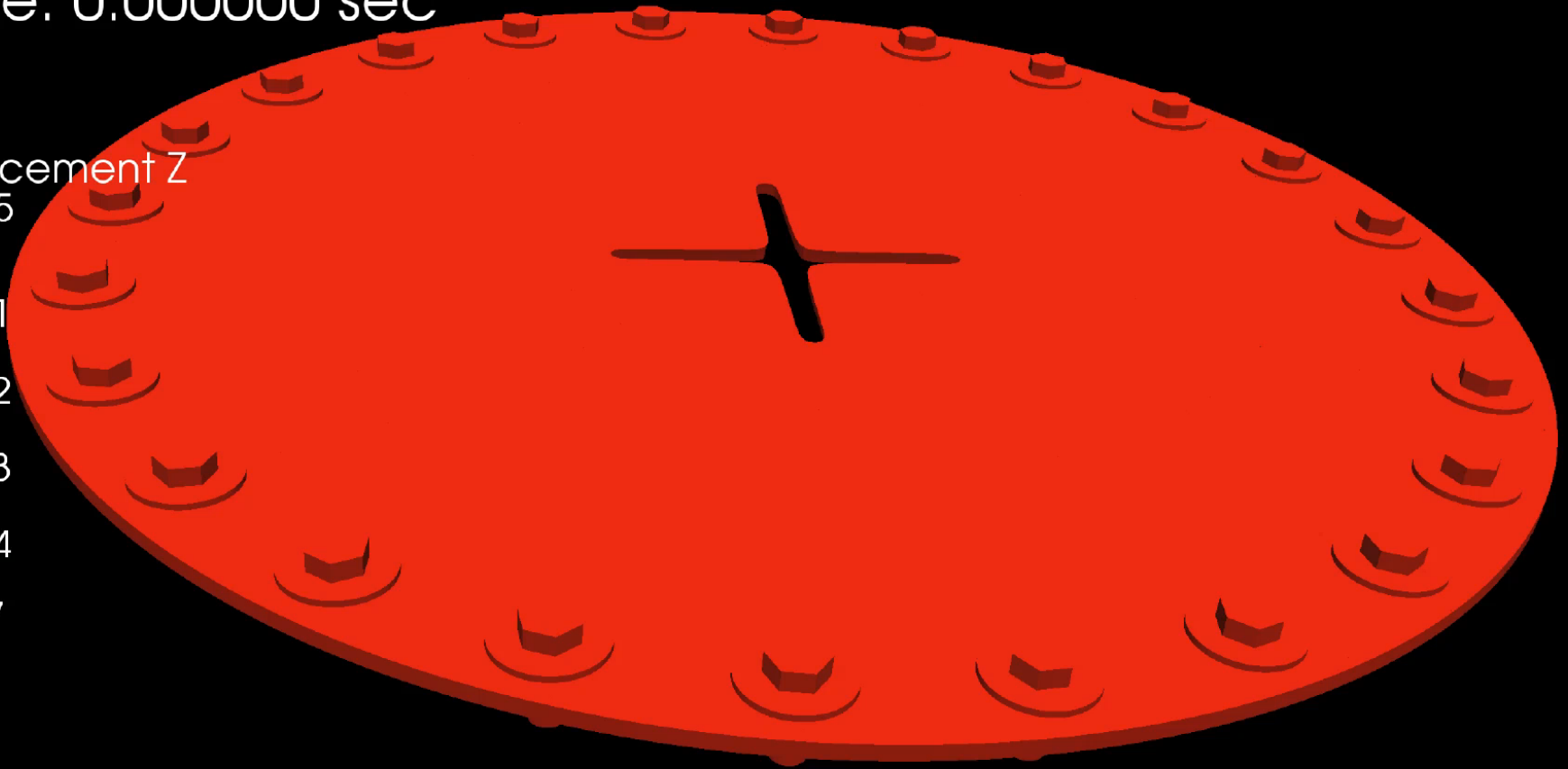
Includes bolts and washers

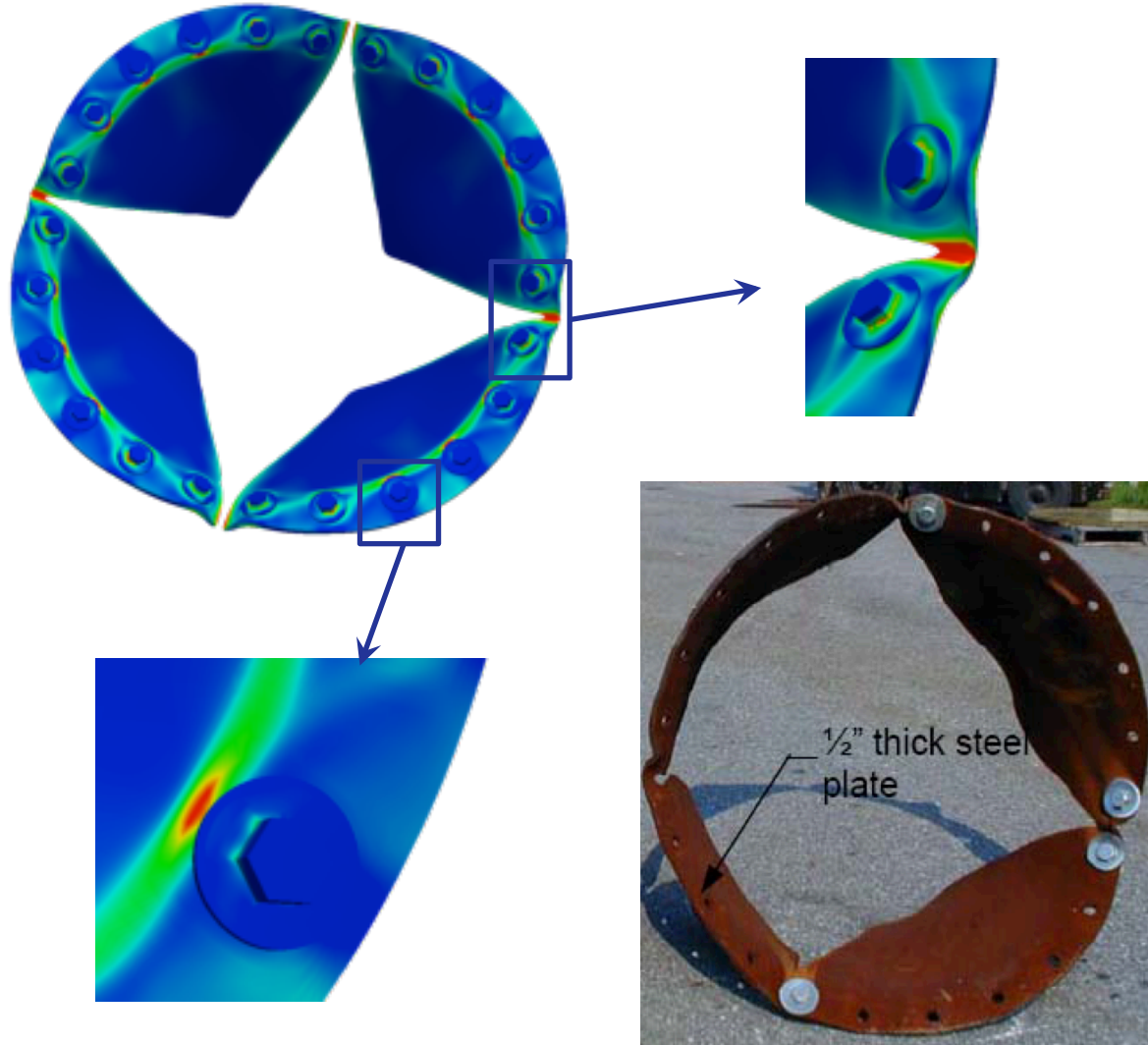
* M.J. Borden, T.J.R. Hughes, C. Landis, A. Anvari, I. Lee, 2016



Time: 0.000000 sec

Displacement Z





Isogeometric Analysis: Summary

- One of the most active areas of FEA and CAGD research
- Overarching goal: Improve engineering product design
- Focus so far: The design-through-analysis process
- “Better, faster, cheaper”
 - Improve quality of analysis
 - Expedite analysis model development
 - Faster analysis
 - Decrease cost

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- Overarching goal: Improve engineering product design
- Focus so far: The design-through-analysis process
- “Better, faster, cheaper”
 - Improve quality of analysis
 - Expedite analysis model development
 - Faster analysis
 - Decrease cost
- A fruitful, promising and growing area of research
- Gaining traction in industry

New ideas

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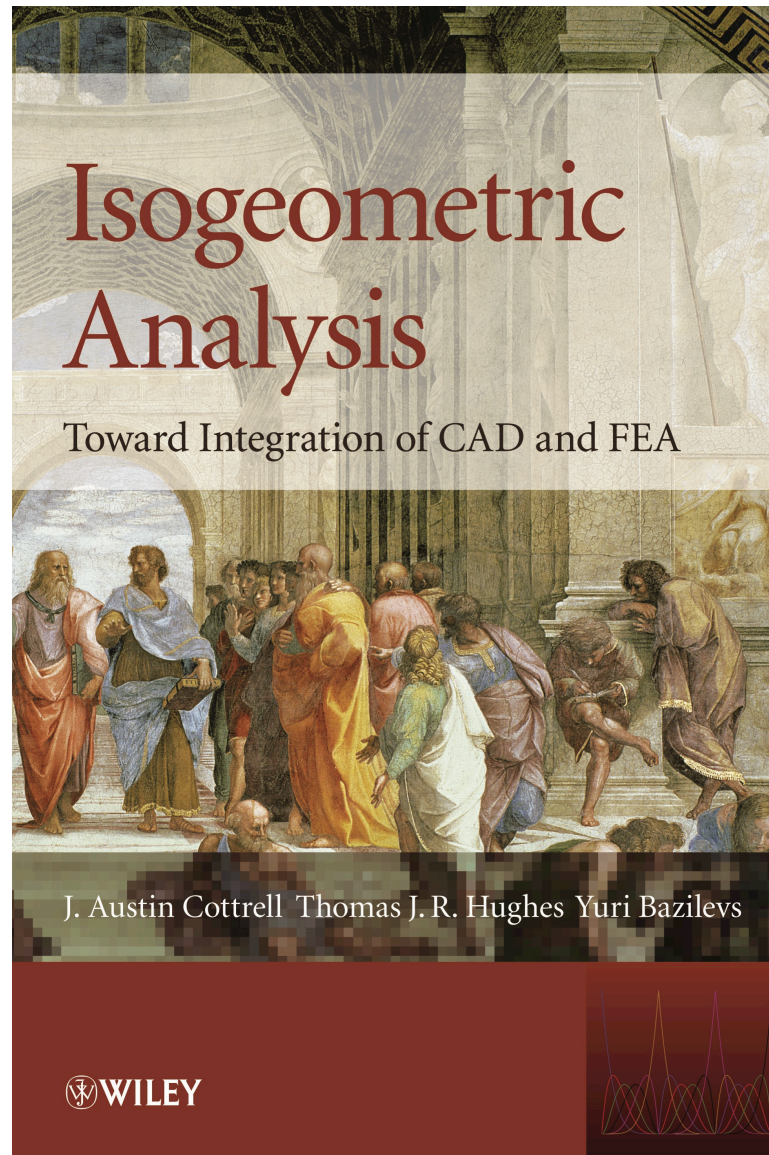
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- 1) It can't be done.
- 2) It probably can be done, but it's not worth doing.
- 3) I knew it was a good idea all along!



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