

A Fresh Look at the Bayes' Theorem from Information Theory

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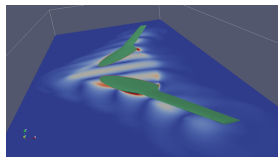
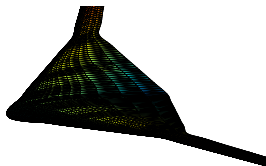
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Outline

- 1 Bayesian Inversion Framework
- 2 Entropy
- 3 Relative Entropy
- 4 Bayes' Theorem and Information Theory
- 5 Conclusions

Large-scale computation under uncertainty

Inverse electromagnetic scattering



Randomness

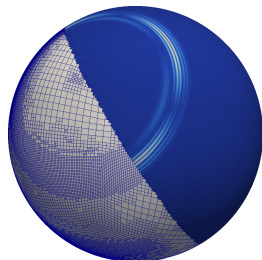
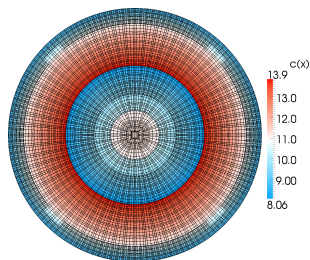
- Random errors in measurements are unavoidable
- Inadequacy of the mathematical model (Maxwell equations)

Challenge

How to invert for the invisible shape/medium using computational electromagnetics with $\mathcal{O}(10^6)$ degree of freedoms?

Large-scale computation under uncertainty

Full wave form seismic inversion



Randomness

- Random errors in seismometer measurements are unavoidable
- Inadequacy of the mathematical model (elastodynamics)

Challenge

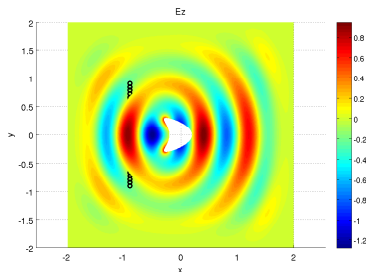
How to **image** the earth interior using forward computational model with with $\mathcal{O}(10^9)$ degree of freedoms?

Inverse Shape Electromagnetic Scattering Problem

Maxwell Equations:

$$\nabla \times \mathbf{E} = -\mu \frac{\partial \mathbf{H}}{\partial t}, \quad (\text{Faraday})$$

$$\nabla \times \mathbf{H} = \epsilon \frac{\partial \mathbf{E}}{\partial t}, \quad (\text{Ampere})$$



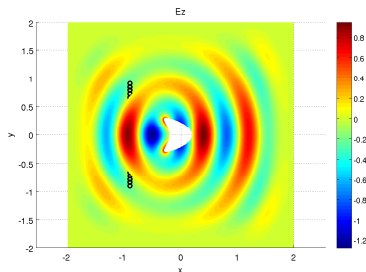
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Forward problem (discontinuous Galerkin discretization)

$$d = \mathcal{G}(x)$$

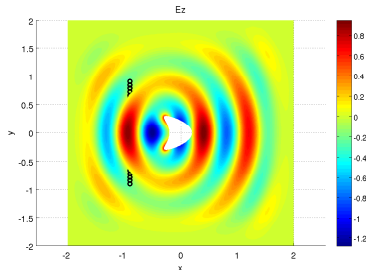
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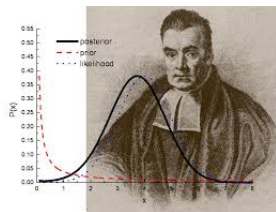
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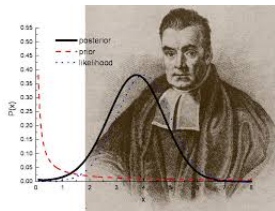
Inverse Problem

Given (possibly noise-corrupted) measurements on d , infer x ?

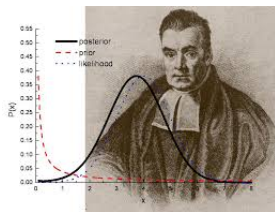
The Bayesian Statistical Inversion Framework



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The Bayesian Statistical Inversion Framework



Bayes Theorem

$$\pi_{\text{post}}(x|d) \propto \pi_{\text{like}}(d|x) \times \pi_{\text{prior}}(x)$$

Bayes theorem for inverse electromagnetic scattering

Prior knowledge: The obstacle is smooth:

$$\pi_{\text{pr}}(x) \propto \exp\left(-\lambda \int_0^{2\pi} r''(x) d\theta\right)$$

Bayes theorem for inverse electromagnetic scattering

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Likelihood: Additive Gaussian noise, for example,

$$\pi_{\text{like}}(d|x) \propto \exp\left(-\frac{1}{2} \|\mathcal{G}(x) - d\|_{C_{\text{noise}}}^2\right)$$

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Entropy

Definition

We define the **uncertainty** in a random variable X distributed by $0 \leq \pi(x) \leq 1$ as

$$H(X) = - \int \pi(x) \log \pi(x) dx \geq 0$$

Entropy



Entropy



Wiener and Shannon



Kolmogorov

Copied from Sergio Verdu

Entropy



Wiener and Shannon



Kolmogorov

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- Wiener: "...for it belongs to the two of us equally"

Entropy



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- **Wiener:** "...for it belongs to the two of us equally"
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Entropy



Wiener and Shannon



Kolmogorov

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- **Wiener**: “...for it belongs to the two of us equally”
- **Shannon**: “...a mathematical pun”
- **Kolmogorov**: “...has no physical interpretation”

Entropy

Entropy of uniform distribution

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$$H(X) \leq H(U)$$

100 years of uniform distribution

source: Christoph Aistleitner



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Hermann Weyl

and Maximum entropy

Maximum entropy distribution

- X with known mean and variance

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$$\max_{\pi(x)} H(X) = - \int \pi(x) \log(\pi(x)) dx$$

subject to

$$\int x\pi(x) dx = \mu$$
$$\int (x - \mu)^2 \pi(x) dx = \sigma^2$$
$$\int \pi(x) dx = 1$$

Gaussian and Maximum entropy

Maximum entropy distribution

- X with known mean and variance
- $\pi(x)$? with maximum entropy
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- Gaussian distribution: $\pi(x) = \mathcal{N}(\mu, \sigma^2)$



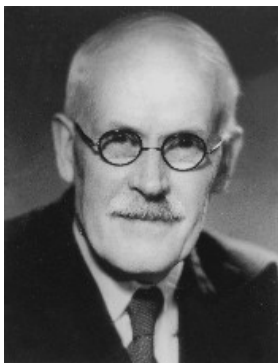
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Relative Entropy



Abraham Wald (1945)



Harold Jeffreys (1945)

$$D(\pi||q) := \int \pi(x) \log \left(\frac{\pi(x)}{q(x)} \right) dx$$

Kullback-Leibler divergence = Relative Entropy



Solomon Kullback
(1951)



Richard Leibler (1951)

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Information Inequality

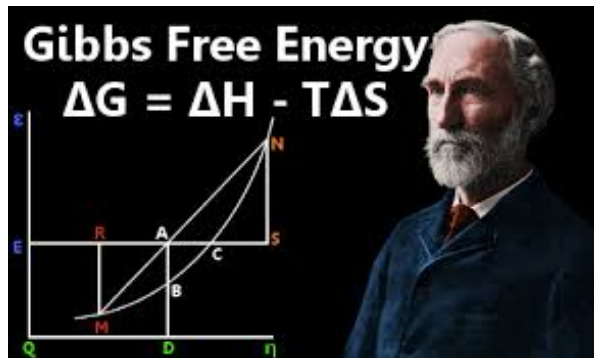
The most important inequality in information theory

$$D(\pi||q) \geq 0$$

Can we see it easily?

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From Relative Entropy to Bayes' Theorem

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each face $\{p_i\}_{i=1}^k$:
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- The likelihood of $\{n_i\}_{i=1}^k$ distributed by $\{q_i\}_{i=1}^k$

$$\prod_{i=1}^k q_i^{n_i}$$

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- The likelihood of $\{n_i\}_{i=1}^k$ distributed by $\{q_i\}_{i=1}^k$ (**Multinomial distribution**)

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Relative entropy = average likelihood \rightarrow Bayes

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- Bayes' theorem $q(x) = L(x)p(x)$

From Optimization to Bayes' Theorem

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$$d = \mathcal{G}(x) + \varepsilon$$

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- The likelihood:** assume $\varepsilon \sim \mathcal{N}(0, C)$

$$\pi_{\text{like}}(x) = \exp\left(-\frac{1}{2} \|d - \mathcal{G}(x)\|_C^2\right)$$

From Optimization to Bayes' Theorem

Prior Elicitation

- Try to get the best prior information = discrepancy relative to the posterior is minimized

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- Conversely, best prior \rightarrow the **information gained** in the posterior should not be large
- Equivalently,

$$\pi_{\text{post}} = \arg \min_{\pi(x)} D(\pi || \pi_{\text{prior}}) = \int \pi(x) \log \left(\frac{\pi(x)}{\pi_{\text{prior}}(x)} \right) dx$$

From Optimization to Bayes' Theorem

How about information from the data?

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- One approach: minimize the **mean squared error**

$$\pi_{\text{post}} = \arg \min_{\pi(x)} \int \pi(x) \|d - \mathcal{G}(x)\|_C^2 dx$$

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$$\pi_{\text{post}} = \arg \min_{\pi(x)} \int \pi(x) \|d - \mathcal{G}(x)\|_C^2 dx = - \int \pi(x) \log(\pi_{\text{like}}(x)) dx$$

From Optimization to Bayes' Theorem

Prior + data information

- From prior

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- A Compromise

$$\pi_{\text{post}} = \arg \min_{\pi(x)} - \int \pi(x) \log (\pi_{\text{like}}(x)) dx + \int \pi(x) \log \left(\frac{\pi(x)}{\pi_{\text{prior}}(x)} \right) dx$$

subject to

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Lagrangian + calculus of variation

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Lagrangian + calculus of variation

- Solution = Bayes' theorem

$$\pi_{\text{post}}(x|d) = \frac{\pi_{\text{like}}(d|x) \times \pi_{\text{prior}}(x)}{\int \pi_{\text{like}}(d|x) \times \pi_{\text{prior}}(x) dx}$$

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- 3 Optimization + information \rightarrow Bayes' theorem